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INSTRUCTION BOOK FOR 800 VOLT DC METAL ENCLOSED SWITCHGEAR

for

WASHINGTON METROPOLITAN AREA TRANSIT AUTHORITY

Lansdowne Way Substation
Windham Lane Substation
Mount Vernon Square Substation
U Street Substation

WMATA Contract No. 1Z1049 SSE-9

Instruction Manuals

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DC AMMETERS DC VOLTMETERS	CROMPTON	U/S700 PG. 19-22	4
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OVERCURRENT RELAY	GEC	R-5257A	9
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CATHODE CIRCUIT BREAKER CONTROL CIRCUIT Description of Operation

- I. Breaker in the Connected Position
 - A. General Breaker In The Connected Position. The cathode circuit breaker control can be set to either the remote or local operating mode by a control switch (43/R, 43/L). The protective trip and lockout functions are operable any time the breaker is in the connected position independent of the position of the remote 43R/local 43L control switch.
 - B. Remote Mode In the remote position the local close/open control switch is disabled and an automatic close circuit is enabled. The automatic close circuit will cause the cathode breaker to close when (1) the lockout relay (86D) is in the reset position; (2) the rectifier feeder breaker is in the connected position (52HR/a); (3) the rectifier feeder breaker is closed (52R/a); and (4) the rectifier enclosure doors are closed (33x).
 - C. Local Mode In the local position the automatic close circuit is blacked and the local close/open control switch is enabled. The breaker can be manually closed with the close control switch (72CS/L) only after the same four conditions for automatic close listed above are satisfied. The breaker can be opened by the open control switch (72CS/T).
- II. Breaker in the Test Position
 - A. Test Mode When the breaker is in the test position both the automatic close, the protective trip, and lockout functions are by-passed. The breaker can be closed or opened by placing the remote/local control switch in local and operating the local breaker close/open control switch. Note the breaker can be closed regardless of the status of rectifier feeder breaker or the rectifier enclosure doors.

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ATERIAL	211 WETMORE AVE., S.E. P. D. BOX 533 MASSILLON, OHIO 44646			REVISI	ONS

D.C. FEEDER BREAKER CONTROL SCHEME Description of Operation

When the D.C. Feeder Breakers are in the Test or connected (On-Line) position, the auto reclose circuit is engaged and closing will only occur after the load measuring equipment has determined that the system is free of shorts or overloads. Activation of the auto reclose circuit can be initiated by the manual control switch, Device 172CS, or by tripping of the circuit when in operation. Tripping will occur immediately upon receiving a trip signal from either a protective device or the manual control switch.

The load measuring scheme described here in detects system conditions for both stub connected and tie connected systems. The load measuring scheme employs two measuring relays referred to as the load measuring relay, Device 182, and the voltage compensating relay, Device 183.

The load measuring relay, Device 182, is an API Type 503X Meter Relay scaled 0-1 ohm, with a left-hand (A) contact.

The voltage compensating relay, Device 183, is an API Type 503X Meter Relay scaled 0-800V and having left-hand (A) and right-hand (B) contact. The left-hand contact (A), normally closed, will be set such that anything over 12 volts across the relay will open its contacts (A). The right-hand contact (B) will be set such that anything over 450 volts across the relay will close its contact. Both contacts are adjustable if different settings are required.

The load measuring resistor is set at 15 ohms to give 47A at 700V. The resistor is designed to carry 47A with one minute "ON" and 30 minutes "OFF". When the circuit breaker is open, this resistance is connected between the positive bus bar and the feeder cable end. The flow of current will be inversely proportional to the sum of the load measuring resistance, i.e. 15 ohms and resistance between the positive contact wire running and negative rails. The load measuring relay, Device 182, is connected such that it will measure the voltage produced by the current flowing between the resistance between the contact wire and running rails and indicates the current that would flow if the circuit breaker is closed.

The load measuring relay also measures any negative return volt rise which may be present in the system. This negative return volt rise appear due to the bonding of the two running rails, and of the "INBOUND" and "OUTBOUND" tracks together. Traffic on the system produces return current which flows back down the running rail of the feeder where the circuit breaker is open. The value of the negative volt rise depends on the nature of bonding, traffic on the system and the distance between substations. This voltage drop rise is compensated for by adjustment of the lower contact of the 183 which will not allow the feeder breaker to close under abnormal conditions.

			 	
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211 WETMORE AVE., S.E. • P.O. BOX 533 MASSILLON, OHIO 44646			RE	VISIONS
B.C. Feeder Breaker Control Scheme	DWG. NO		!-A52	Sheet 1 of 3
	CONTROLLED POWER CORP. 211 WETMORE AVE., S.E. • P.O. BOX 533 MASSILLON, OHIO 44646 D.C. Feeder Breaker Control Scheme	211 WETMORE AYE, S.E. P.O. BOX 533 MASSILLON, OHIO 44646 DWG. NO	211 WETMORE AVE., S.E. • P.O. BOX 533 MASSILLON, OHIO 44646 DWG. NO.	211 WETMORE AVE., S.E. • P.O. BOX 533 MASSILLON, OHIO 44646 DWG. NO.

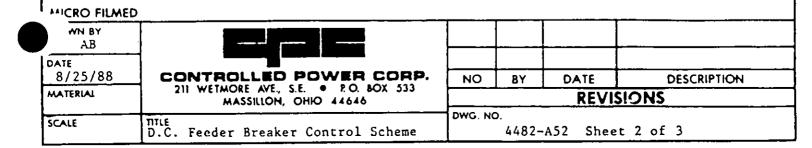
"This scheme is based on the fact that the voltage drop in the negative rails will normally be less than a certain value and anything higher than this will be of a transient nature. The value of this voltage will depend on track resistance, distance between substations and traffic conditions. It is expected to be about 12 volts."

When the feeder breaker is in the test or connected position, operation of the control switch, Device 172CS, will energize the latching relay, Device 201X (Operated). A contact on Device 201X will complete the circuit to the auto close relay timer, Device 186 and 102 will commence counting time.

The voltage compensating relay, Device 183, continuously measures the voltage between the feeder end and the negative rail.

"For the stub condition assume the voltage across the voltage compensating relay, 183 will be zero or below the 12 volt setting." The "A" contact on Device 183 will remain closed. When cam contact No. 2 on Device 102 closes after three seconds, contactor, Device 129 will be energized and sealed in by its contact No. 3 and the 15 ohms resistor will be connected between the positive bus bar and feeder cable. The flow of current is limited by this load resistor and the load or fault on the track. The load measuring relay, Device 182, will measure the voltage across the positive contact wire and the negative track. If this voltage exceeds the setting of the "B" contact on Device 182, it will close the "B" contact which will energize the auxiliary closing relay, Device 172/Z.

When the cam contact No. 3 on Device 102 operates, a contact on 172/Z will seal in the Device 172/Z. Another contact Device 172/Z will energize the closing coil which in turn will Device the circuit breaker. The anti-pumping relay device deenergizes once the circuit breaker is closed or operates If in the sub condition, the voltage across the voltage measuring relay is in excess of 12 volts, which may be due to excessive negative volt rise, then its "A" contact will be opened. Device 129, from becoming will prevent the contactor, energized when the can contact No. 2 on Device 102 closes. Closure of the circuit breaker will not take place. A further load measurement will continue after an interval of 14 seconds because Device 186 will remain energized, and the Device 102 will continue rotate. It is expected that the negative voltage rise will be 12 volt during one of the load measurements, in which case the circuit breaker will close. The time-delay contacts on Device set at three times the cycle time of Device 102. If the circuit breaker does not close during the checking period, Device 186 will close its time-delay contacts which will reset the Device 201 and the load measuring circuit.



Page 3

If a successful closing of the circuit breaker take place in the first closing attempt, the supply to Device 186 is maintained by the cam contact No. 1 on Device 102, and this in turn keeps the Device 102 running. As Device 102 runs it opens first cam contact No. 2 then No. 3 and No. 1 thereby resetting Device 129. About eight seconds after cam contact No. 2 on Device 102 opens, cam contact No. 1 opens which deenergizes Device 186 and 102.

the tie condition, if the voltage across the In compensating relay, Device 183, is above the setting 450 volts, this "B" contact will be closed which will energize the auxiliary closing relay, Device 172/Z, when the cam contacts No. 2 and No.1 2 on Device 102 are closed. This will close the circuit breaker as described before.

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SCALE	TITLE	DWG. H	D .		
	D.C. Feeder Breaker Control Scheme	448	2-A52	Sheet 3	of 3

HIGH SPEED D.C. SWITCHGEAR TYPE HSN(P)



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FOREWARD

The type HSN (P) high speed circuit-breakers are designed to perform satisfactorily under the arducus conditions imposed by a modern D.C. Rapid Transit System. The large capacity silicon rectifiers used in these systems demand a highly rated circuit-breaker capable of high speed operation to limit the rapidly rising fault currents without producing dangerous overvoltages.

When given the maintenace stated in this instruction book, the type HSN (P) circuit-breaker will continue operating satisfactorily for many years. It should be appreciated that a high speed circuit-breaker is a machine doing extremely heavy work. The moving contact is given a rapid acceleration and is brought to rest even more rapidly, therefore the breaker is very strongly built. Its function is so extremely important that it requires periodic examinations, cleaning and lubrication like any other piece of machinery.

1.1 STANDARD SPECIFICATIONS

The type HSN (P) high speed circuit-breaker is constructed in accordance with the following standards:

B.S. 4752

Specification for switchgear and controlgear for voltages up to and including 1,000 volts A.C. and 1,200 volts D.C.

I.E.C. 157

Low voltage switchgear and controlgear.

A.N.S.I. C37.14

Low voltage D.C. power circuit-breakers.

2. HANDLING

2.1 SHIPMENT

Breakers are usually shipped in their housings with the breakers racked home into the service position. They may be in individual units, or several units together, depending upon site handling facilities and suitable natural separating points in the busbars. They are shipped on wooden pallets with the units firmly banded to prevent movement.

2.2 CHECKING THE EQUIPMENT ON ARRIVAL

Check the equipment against the dispatch notes and the check list as soon as the equipment arrives. If damage is evident, determine the extent and cause of the damage immediately. Should the damage have occurred during transit, inform the carrier and together with him, make out a report. This is essential, where a claim for damage is to be made.

2.3 UNPACKING

Dismantle the crate from the top, leaving the units standing on the base. Lift the units from there, with breakers in the housings, using the lifting beams provided.

Note:

Single units have four lifting eyes screwed into angle brackets in the center section of the cubicle. Multiple units have a lifting beam, with lifting eyes bolted onto the same angles. After lifting, the eyes on single units or the beams on the multiple units must be removed.

When the breakers have been removed from the crate, the breakers can be withdrawn from the housings if required. See later instructions under OPERATION - Section 8.

3. STORAGE

If the breakers cannot be installed immediately following delivery, store them in a clean dry area. Should the switchgear accidentally become damp, dry it as soon as possible using forced warm air.

4. DESCRIPTION

Each type HSN (P) breaker unit consists of a wheeled truck and housing. The circuit breaker is mounted on the truck together with its mechanism, controls and closing and tripping devices. The housing contains busbars, cable connections, isolating contacts together with control relays and metering equipment.

It is normal for a number of units to be installed side by side to form a switchboard. Housings which make up a switchboard are bolted together, while trucks remain independent, and be readily inserted or withdrawn without disturbing the others. All trucks of a similar current rating are fully interchangeable.

There are three positions for the trucks, SERVICE, TEST and WITHDRAWN. In the "service" position, the truck is fully inserted into the housing and all the circuits are completed. In the "test" position, the truck is withdrawn to the full extent of the rack, but not pulled further. In this position, the main contacts are disconnected, but the control circuits remain intact so that test operations are possible. In the ""withdrawn" position, the truck has been pulled clear of the housing and the circuit breaker is completely disconnected.

Interlocks prevent the trucks being withdrawn from or inserted into the "service" position with the circuit breakers closed. Safety shutters automatically shield the main contacts when the circuit-breaker is removed.

Control switches and indicator lamps for the circuit-breaker are mounted on the front panel. The control selector switch selects either local or remote control. The trip and close switch trips the breaker direct and either closes the breaker direct or initiates the load measuring auto-reclose sequence coil. The closing operation is powered by the closing solenoid 18 which also charges the opening springs 6 (\$778A). The breaker can be closed by hand using the manual closing handle provided, but this is intended for emergency and maintenance operations only.

When the breaker is tripped, it opens extremely rapidly under the action of the opening springs 6 (\$778A). To ensure high speed operation the main moving contacts are designed to have a low mass. They are constructed of lightweight alloy with silver contact tips.

The silver cadmium oxide tip 56 (\$778B) fitted to the moving arcing contact 57 is given a lead over all the silver tips 55 fitted to the main moving contacts 35, so that it makes before and breaks after them, thus acting as an auxiliary arcing contact.

A fixed arcing contact assembly (S778E) is fitted above the top fixed contacts (See Illustration S778A). The two spring-loaded arcing contacts 78 (S778E), make contact with the moving arcing contact 57 when the breaker is closed. The arcing contacts 78 are adjusted so that they make first on breaker closing and open last on breaker opening.

The arc is, therefore, transferred to the arcing contacts 57, and on to the arc runners 1 and 2 (\$778A).

The arc chute 166 (S778N) is comprised of a number of verticle steel plates arranged around and over the arc runners in such a way that the arc is drawn into the stack of steel plates, and is broken into a number of small arcs which are cooled and extinguished as they move rapidly towards the top of the plates.

The breaker is equipped with an air puffer, mounted between the top and bottom main contacts and operated by the breaker mechanism. This is completely automatic and assists with the control of small arcs, produced by the interruption of low value currents, in either direction, which may otherwise tend to linger on the main arcing contacts.

Operator tripping is performed electrically by the shunt trip coil 138 or manually by pressing the hand trip knob 131 on the front panels (S778L).

Automatic tripping is initiated by one of the several possible protection devices e.g. the instantaneous bi-directional overload device, the low set uni-directional reverse current device, the shunt trip or undervoltage release.

Protection relays and instruments are mounted on the hinged door fitted to the housing immediately above the front panel of the truck. Behind this hinged door are accommodated the terminals and buswires.

Further relays are accommodated at the rear of the housing. Shunts, transducers or current transformers are mounted on the connections at the cable side of the circuit.

Load measuring resistors are mounted on the top of the housings.

5. INSTALLATION

Switchboards are often too long to be shipped in one piece and they are therefore split into portions of up to four units, which are of a suitable size and weight to permit them to be readily handled without damage.

Before commencing installation, ensure that the substation layout and foundation plan are available.

According to the customer's requirements the switchboards are supplied for solid grounding or to be grounded through a resistance and monitoring device. In the latter case, the switchboard stands on an insulated foundation and the units may be insulated from each other. The installation procedure will vary according to these circumstances.

5.1 DIRECTLY GROUNDED SWITCHBOARD

- 5.1.1 Lay a suitable concrete foundation, that is, one that is flat and level. It must also contain cable holes and fixing pockets in the correct positions as shown on the foundation plan.
- 5.1.2 Mark out the front line of the switchboard on the floor. The position of this will be determined by the positions of the fixing pockets.
- 5.1.3 Having removed the trucks from the housings, position the switchboard with its front edge on the line marked out.
- 5.1.4 Where necessary use shims under the base to make the switchboard plumb and level.
- 5.1.5 Link the portions of the switchboard together using the nut, bolts and washers supplied.
- 5.1.6 Secure the switchboard to the floor using the fixing details supplied in accordance with the foundation and switchgear assembly drawings.
- 5.1.7 Fit the trucks into the panels and check that they line up correctly with the contacts locating properly.
- 5.1.8 Couple the busbars together, where they have been split, using fishplates, nuts, bolts and washers supplied.
- 5.1.9 Couple the buswire sections together.
- 5.1.10 Remove the lifting beams.

- 5.1.11 If load measuring resistors are supplied, fit these on top of each feeder unit. Each panel will then require two electrical connections to be made in addition to the mechanical fixing.
- 5.1.12 Connect the cables to each unit in accordance with the appropriate diagram.
- 5.2 SWITCHEOARD GROUNDED THROUGH RESISTANCE
- 5.2.1 Lay a suitable concrete foundation, that is, one that is flat and level. It must also contain cable holes and fixing pockets in the correct positions as shown on the foundation plan.
- 5.2.2 Cover the concrete with a layer of plastic resin cement, Amazite or equal to a thickness of 3/8". This should be continuous and over all surfaces of the fixing pockets. The method of securing the switchboard may require epoxy blocks and rawlplugs with greased bolts to be positioned in the fixing pockets before applying the plastic resin cement. If another method of securing has been selected by customer, this will not apply.
- 5.2.3 Mark out the front line of the switchboard in the floor. The position of this will be determined by the positions of the fixing pockets.
- 5.2.4 Remove the trucks from the switchboard and the greased bolts from the floor fixing pockets (if fitted). Position the switchboard with its front edge on the line marked out.
- 5.2.5 Where necessary use shims under the base to make the switchboard plumb and level. If the units are insulated from each other ensure that the shims do not bridge this insulation.
- 5.2.6 Link the portions of the switchboard together using the components supplied. For units insulated from each other these include insulating study, bushes and washers.
- 5.2.7 Secure the switchboard to the floor using the greased bolts removed in Paragraph 5.2.4 or using any other agreed fixing procedure.
- 5.2.8 If the switchboards are insulated from each other, special steel bolts are used to link the units during shipment and these must be changed for the insulated links provided when the switchboard is in its final position.
- 5.2.9 Fit the trucks into the panels and check that they line up correctly with the contacts locating properly.

- 5.2.10 example the lifting beams.
- 5.2.11 Use exegger to check that the level of insulation between each united ground is satisfactory.
- 5.2.12 Couple the busbars together, where they have been split using the fishlates, nuts, bolts and washers provided.
- 5.2.13 Coups the buswire sections togetheer.
- 5.2.14 Ifided measuring resistors are suppplied fit these on top of each feet unit. Each panel will then require two electrical consections to be made in addition to the mechanical fixing.
- 5.2.15 Conner the cables to each unit in accordance with the appropriate digram.

SETTINGS AND ADJUSTMENTS

6.1 CLOSING SOLENOID

(See Illustration \$778A)

- 6.1.1 To check that the closing solenoid is correctly set, measure the gap V between the end of the prop arm 14 and the notch in the prop link 10 (See Illustration S778F). With the solenoid energized, this gap should be 1/32" to 1/16" (1.0mm to 1.5mm).
- 6.1.2 To reduce the gap, release nuts 25 and transfer shims 24 from their storage position immediately below nuts 25 to a position between the solenoid top plate and the underside of the truck top plate. For each nut 25 transfer an equal number of shims. These shims are slotted to facilitate transfer. To increase the gap, reverse the above procedure so that more of the shims are in the storage position. Ensure that nuts 25 are tight before re-checking the gap.

6.2 ARCING CONTACTS

(See Illustrations S778B, C, D and E)

- 6.2.1 To check that the arcing contacts are correctly set, measure the gap between the silver contact tip 56 on the moving arcing contact 57 and the auxiliary arcing contact fingers 64. With the moving arcing contact 57 just touching the fixed arcing contact 78, this gap should be 2.5mm.
- 6.2.2 To measure the gap between silver contact tip 56 and auxiliary arcing contact fingers 64, insert a 2.5mm rod tool No. 408267 between contact tip 56 and the face of contact fingers 64. When the arcing contacts touch, the rods should be just free to move.
- 6.2.3 To adjust the gap, raise the arc chute 166 and insert a 3/8" (10mm) thick x 3/4" (15mm) wide strip between the moving arcing contact 57 and ONE of the fixed arcing contacts 78.
- 6.2.4 Partially close the breaker until the interference between the square arcing contact nuts 69 is lost.
- 6.2.5 Adjust the contact nut 69 on the contact where the strip has been inserted and by trial and error arrive at the correct setting, inserting the strip each time for adjustment. When that one contact is correct, insert the strip in the other contact and similarly adjust until both contacts are exactly level.

- 6.2.6 There should be a gap of 2.0mm to 3.0mm between the top of both fixed and moving contacts and the associated arc runner.
- 6.2.7 When the moving arcing contact 57 is reduced by burning to half its original thickness at the point where it makes contact with the fixed arcing contact 78 (S773E) both fixed and moving arcing contacts should be changed and the auxiliary arcing contact fingers 64 should be examined to ascertain if these should be changed at the same time (See Para. 6.3.7).

6.3 MAIN CONTACTS

To obtain access for checking and setting proceed as follows:

- 6.3.1 Remove the arc chute 166 (\$778N).
- 6.3.2 Release the two insulated return connections 41 by removing bolts 40 and 49 (\$7783).

Note:

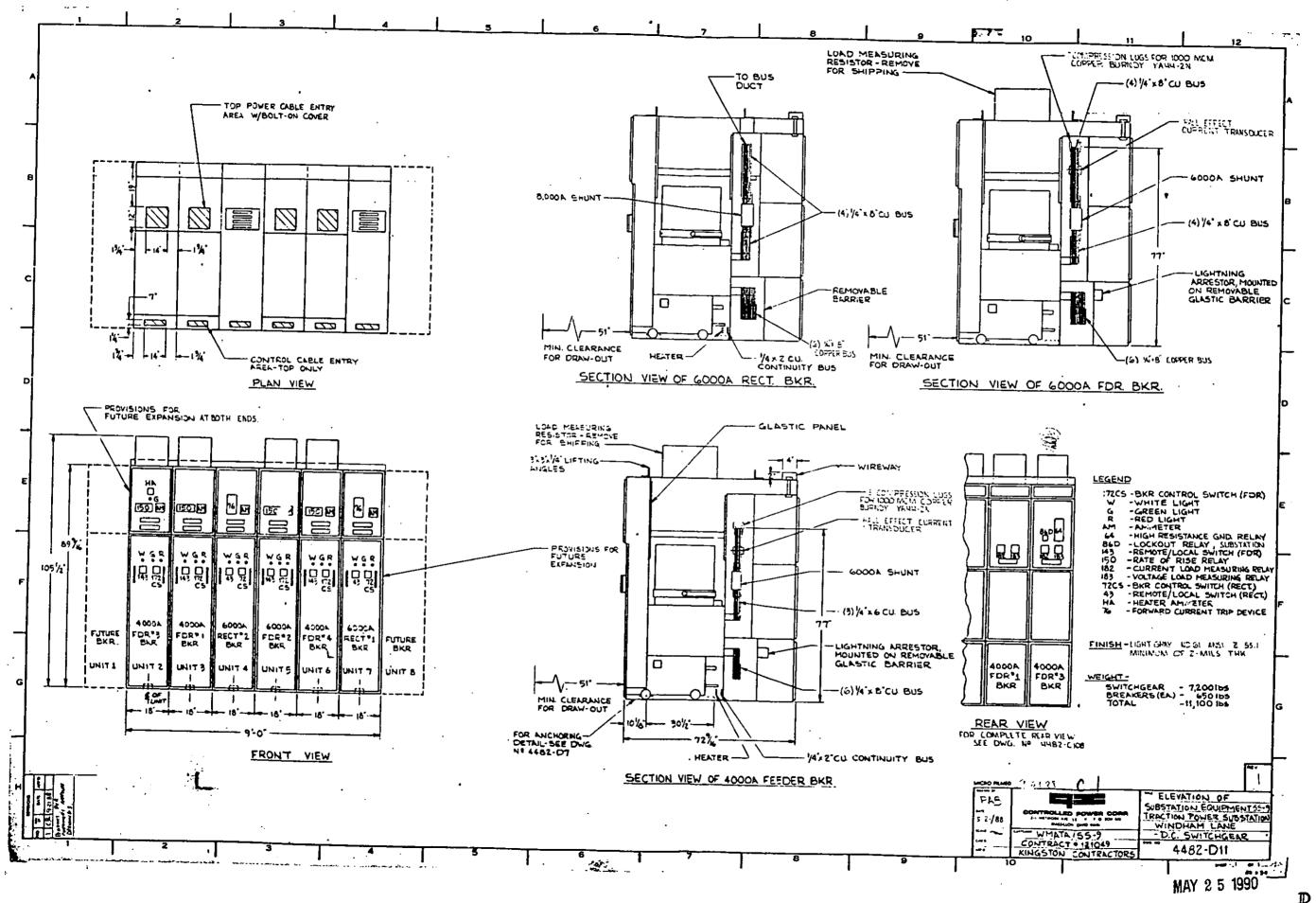
These connections perform the important duty of passing the fault current from the arc runner 2 to the bottom fixed contact 27 when the breaker opens on fault. It is most important that these connections should be replaced and properly tightened after adjustments are completed.

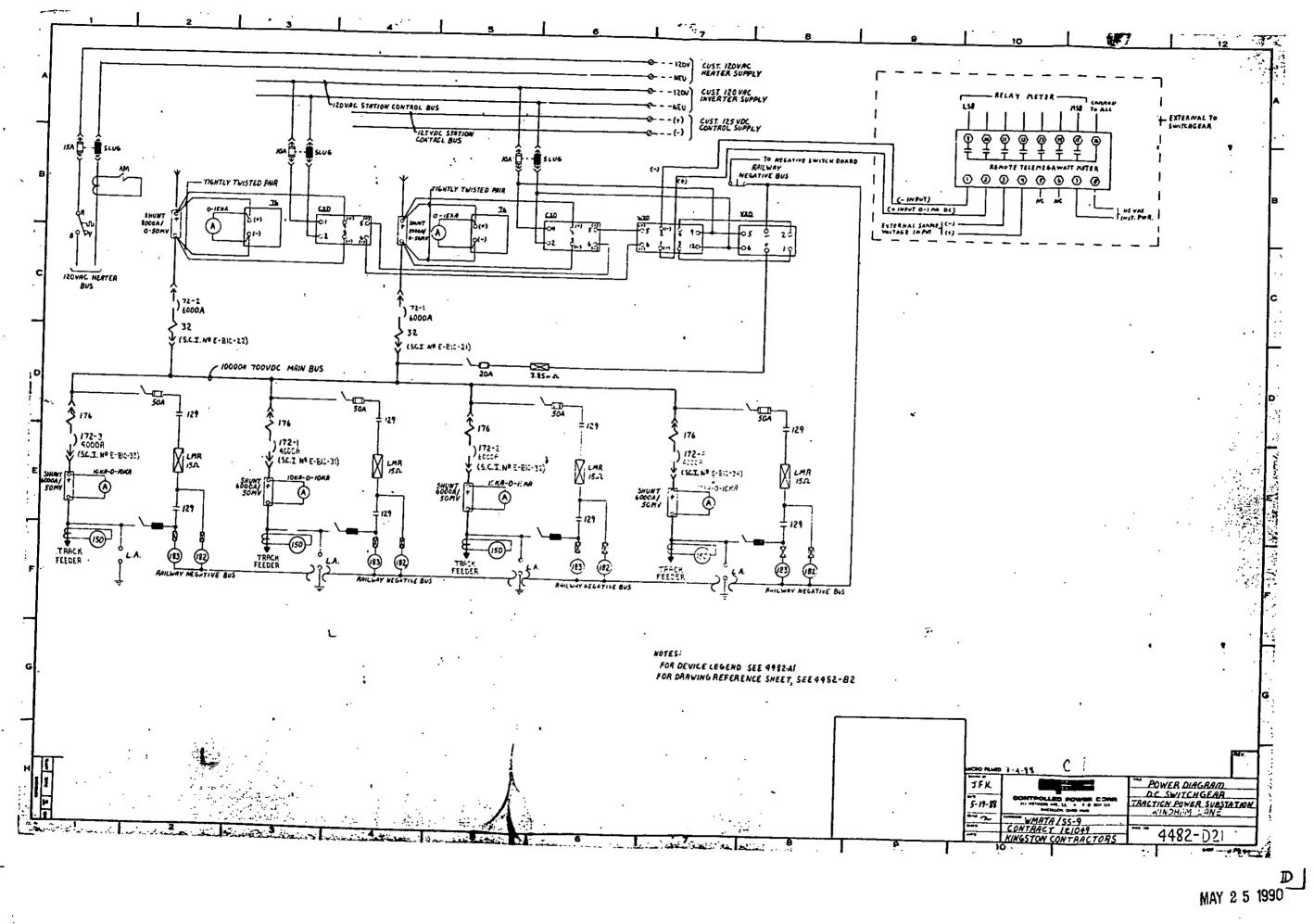
6.3.3 To check that the main contacts are correctly set measure the gap between the back edge of the brass contact guide 53 and the groove in the fixed contact finger 63. With the breaker closed this gap should be between 1.0mm and 1.5mm. This is shown as gap W on Illustration S778C, Figure 2.

Adjustment of the gap is made by adding or removing shims 8 (See Illustration S778P, Figure 2) to or from the space between block 7 and the vertical member of the mechanism. Adding shims will increase the contact pressure.

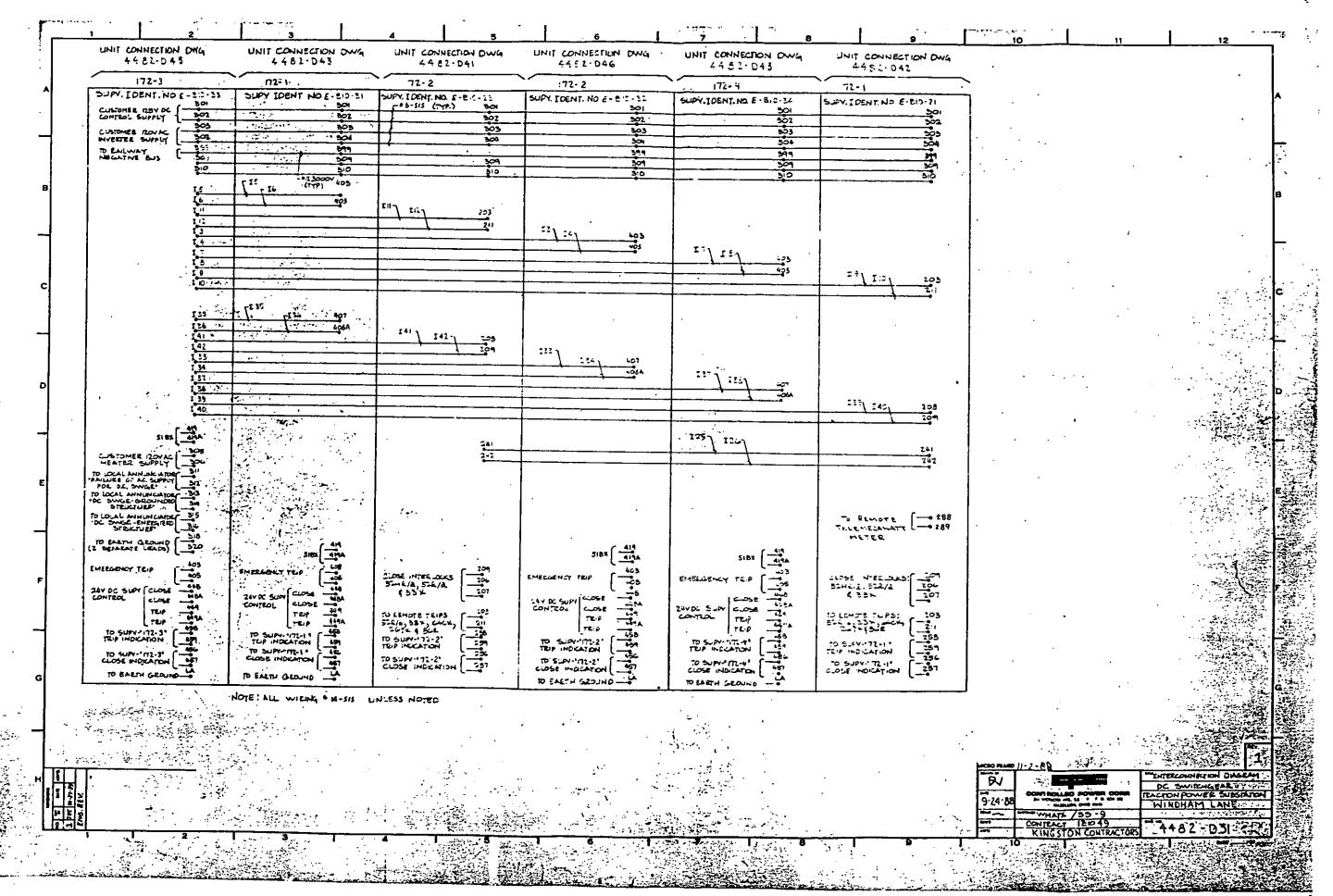
To adjust proceed as follows:

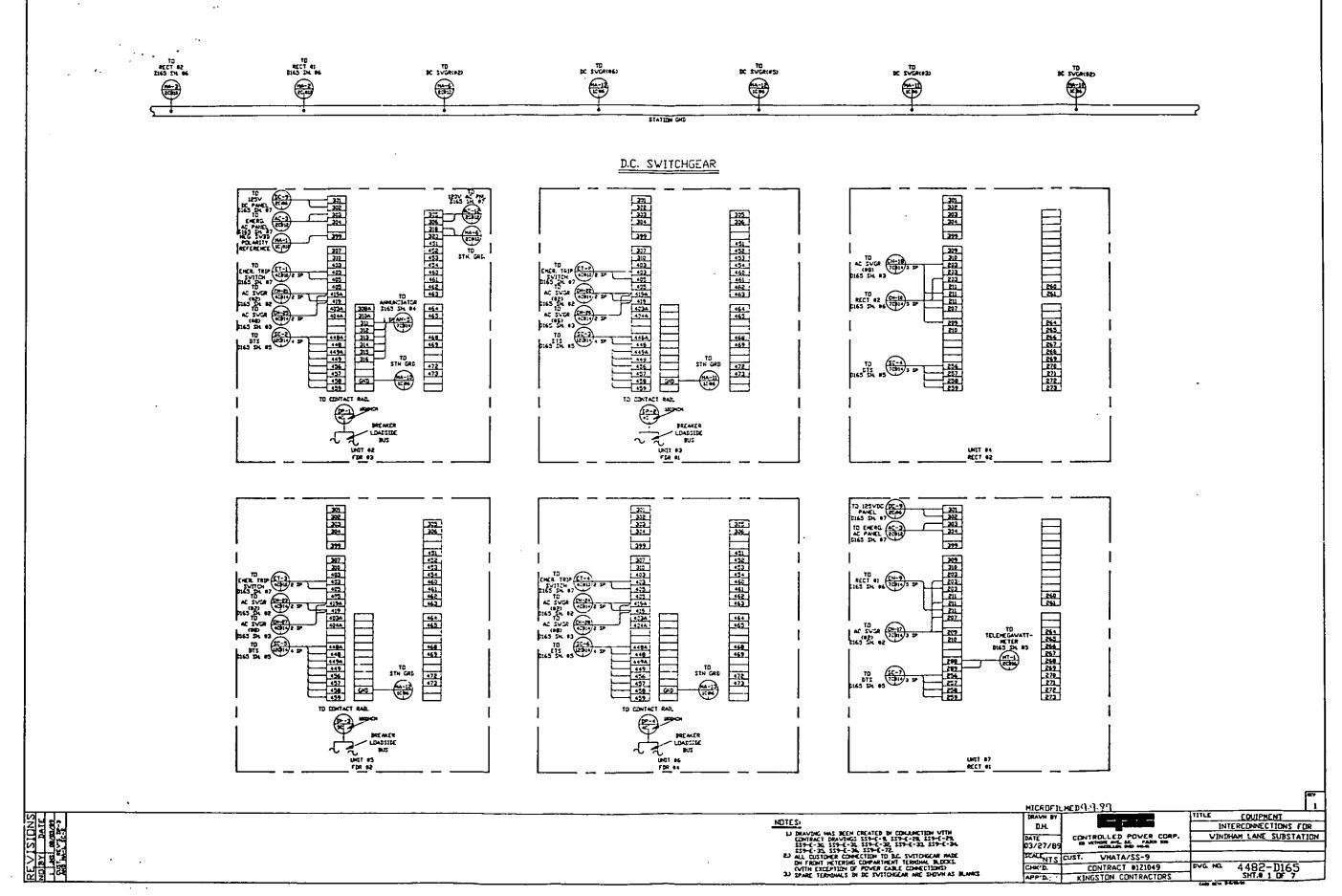
- 6.3.4 Ensure that the breaker is tripped. Release the two bolts 179.
- 6.3.5 To increase the contact pressure take spare shims 8 from under the heads of bolts 179 and insert beneath the mechanism adjustment bracket 7 as shown in Illustration S778P.

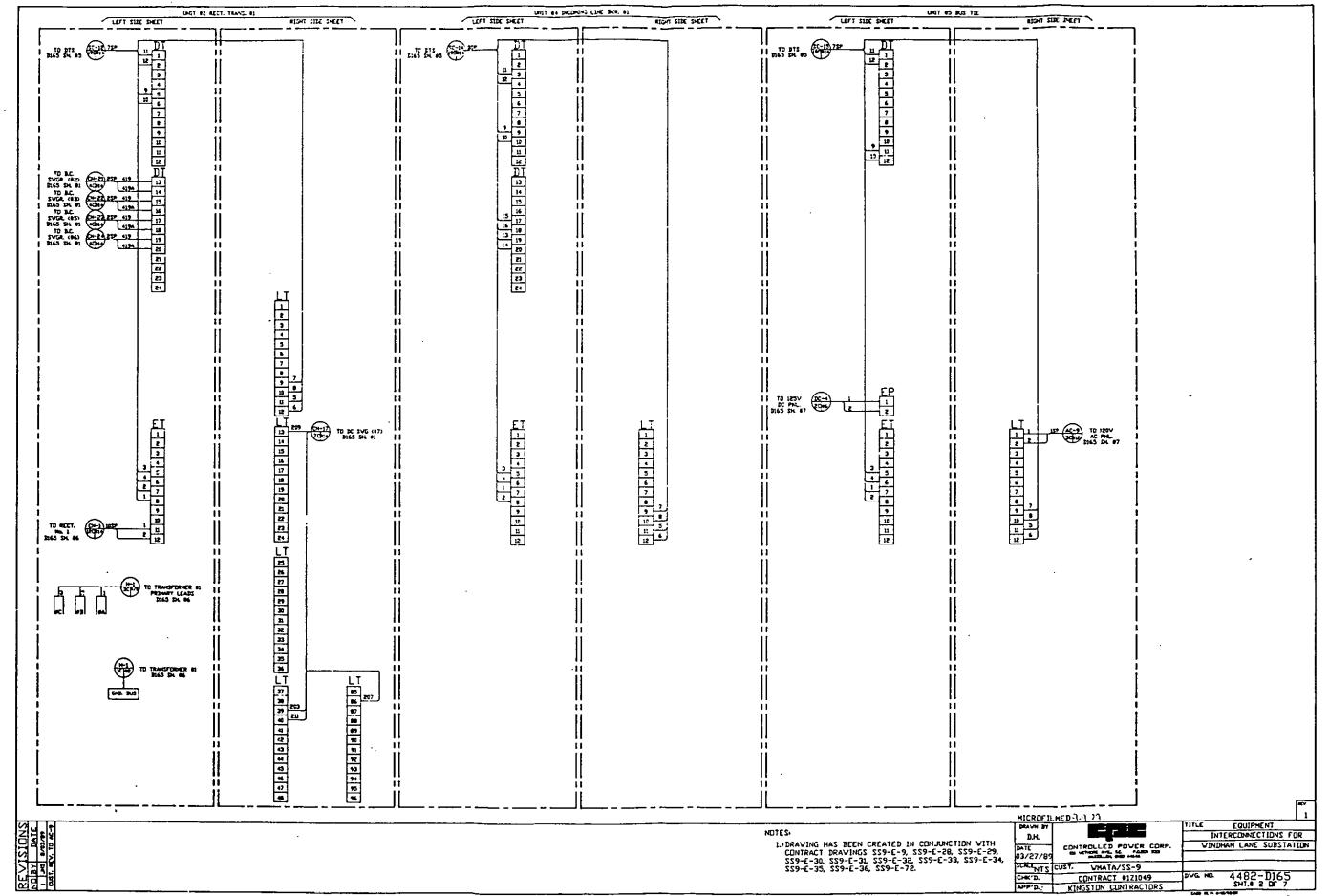


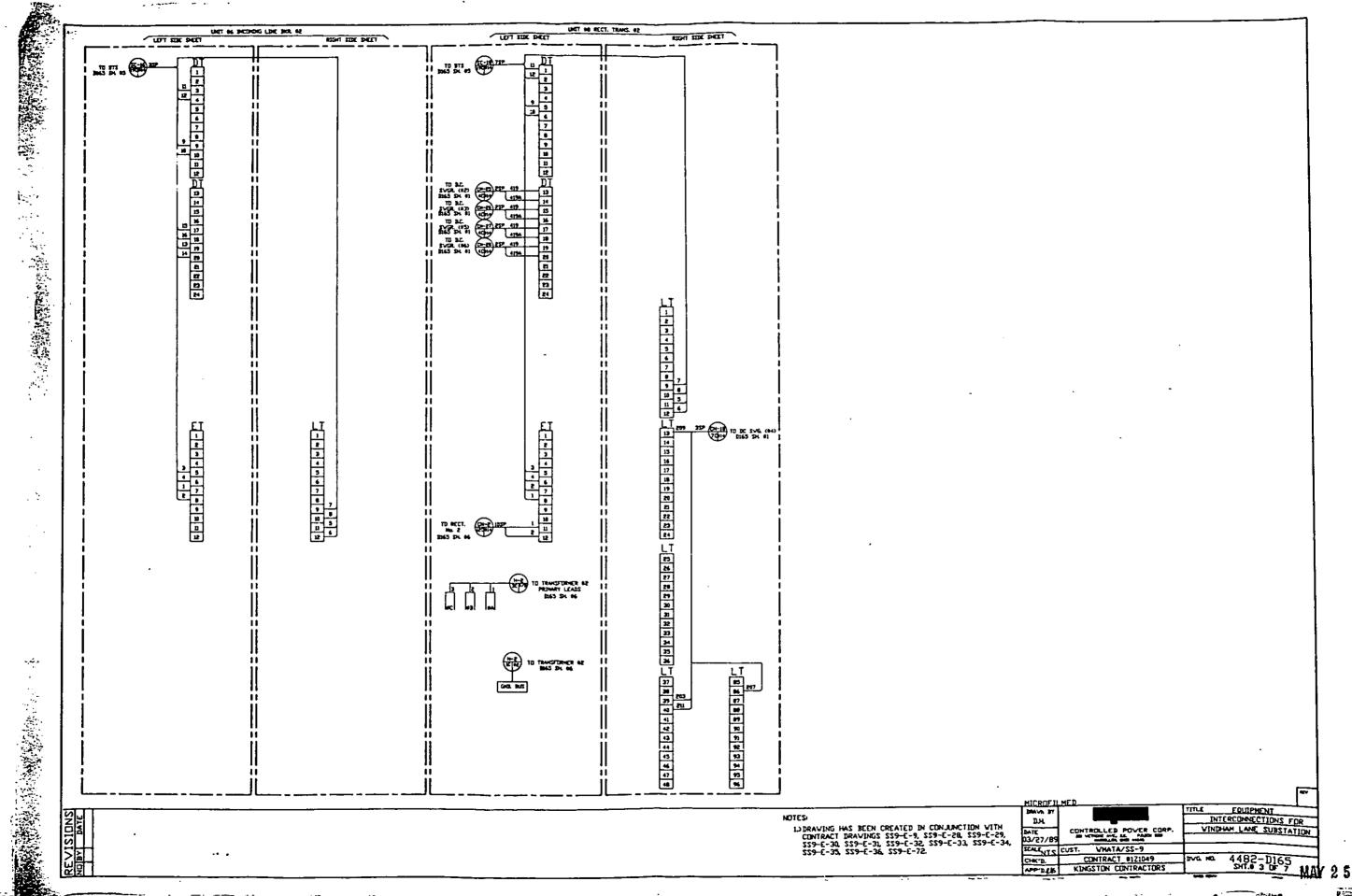


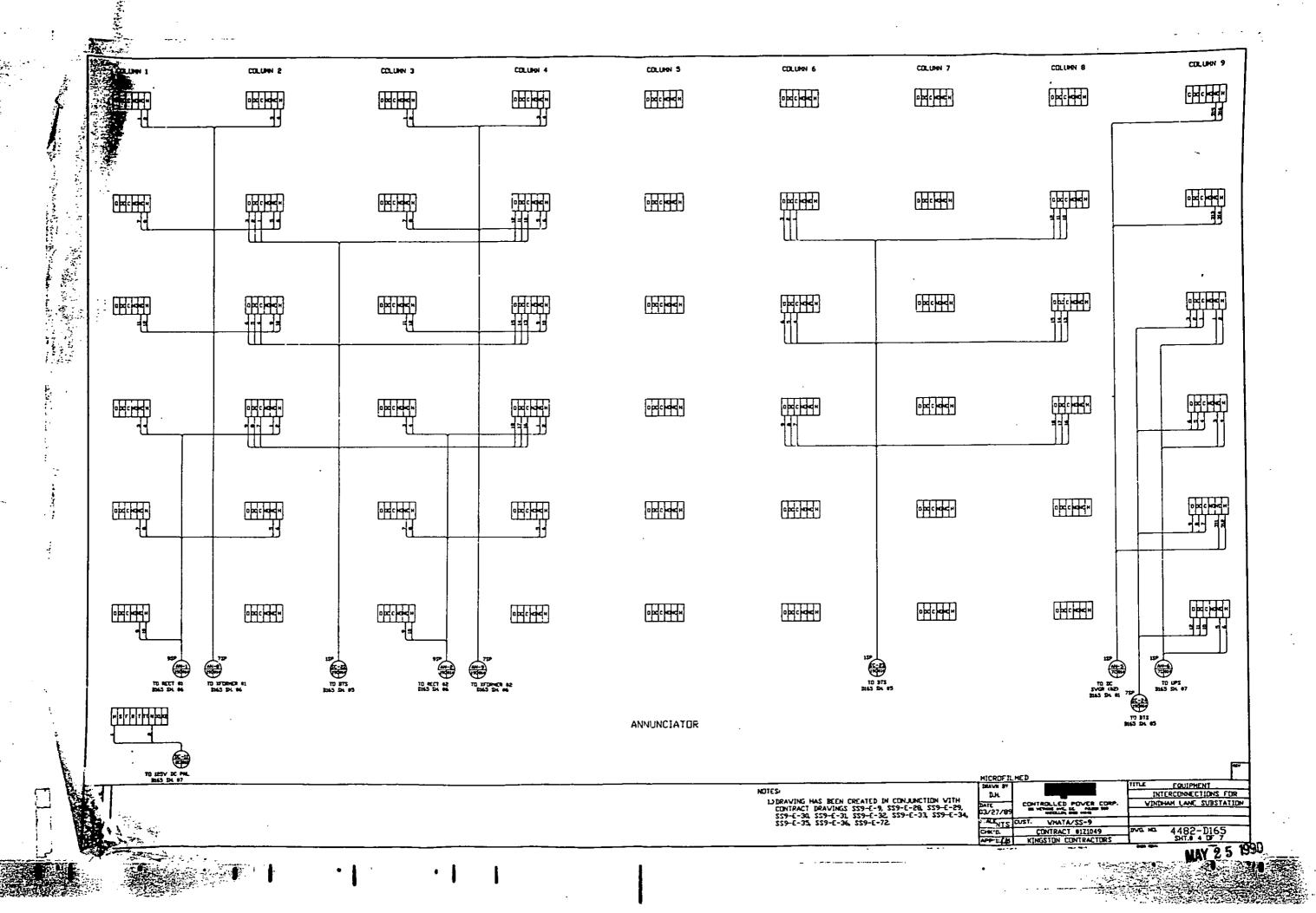
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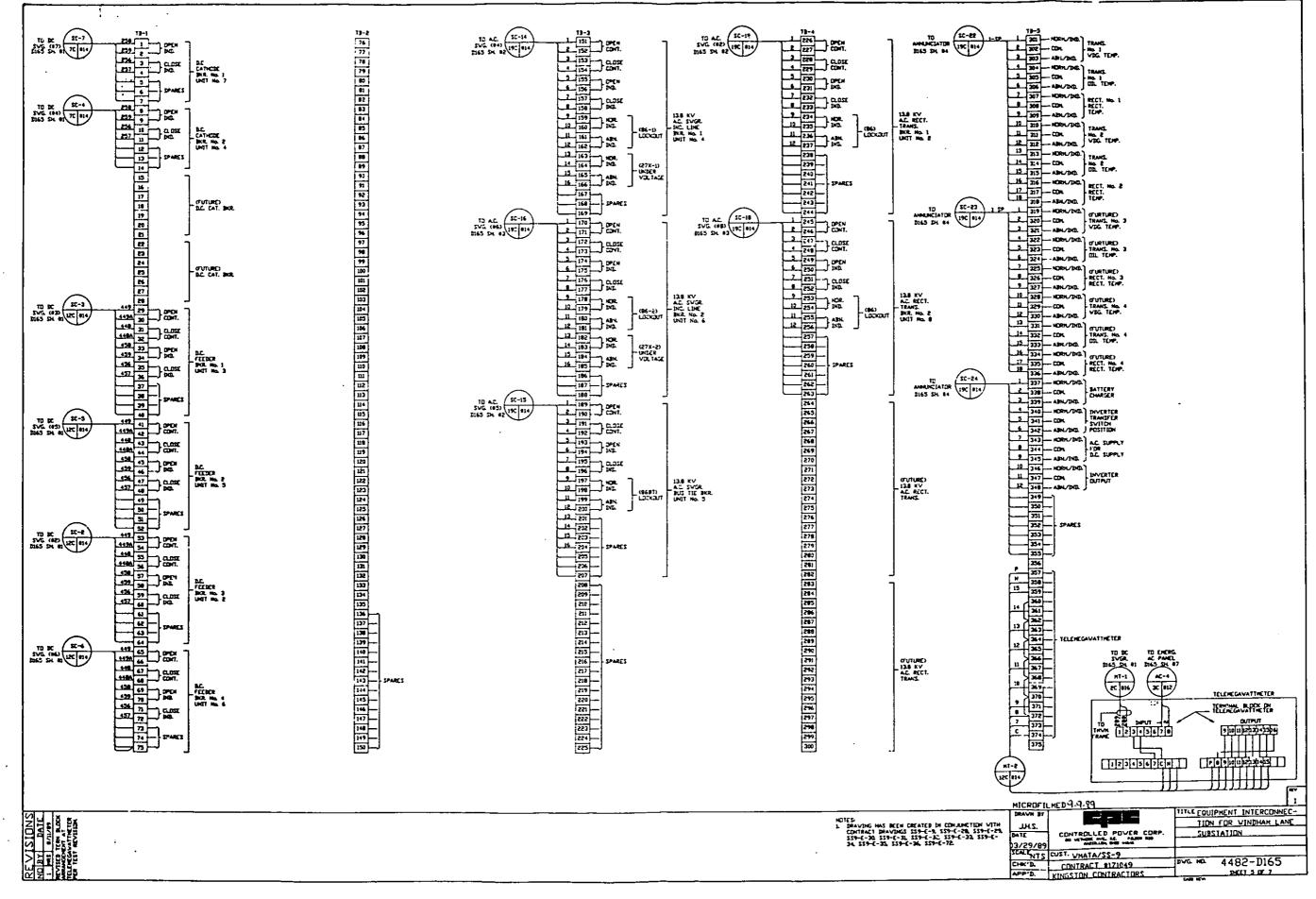


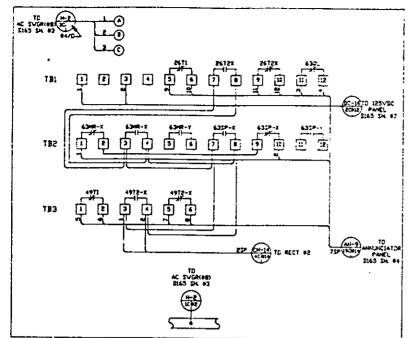




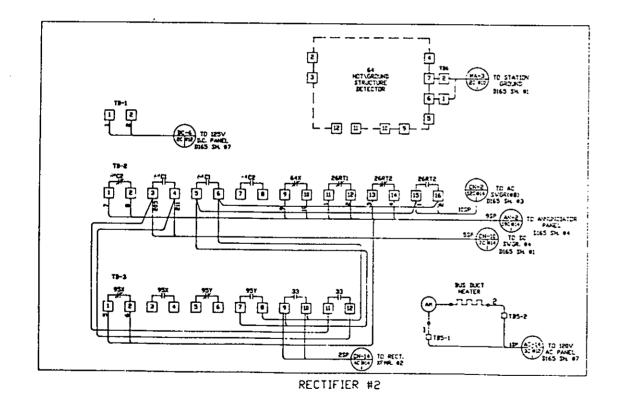
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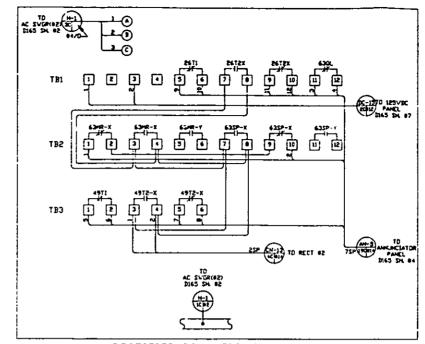
Service Control



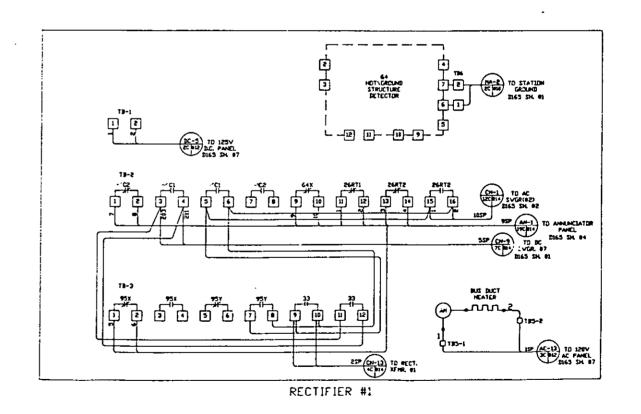


RECTIFIER TRANSFORMER #2





RECTIFIER TRANSFORMER #1

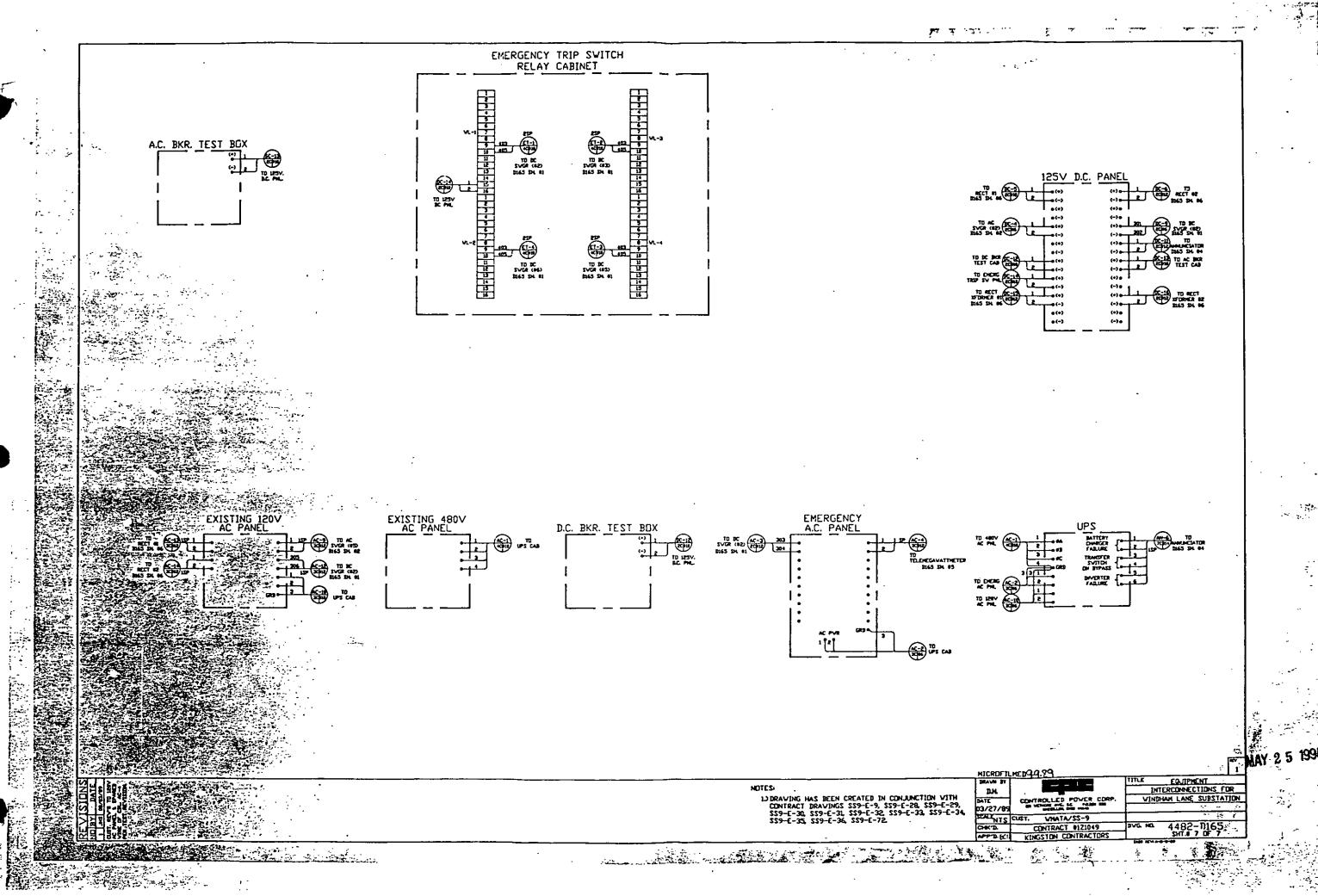


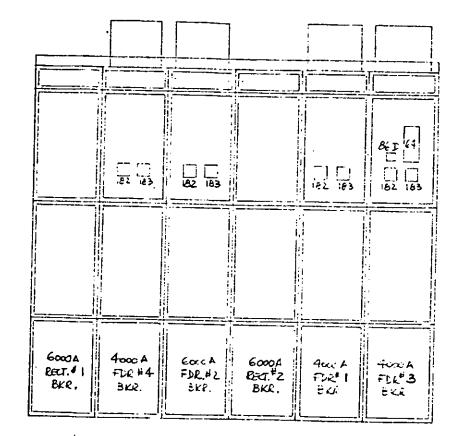
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NOTES

1) DRAVING HAS BEEN CREATED IN CONJUNCTION VITH CONTRACT DRAVINGS 559-E-9, 559-E-28, 559-E-29, 559-E-30, 559-E-31, 559-E-32, 559-E-33, 559-E-34, 559-E-35, 559-E-36, 559-E-72.

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SEE DWG Nº 4482-D11

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CONTROLLED POWER CORR TRACTION POWER SUBSTATION WINDHAM LAND

Note:

The shims 8 are slotted for ease of insertion, but there is a locking plate with two holes which must always be placed immediately under the heads of the bolts 179.

Two sizes of shims are provided, the thinner shim being 0.7mm and this will be the shim normally used for adjustments.

- 6.3.6 Re-tighten the bolts 179 and close the breaker to check the effect of the adjustment.
- 6.3.7 Repeat the previous steps if necessary.

The two extended moving contacts 33 (S778B) at the center of the moving contact assembly carry a moving arcing contact 57, which is fitted with a silver cadmium oxide contact tip 56 (S778B). This is advanced so that it will contact the auxiliary arcing contact fingers 64 before the silver contact tips 55 on the moving contacts 35 touch either the advanced contact fingers 61 or the main contact—fingers 63 (S778B and D).

The advance is such that when the moving arcing contact tip 56 makes contact with the longer auxiliary arcing contact fingers 64, there is a gap of between 6.0mm and 8.0mm between the silver tips 55 of the moving contact fingers 35 and the main contact 63. This is not adjustable and the auxiliary arcing contact fingers 64 should be changed when this gap is reduced to 4.0mm.

Extra spring pressure is required on the two extended moving contacts 64 because of their increased length and leverage. This is achieved by additional springs 183 (S778C) at the rear of the contacts located in a separate housing.

After all checks on the main contacts are complete, ensure that all the parts, which were removed to permit access, are replaced, and all screws tightened.

6.4 OPENING SPRINGS

(See Illustration S778P)

There is no adjustment for the opening springs 6. They are correctly tensioned when the nuts 178 with their springwashers have been screwed onto the spring retainer 180 far enough to cause the face of the spring retainer 180 to press firmly against the spring block 177.

Access to the nuts 178 is obtained by opening the front of the truck. The panel is secured by three screws at the right hand side of the panel.

Note:

The spring retainer 180 must always be assembled so that it is above the spindle upon which block 177 is mounted.

6.5 HALF SHAFT

(See Illustration S778F)

To adjust the half shaft proceed as follows:

- 6.5.1 Screw in the knife safety screw 85 until the circuit breaker will not close.
- 6.5.2 Screw out the knife safety screw 85 slowly until the breaker will just close when operated gently by hand.
- 6.5.3 Screw out the knife safety screw 85 a further 3 flats (half turn) and lock up.

Note:

Both locknuts on screw 85 must be tightened for each trial should not be unduly locse for adjustment to minimize free movement of the screw.

- 6.5.4 Adjust the half shaft limit screw 86 so that there is a 6.0mm gap between the end of the screw 86 and the bottom of the trip lever 87. This is shown as gap & on Illustration S778F, Figure 2.
- 6.5.5 Tighten both locknuts on limit screws 86.

6.6 TRIP KNIFE

(See Illustration S778F)

To adjust the trip knife proceed as follows:

- 6.6.1 Trip the circuit-breaker and allow to re-set.
- 6.6.2 Set the gap between the trip knife 81 and half shaft 82 to 1.0mm approximately. This is shown as gap X on Illustration S778F, Figure 1. This is achieved by adding or removing plain washers 80 from under the head of bolt 79. The two neoprene and two plain washers which are also in this position must not be removed.
- 6.6.3 Tighten the castle nut by hand onto the bolt 79 until finger tight i.e. just able to turn the assembly.

Then tighten a further half turn and lock up with a split pin.

6.7 HAND TRIP

(See Illustration S778F)

Check the gap between the striker nut 83 and the trip lever 87. This is shown as gap Z on Illustration S778F, Figure 2 and should be 3mm.

If necessary adjust by releasing locknut 84 and screwing striker nut 83 in the appropriate direction, afterwards secure with locknut 84.

6.8 OVERLOAD UNITS

(See Illustrations \$778G and H)

The unit has been carefully set and calibrated in manufacture and should not need adjustment except in the case of complete dismantling.

The screw 108 has been set to give the correct armature gap and should not be disturbed. If by accident this adjustment is altered, it can be recovered as follows:

- 6.8.1 Trip the circuit breaker.
- 6.8.2 Turn the calibration screw 103 to minimum trip setting and lock for a number generally between 5 and 7.5 stamped on top of the calibration screw bearing block.
- 6.8.3 Slacken the locknut on screw 108.
- 6.8.4 Close the armature 115 by inserting a screwdriver through the hole in the side plate of the breaker using the screwdriver as a lever.
- 6.8.5 While holding the armsture 115 closed, tighten screw 108 by hand until it is finger tight (5 lb. in. if this is possible) and then screw out by the number of turns observed on the calibration screw bearing.
- 6.8.6 Lock up screw 108 with its locknut.
- 6.8.7 Re-set calibration screw 103 to required setting.

6.9 OVERLOAD TRIP ROD CLEARANCE

(See Illustrations S778H and J)

To adjust the clearance between the trip lever 116 and the striker nut 188, proceed as follows:

- 6.9.1 Slacken locknut 117 and screw the striker nut 118 until it just touches the trip lever 116.
- 6.9.2 Screw striker nut 118 back 1-2/3 turns (10 flats) and secure with locknut 117. On 2,000 amp and other low calibration applications with values less than 4,000 amps set the striker nut 118 back 3-1/3 turns (20 flats) and secure with locknut 117.

6.10 UNDERVOLTAGE RELEASE

(See Illustration S778K)

This is located behind the front panel door of the circuitbreaker, which can be opened by removing the three screws at the right rear of the panels, giving easy access.

The unit has been carefully set in manufacture and should not need adjusting except in the case of complete dismantling.

A variable D.C. voltage is required for re-setting this unit.

The unit is set as follows:

- 6.10.1 Trip the circuit breaker.
- 6.10.2 Adjust nut 123 so that the armature 125 picks up from its stop and closes against the core 128 when the voltage applied across the coil is raised slowly to 85% full voltage. Switch off supply.

Note:

Most undervoltage releases have series resistors connected and this must be taken into account when deciding the correct voltage to apply (See Diagrams for particular contract).

- 6.10.3 Set the screw 126 back so that its bottom end is just below the surface of the armsture 125. Turn the screw 126 forward by very small amounts, applying full voltage to the coil for each trial and reducing the voltage, noting when the armsture 125 releases. Repeat until the armsture 125 is released at a value of approximately 20% of full voltage. Lock the screw 126 securely by its locknut 127.
- 6.10.4 (See Illustration S778J).

Set the striker nut 121 back so that the breaker can be closed without voltage on the undervoltage coil. Close the circuit breaker.

6.10.5 Operate the undervoltage armature by applying full volts and then switching off, each time advancing striker nut 121 until the breaker just trips when the voltage is switched off. Add 1/2 turn (3 flats) further for safety and lock up securely with locknut 122.

6.10.6 Check that the unit picks up at full voltage and that it is possible to close the circuit-breaker.

Check that with the breaker closed, the breaker trips when the voltage is switched off. Check too that the breaker cannot be closed without volts on the undervoltage coils.

Note:

This is an undervoltage release of the NO-VOLT type.

6.11 SHUNT TRIP

(See Illustration S778L)

To obtain access, open the front panel door of the circuitbreaker. Three screws at the back of the right hand side of the panel require to be removed to allow the door to open.

The shunt trip is set to allow the moving core 137 to rise and trip the breaker when 56% full volts is applied to the shunt trip coil 138.

Adjust the setting as follows:

- 6.11.1 Set the trip button 181 so that the trip poker 142 and moving core 137 have 1.5mm travel still available.
- 6.11.2 Remove nut 134 with its springwasher.
- 6.11.3 Add or remove plain washers under the head of screw 134 until the shunt trip will operate at 56% volts.
- 6.11.4 Secure with nut 134 and springwasher.

6.12 REVERSE CURRENT TRIP

(See Illustrations S778F and M)

The position of the trip armature 176 between the pole faces has been accurately set during manufacture and should not be disturbed. This position is decided by the stop screw 148 at the top of the unit. It is set so that the gap to the "trip" side is marginally greater than the gap to the "stop" side, thus ensuring stability.

The setting of stop screw 148 cannot be carried out easily with the unit in the breaker, but if the setting has been accidentally lost, it may be recovered as follows:

- 6.12.1 Trip the circuit-breaker.
- 6.12.2 Set the stop screw 148 well back and remove the spring 152.
- 6.12.3 Apply the full polarizing voltage to the coil.
- 6.12.4 Advance the stop screw 148 by small steps until the armature 176 "clicks" over center to the "trip" side.
- 6.12.5 Turn stop screw 148 back by 1/2 turn and lock up. Switch off the polarizing voltage, pull the armature 176 back against the stop screw 148 and switch the voltage on again. If the stop screw 148 has been correctly set, the armature 176 will stay agains stop screw 148, thus providing the requisite safety. If it "clicks" over, the stop screw 148 has been incorrectly set.
- 6.12.6 Calibration is achieved by adjustment of the return spring 152.

6.13 REVERSE TRIP ROD

(See Illustration S778F, Figure 2)

To adjust the clearance between the trip lever 87 and the striker nut 89 proceed as follows:

- 6.13.1 Slacken locknut 88 and screw the striker nut 89 until it just touches the trip lever 87.
- 6.13.2 Screw striker nut 89 back 1-1/3 turns (8 flats) and secure with locknut 88.

6.14 L.T. CONTACTS

(See Illustration S778P, Figure 1)

The L.T. Contacts must be even from end to end of the row, within the 1.0mm tolerance. The spring contact 171 must be firmly against the bottom of the slot in the insulated base 170.

The spring contacts 171 must be free from vertical displacement or distortion.

6.15 LOCKNUTS, SPLIT PINS AND CIRCLIPS

Before commissioning the breakers and after maintenance examine all locknuts to see that they are locked. Ensure that all split

pins are in place and are open. Ensure that all circlips are in place in their grooves.

COMMISSIONING

7.1 INSPECTION

After unpacking and installing, before a breaker is put into service, check that:

- 7.1.1 All packing has been removed.
- 7.1.2 No parts have been damaged in transit.
- 7.1.3 The main and auxiliary plug-in contacts are clean and in good order.
- 7.1.4 The racking gear, shutters and interlocks are fully operational.
- 7.1.5 The trucks are lined up correctly and are interchangeable, where applicable.
- 7.1.6 No wiring has been damaged and that all buswires have been properly connected.
- 7.1.7 The breaker can be closed and tripped manually.

7.2 ELECTRICAL TESTS

All switchgear is fully tested before it leaves the factory, but it is desirable to subject small wiring of newly erected switchgear to a further electrical pressure test if this is at all possible.

It suitable supplies and apparatus are available, the small wiring should be subjected to a test of 1,500 volts A.C., 50 or 60 Hz for one minute.

All ground leakage equipment should be disconnected and voltmeters shorted out for this test and the main busbars and connections grounded. The main busbars and main breaker connections should be checked with a "Megger", with all breakers closed and the small wiring grounded. The main circuit can be hi-pot tested according to the particular specification for the contract or as a rough guide 2 x the working voltage + 1,000 volts.

7.3 ROUTINE TESTS

All relays and circuit-breakers can now be checked for proper electrical operation in line with diagrams and instructions for the particular contract. Start with the breakers in the "TEST" position and finally in the "SERVICE" position, observing that all instruments and alarms function correctly.

7.4 TRIP SETTINGS

The overload unit is adjustable over a pre-determined range usually with a 2/l ratio. Adjustment is achieved by turning the calibration screw (Item 103 on Illustration S778G) at the rear of the breaker. The trip setting in kiloamps is shown on a graduated scale. The calibration is absolute and is independent of voltage variations and is bi-directional.

Before going into service, the overload unit should be set to the agreed trip setting for the particular application.

The reverse unit is directional and is not adjustable. This is pre-set usually at 10% of full load current and cannot be altered.

8. OPERATION

8.1 REMOVAL OF TRUCK AND BREAKER FROM HOUSING

- 8.1.1 Press the black trip knob 131 and turn clockwise until a "check" position is reached. This will trip the breaker, if it was closed and lockout the trip mechanisms.
- 8.1.2 Turn the knob 131 fully clockwise, against the resistance of a spring, which will open a shutter over the racking handle aperture at the bottom center of the front panel. While holding the knob against the spring pressure, insert the racking handle on to the racking shaft in the exposed aperture.
- 8.1.3 Turn the racking handle anticlockwise until the handle is free and the lead screw can be felt to be free from the nut.
- 8.1.4 Remove the racking handle, then the black knob will return to the "check" position. If turned fully anticlockwise the knob will move outwards and in this condition the breaker is in the "test" position and close and trip operations can be carried out.
- 8.1.5 Turn the knob 131 back to the "check" position and pull on the handles 197 to completely withdraw the truck and breaker from the housing.

8.2 REPLACEMENT OF TRUCK AND BREAKER IN HOUSING

- 8.2.1 Press the black trip knob 131 to trip the breaker if closed and then allow the knob to return to the out position.
- 8.2.2 Insert the circuit-breaker truck into the housing as far as it will go (a click will be heard as the bolt engages). This is the test position and in this position all operations can be checked.
- 8.2.3 Turn the knob 131 fully clockwise against the spring resistance and insert the racking handle as described in Paragraph 8.1.2.
- 8.2.4 Turn the racking handle clockwise until the breaker is racked fully home.

Note:

Do not insert the racking handle in the fully withdrawn position and ram the truck home, as this action will damage the lead screw and nut. The "test" position must be reached before inserting the racking handle.

8.3 CLOSING THE BREAKER MANUALLY

- 8.3.1 The breaker can be closed manually in either the "test" or the "service" position for maintenance or emergency operations. A safety shutter can be provided which prevents the breaker being closed in the ""service" position. To close manually, proceed as follows:
- 8.3.2 Turn the trip knob 131 anticlockwise and allow the knob to move out.
- 8.3.3 Insert the closing handle vertically in the closing handle aperture (on front panel midway between the trip knob and racking handle aperture). Rotate the closing handle clockwise until the breaker closes and latches.

8.4 TRIPPING THE BREAKER MANUALLY

8.4.1 Depress the trip knob 131.

8.5 LOCKING OUT THE BREAKER

8.5.1 Depress the-trip knob 131 and turn clockwise.

8.6 CLOSING THE BREAKER ELECTRICALLY

- 8.6.1 Turn the control selector switch, if fitted, to either the "local" or "remote" position.
- 8.6.2 Turn the control switch, if fitted, at the appropriate station (the breaker front panel for "local" or the supervisory control for "remote") the the "CLOSE" position. This will either close the breaker direct or start up the load measuring auto-reclose sequence, which will then close the breaker if the circuit is acceptable to the load measuring relays.

8.7 TRIPPING THE BREAKER ELECTRICALLY

- 8.7.1 Turn the control selector switch, it fitted, to either the "local" or "remote" position.
- 8.7.2 Turn the control switch at the appropriate station (the breaker front panel for "local" or the supervisory control for "remote" to "TRIP" position).

9. SAFETY PRECAUTIONS

In the United Kingdom, the Health and Safety at Work Act 1974 imposes a general duty on the employer to do what is reasonably practical to safeguard employees and the public in general from the risks arising from his business.

Inspection and maintenance the equipment must therefore be carried out in accordance with the appropriate Factories Act and the British Code of Practice for the Maintenance of Electrical Switchgear B.S. 5405. No instruction in this manual takes precedence over the above.

In other countries, the operator must make himself familiar with any National or Local Safety regulations.

It should be particularly noted that once the circuit-breaker truck has been withdrawn, it is complete isolated and safe to work upon. This does not apply to fixed housing which, although shielded, contains isolating contacts, busbars, buswires etc., that are still energized and must be isolated and grounded elsewhere before any work is done upon them.

This instruction book may recommend the use of various oils, greases, solvents, adhesive sealants etc. It is important that these products should be used only in the manner for which they are intended and that any instructions and cautions contained in the Manufacturer's literature or package markings are followed.

10. MAINTENANCE

The continued efficiency of a circuit-breaker and the length of its working life will depnd upon the maintenance it receives. With regular attention, its ability to operate satisfactorily under emergency conditions will be preserved for many years.

10.1 ROUTINE MAINTENANCE

A circuit breaker in continuous service requires a regular check over all its functional elements.

10.1.1 MONTHLY

Check the automatic and manual closing and tripping of the circuit breaker.

Examine the breaker for superficial damage. To do this remove the front cover and raise the arc chute 166. Check bolts and screws for tightness, particularly the countersunk screws 31 and 73.

Clean off any accumulation of dust.

10.1.2 ANNUALLY

Thoroughly overhaul the breaker contact system, replacing any badly corroded contacts.

Check all mechanism settings and adjust if necessary replacing any doubtful components.

Inspect the arc chute and monitor the extent of arc erosion. The service life of the arc chute is exhausted when erosion has reduced the wall thickness in local areas to approximately half its original thickness.

Note:

Under "Spares and Replacement Procedures" advice is given as to when some parts should be replaced.

10.2 CLEANING

Dust all insulation carefully. Substations are frequently close to the railway track and may receive metallic dust from vehicle brakes. It is important to exclude all dust as far as possible.

The mechanism of the breakers should be wiped carefully, particular attention being paid to the trip knife 81 and half shaft 82.

10.3 LUBRICATION

No working surfaces should be allowed to become dry and a good high film strength lubricant should be used. For example: Shell Alvania No. 2 + 37 MoS2 grease.

10.4 CONTACTS

The arcing contacts, which are made of copper require little attention apart from removing blobs, which may appear after heavy short circuits.

The main contacts are silver faced and should be kept clean, to avoid damaging the fine silver face, harsh abrasives should not be used.

10.5 AUXILIARY CONTACTS AND SECONDARY ISOLATING CONTACTS

These contacts are heavily silver plated and should not be cleaned with harsh abrasives which would damage the silver face. Any regular switch cleaning fluid can be used for cleaning these.

11. SPARES AND REPLACEMENT PROCEDURES

11.1 ORDERING

Attention to the following points will hasten dispatch and ensure that the correct part is supplied.

- 11.1.1 Identify parts in accordance with the spares drawing in this instruction book or by reference to the other illustrations.
- 11.1.2 Always quote the serial number of the circuit breaker, together with the details on the rating plate, which is on the front side member of the breaker truck.
- 11.1.3 In the case of coils quote the ES number if this can be ascertained from the old coil, the voltage, if this is known, but always the serial number of the breaker.

11.2 ARC CHUTES

(See Illustration S778N)

These are removed and replaced by raising vertically. Apart from cleaning as recommended in the maintenance section of this book, it is not possible to service the arc chute or to replace detail parts.

The arc chute should be replaced when arc erosion has reduced the side plate locally to half its original thickness.

A complete new arc chute should be ordered.

11.3 CONTACTS

Replace both fixed and moving arcing contacts, when one of the moving contacts has worn halfway. Normally the moving contact is the first to wear.

11.4 ARCING CONTACTS

(See Illustrations \$778B and E)

11.4.1 MOVING CONTACTS

(See Illustration S778B)

The moving arcing contact 57 is secured to the two extended moving contacts 33 which are positioned centrally in the moving contact assembly. The same moving arcing contact 57 is used irrespective of the current size of the breaker or the number of main contacts.

To renew the moving arcing contact 57, remove the four countersunk screws 73 and the complete moving contact side arc runner 2. Remove nuts 34 with the associated stud and the two countersunk screws 31.

The arcing contact can now be removed from between the two center blades. It is not usually necessary to replace the fiberglass backing plate.

As aluminum and copper are dissimilar metals, when re-making the joints between the moving arcing contact 57 and extended moving contacts 33, both surfaces should be cleaned and a similar jointing compound such as Cual-Aid should be applied, before clamping together.

Assemble the backing plate and the new copper moving arcing contact 57, fit the stud and two nuts 34, but do not tighten. Replace the countersunk screws 31, tighten the nuts 34 and then check that the new contact lies flat along the face of the aluminum blades to give the correct auxiliary arcing contact setting as described under "Settings and Adjustments - Main Contacts".

11.4.2 ARC RUNNERS

(See Illustrations S778B or E)

If it should be necessary to replace an arc runner 1 or 2 and not the fixed arcing contact 78,, this can be accomplished without disturbing any settings.

Lift off the arc chute and remove the four countersunk screws 73, which secure each arc runner. A hexagon wrench with a short reach will be required for this. If an arcing contact change is being carried out, the arc runner can be changed at the same time.

There should be a gap of between 2.0mm and 3.0mm between the top of both the fixed and moving arcing contacts 78 and 57 and the associated arc runners 1 and 2.

11.4.3 FIXED ARCING CONTACTS

(See Illustration S778E)

To change the fixed arcing contacts, proceed as follows, first removing the complete fixed arcing contact assembly.

- (1) Remove the screws 71, which secure the flexible connections 70 to the base place.
- (2) Remove the four front screws 72 at the sides of the fixed arcing contact assembly.

The complete fixed arcing contact assembly, with arc runner can now be removed from the circuit breaker.

- (3) Remove the countersunk screws 73 from one support plate 74 so that it can be removed leaving the other support plate still in place.
- (4) With a suitable clamp or vice, compress the springs 65 JUST SUFFICIENTLY for the two square arcing contact nuts 69 to pass one another (i.e. about 3/8") (10.0mm) DO NOT OVER COMPRESS. Unscrew nut 69 and remove the fixed arcing contact 78 complete with springs.
- (5) Remove the other fixed arcing contacts.

The complete fixed arcing contact is a replaceable spare and comes with stud.

Replacement of the fixed arcing contact is the reverse of the above procedure. Make sure that spring retainer 77, trunnion 66, buffer 67, buffer plates 68 and arcing contacts nuts 69 are all threaded onto the stud in the correct order. Be careful not to overtighten the springs during assembly and note that there are two springs (an inner and an outer) per contact.

Final adjustment can be carried out only when the fixed arcing contact assembly has been fitted to the breaker and is described earlier under - "Settings and Adjustment - Arcing Contacts". If it should be necessary to change the fixed arc runner 1 at the same time as the arcing contacts this should be done after the arcing contacts have been removed, bolting up to one side first.

Note that the arcing contact guide pin 76 is loose and must be located properly in its special bearing, which is lubricated for life.

Make sure that the flexible connections 70 are connected up and that screws 71, 73 and 72 are properly tightened.

11.5 MAIN CONTACTS

11.5.1 MOVING CONTACTS

(See Illustrations \$778A and B)

All circuit breakers have two extended moving contacts 33 in the center which carry the moving arcing contact 57. The total number of blades varies with the current size as follows:

4,000 amp - 4

6.000 amp - 6

8,000 amp - 8

10,000 amp - 10

12,000 amp - 12

To remove the complete moving contact assembly proceed as follows:

- (1) Open circuit breaker, remove arc chute 166 S778N.
- (2) Remove screws 38 (\$7783) and the complete moving side arc runner assembly.
- (3) Open front panel of the circuit breaker by removing the 3 screws on the right hand rear of the panel.
- (4) Remove the nuts from the spring retainers at the front end of the opening springs 6 (S778A), which are thus released.
- (5) Remove the screws 44 securing the flexible connection 28 to the moving contacts 35 (S778B), retain the bridging connection which links all the blades electrically.
- (6) Remove pin 42 which will free the springs 6, the spring spacers and the horizontal front links 3 (S778A) and the drive links to the puffer bellows.
- (7) Remove pin 45 (S778B), which will free the complete assembly.

Examine the flexible connection 28. This connection provides the return path from the arc runner 2 to the bottom fixed contact 27 and passes heavy current during fault interruption. It is important and if damaged should be replaced. Individual blades cannot be replaced, the standard spare part is a complete assembly which varies according to the current size of the breaker. It is supplied with the moving arcing contact 57 already fitted. If in an emergency, individual blades have to be fitted, they should be lined up carefully on the pins 42 and 45, before the nuts 36 and

43 are tightened. A check should be made that the silver faces of the contact system are all exactly in line, correct where necessary by careful filing.

Tighten the nuts 36 and 43 to 25 lb./ft. (33 Nm) and then ream the two main holes to give a clearance of 0.002" to 0.004" (0.05mm) to 0.10mm) over the pin diameter. This should be attempted in cases of extreme urgency only.

To replace the contact assembly proceed as follows:

- (1) Place the contact assembly in position and insert pin 45. The pins are initially treated with graphite and a little oil or a good quality grease with molybdenum disulphide should be applied before insertion. Shell Alvania 2 + 3% MoS2 is suitable.
- (2) Insert pin 42 picking up the two horizontal links

 3 (these fit equidistant from the center of the
 assembly between the standard moving contacts 35
 and the extended moving contacts 33) and also the
 spring spacers.
- (3) Hook the opening springs 6 over the pin 42, these fit equidistant from the center of the assembly separated by four moving contact blades. Secure the pin 42 with washers and split pins.
- (4) Re-connect the flexible connections 28. It is necessary to clean the adjoining faces of the bridging connection and the blades and to apply a jointing compound as these are made of dissimilar metals. A suitable compound is Cual-Aid.

Ensure that all the screws are securely tightened.

Note:

The bridging connection, which electrically joins all the aluminum moving contact blades must be located between the flexible connection 28 and the blades.

(5) Hook the face ends of the opening spring 6 through the spring retainer, pass the stems of the retainer through the spring block attached to the mechanism adjustment bracket 7 and secure with the nuts and springwashers removed during dismantling. These nuts are tightened until the flange of the spring retainer is brought into contact with the spring block.

Note that the spring retainer 180 (\$778P) must always be assembled so that it is above the spindle upon which block 177 is mounted.

- (6) Replace moving side arc runner assembly and tighten screws 38.
- (7) Check contact pressure and arcing contact lead as described under "Settings and Adjustment - Main Contacts and Arcing Contacts".
- (8) Secure front panel of circuit breaker, replace the arc chute 166.

11.5.2 FIXED CONTACTS

(See Illustrations S778A, B, C, and D)

To remove the complete fixed contact assembly, refer to Illustration S778B and proceed as follows:

Bottom Contacts

- (1) Remove insulation connection 41 (S778B).
- (2) Close the circuit breaker.
- (3) Remove the hex head screws 52 from the bottom fixed contact assembly, to free the contact guide 53.
- (4) Open the circuit breaker by pressing hard on the manual closing handle as though trying to further close the breaker and while retaining this pressure, release the prop arm (14 on \$778A) by pulling its spring holder forward and slowly releasing the pressure on the closing handle, thus permitting the breaker to open. DO NOT TRIP the circuit breaker by its manual "Press to Trip".
- (5) Remove the screw 172 (S778B) from each side of the spring channel 59 (S778C). Remove the pillar 46 from one side; this requires the removal of screw 47, which is achieved by obtaining access from underneath through the hole in the truck platform.

The complete assembly can now be removed by sliding sideways.

Top Contacts

(1) Remove the fixed arcing contact assembly (See 11.4.3).

- (2) Remove the insulated connection 41 (S778B).
- (3) Remove the nylon screws 173, thus freeing the finger shield 50 and disconnect the puffer drive links from pin 42.
- (4) Remove the two screws 172 (S778B) and the spring guide 184 taking care not to lose the spring 183 (S778C) or spring holders 185 (S778C) and lift the contact guide off its dowel pins.
- (5) The top fixed contact assembly can now be withdrawn forwards. It will be necessary to depress the finger shield 50 (\$778B) while doing this.

This is easier when the bottom contact also has to be removed, if the bottom contact is removed first.

Examine the silver contact tips 48 and 51 and clean carefully if necessary.

Replacement of the complete assemblies is a reversal of the removal. Replace the top assembly first and close the breaker to replace the contact guide 53 onto the dowel pins.

Ensure that the springs and plungers are inserted in the housing, with the plungers at the rear, adjacent to the arcing contact assembly (S778C) before offering this up for re-assembly.

Ensure that the puffer nozzles 199 are re-sited correctly in the finger shield assembly.

Contact pressure should be checked and re-set if necessary according to instuctions given under "Settings and Adjustment - Arcing Contacts and Main Contacts". Replace arc chute.

Individual Contacts

(See Illustrations S778C and D)

In the case of fixed contacts, it is possible to replace individual contacts and this may be necessary as the center two top fixed contacts act as auxiliary arcing contacts, and will be subjected to some burning.

The complete assembly is as shown on Illustration S778D. The center two contacts at the top are extended to form auxiliary arcing contacts. These two contacts have additional spring pressure, because of their increased length, provided by the additional springs at the rear.

All current sizes have two extended auxiliary arcing contacts 64 at the top center. The equivalent center bottom contacts are advanced over the remainder but not extended in length.

On all breakers except 4,000 amps, the next contact on each side of the two extended auxiliary arcing contacts are advanced contact fingers 61 which are advanced but not extended and are similar to the two center bottom contacts.

8,000 amp breakers have two auxiliary arcing contacts 64 in the center, one advanced contact finger 61 on each side and then two half size contact fingers 188 and 187 on each side.

The individual contact fingers 63 (S778C) can be removed from the channel 59 by starting one contact at a time from either end and compressing the spring 60 with a compression Tool No. S408766 if a vice is available, or squeezing the contact guide and spring holder at the points "T" with slip-joint pliers or "channel-locks" if a vice is not available (S778C, Figure 2). With a little juggling, the grooved pin 58 will fall out releasing the spring and spring-holder.

Replacing the contacts is somewhat easier; start at the center and note that the extended auxiliary arcing contacts have reduced length "tee" pieces 62 (S778C) and the advanced contact fingers 61 adjacent to them and those acting as center bottom contacts have a wider slot in the top to provide the advance.

All these must be returned to the position from which they were removed, or replaced with equivalent parts. All springs 60 are the same.

11.6 MAIN ISOLATING CONTACTS

These are replaceable spares and are all alike for various current sizes. The complete assembly should be ordered; individual contacts are not replaceable.

11.7 OVERLOAD TRIP

(See Illustration S778G)

It is not possible to remove the complete overload unit from the breaker without completely dismantling the bottom fixed contact 27, because the magnetic yoke 110 encloses it. It should never be necessary to remove the complete assembly.

To remove the overload springs 106, proceed as follows:

- 11.7.1 Trip circuit breaker.
- 11.7.2 Note the trip setting and turn the calibration screw 103 anticlockwise as far as possible to reduce the tension on the springs.
- 11.7.3 Remove screws 113 from top and bottom of the calibration bearing plate.
- 11.7.4 Remove screws 105 top and bottom and slacken screws 174 top and bottom. Do not release screws 109.
- 11.7.5 Slacken nut 111 and separate the two guide plates sufficiently to allow the trunnion 112 to pass beyond its slot.

The calibration screw 103, locating block, trunnion 112, bearing washer, springs 106 and spring guides are now free and the springs may be changed.

Replacement is a reversal of the above; ensure that the pips at the end of the spring guide locate correctly in the armature pressure plate 107. Be sure to re-set the trip setting to its original position before putting the breaker back into service.

11.8 UNDERVOLTAGE RELEASE

(See Illustration S778K)

The undervoltage release is mounted behind the front panel and is easily removed if the front panel of the circuit breaker is opened by removing the three screws on the right hand rear of the panel.

Disconnect the coil leads and ensure that these are properly connected and tightened on replacement of the unit and that the series resistor is in order.

The undervoltage release unit is secured to the top of the truck at the front with screws underneath. Re-set as described earlier.

11.9 UNDERVOLTAGE RELEASE COIL

(See Illustration S778K)

To remove the undervoltage release coil proceed as follows:

11.9.1 Open breaker front panel as previously described.

- 11.9.2 Disconnect coil.
- 11.9.3 Remove pin 129 and disengage the striker nut 121 from the trip lever. Do not disturb screws 130.
- 11.9.4 Remove pin 124 and swing the armature 125, links and spring, forward out of the way.
- 11.9.5 Unscrew the core 128 using the 2 flats provided to free the coil.

Replacement is a reversal of the above. Ensure that the striker nut 121 engages in the correct hole in the trip lever (See Illustration S778J) before replacing pin 129.

The setting should not have been disturbed but should be checked in accordance with the instructions under "Settings and Adjustments - Undervoltage Release".

Note:

Undervoltage releases usually have a series resistor which may have been damaged if the coil has burnt out and this will also require replacing.

11.10 SHUNT TRIP

(See Illustrations S778L and Q)

The shunt trip is mounted behind the front panel on a sub-panel 196. For access first remove the three screws on the right hand rear of the panel.

Remove clevis pin 189 and pivot screw 190 (S778L) and swing the associated links out of its way. Remove bolt 194 (S778Q) from both sides of the front truck shrouds and release but do not remove bolts 195.

The sub-panel 196 can now be swung outwards and downwards through 90 degree complete with its components and wiring to give access to remove the shunt trip assembly.

Disconnect the coil leads and ensure that these are properly connected and tightened on replacement of the unit.

Re-set as described earlier.

11.11 SHUNT TRIP COIL

(See Illustration S778L)

To remove the shunt trip coil proceed as follows:

- 11.11.1 Open the circuit breaker and remove from the housing.
- 11.11.2 Open front panel and lower the sub-panel as described in 11.10.
- 11.11.3 Disconnect coil leads.
- 11.11.4 Release spring 192.
- 11.11.5 Remove the four screws 133 which secure the shunt trip unit to the sub-panel. This will free the complete shunt trip assembly from the circuit breaker.
- 11.11.6 The moving core 137 is now free and can be removed from the bottom of the shunt trip assembly; care should be taken to retain the anti-cling washer 191 for replacement.
- 11.11.7 Remove the two bottom screws 136. This will release the bottom plate together with spool 139, and shunt trip coil 138.
- 11.11.8 Remove the two screws which secure the spool 139 to the bottom plate. The shunt trip coil 138 with its spool 139 will then be free.

Replacement is a reverse of the above; ensure that the anti-cling washer is in place.

The setting should not have been disturbed, but should be checked in accordance with the instructions under "Settings and Adjustment - Shunt Trip".

11.12 AUXILIARY SWITCH, INTERLOCK, COUNTER ETC.

Access for removal or checking of the auxiliary switch, the operations counter, the ON/OFF indicator, the Castell interlock and various auxiliary indicating micro-switches (if fitted) or wiring alterations or checks can be obtained by opening the front panel and releasing the sub-panel as in 11.10.

11.13 REVERSE CURRENT TRIP

(See Illustration S778M)

The reverse current trip magnet assembly encloses all or part of the vertical bottom fixed contact 27. It is divided into parts, a coil, 160, armature 176 and magnet assembly and a horseshoe magnet yoke 154. To remove the unit from the breaker, the two parts have to be separated.

To remove the complete unit proceed as follows:

- 11.13.1 Remove the circuit breaker from the housing.
- 11.13.2 Remove the clevis pin 151 from the top end of the armature. This pin is retained with a special spring clip which must be kept for replacement.
- 11.13.3 Remove the two screws 158 to free the spring adjuster 157, return spring 152 and clevis. Do not disturb the spring adjuster 157 or its nut 156. The bracket, return spring 152 and adjuster 157 should be left assembled to preserve its setting.
- 11.13.4 Remove the clevis pin 155, again keeping the spring retainer for replacement. This frees the trip rod which should be removed completely and kept for replacement.
- 11.13.5 Remove the coil leads, noting and marking so that each lead is returned to the same terminal.

Note:

Reversing these leads will reverse the current direction in which the unit will operate. If left off, the unit will not operate at all.

- 11.13.6 Remove the socket headed screws 149 (two on each side) to free the coil 160 and armature assembly 176 from the horseshoe yoke 154.
- 11.13.7 Remove the screws 147 from each side of the breakers, noting that on larger sized breakers there are spacing tubes between the unit and the breaker side panel 30.

The unit can now be removed from the breaker by lowering it and passing it underneath the mechanism. The horseshoe yoke 154 will be left behind. Replacement is a reversal of the above procedure. Make sure that the coil is correctly connected and that the trip linkage is free. A check should be make on the trip linkage clearance as described previously under "Settings and Adjustments - Reverse Current Trip".

11.14 REVERSE CURRENT TRIP COIL

(See Illustration S778M)

To replace the reverse current trip coil, the unit must be split and removed from the breaker as described previously in Section 11.13 - Reverse Current Trip.

With the coil and armature assembly removed from the breaker, to remove the coil, proceed as follows:

- 11.14.1 Remove the eight coil fixing screws 161 four at the top and four at the bottom.
- 11.14.2 Release re-set spring 150 at one end and swing the link 159 out of the way. Release M8 nuts and remove lower fixing bar.
- 11.14.3 The coil and armature assembly will now slide sideways from the yoke allowing the former-wound coil to be removed from the bobbin, which carries the pivot for the armature 176.

Replacement is a reversal of the above.

Note 1:

The coil can be fitted either way up without changing the direction of operation, but the leads must be connected the right way around i.e. the lead connected to the top before replacement of the coil must be connected to the top afterwards, similarly, the lead to the bottom must also still be in the same position.

Note 2:

Reverse current releases usually have a series resistor which may have been damaged and need replacing if the reverse coil has burnt out.

Note 3:

If on returning the circuit breaker to service, the breaker trips immediately load is applied, the coil has been incorrectly connected.

11.15 CLOSING SOLENOID COIL

(See Illustration S778A)

To facilitate removal of the coil, the breaker truck must be raised about 50mm by jacking or running up onto ramps.

- 11.15.1 Remove the split pin 182 in the racking shaft and withdraw the complete shaft from the front.
- 11.15.7 Disconnect coil leads.
- 11.15.3 Operate the trip lever 116 (S778J) and while keeping this in the operated position attempt to close the breaker with the manual emergency closing handle. This will raise the moving core 21 (S778A) without closing the breaker. Tie or hold the handle in this position.

- 11.15.4 Remove screws 22 and the bottom solenoid plate which can remain within the confines of the truck.
- 11.15.5 The coil can now be removed from the rear of the truck. If difficulty is experienced remove the two rear pillars 23. Should it be necessary for any reason, the complete solenoid can be removed by removing the pin through the guide roller 17, the screws holding the guide plate and the mounting nuts 25. The weight of the solenoid must be supported from the bottom for this operation.
- 11.15.6 Replacement is a reversal of the above. Settings should not have been disturbed but should be checked in accordance with Paragraph 6.1.

ILLUSTRATIONS

KEY TO COMPONENT NUMBERS ON ILLUSTRATION S778A

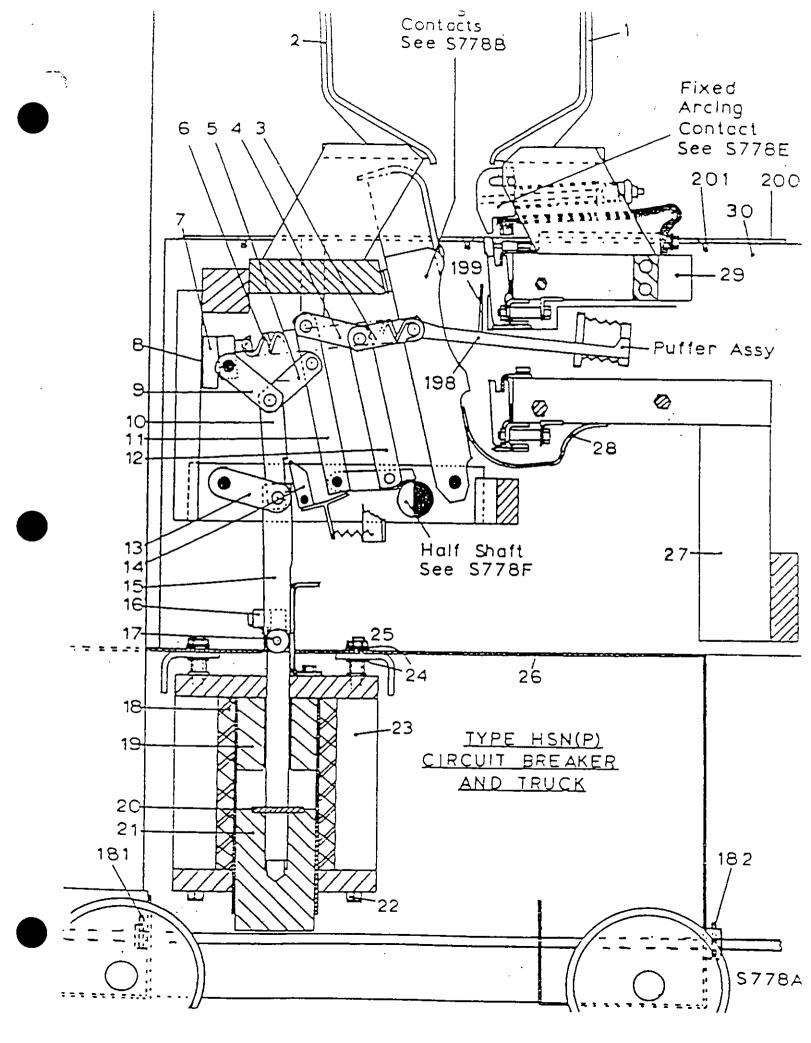
TYPE HSP CIRCUIT BREAKER AND TRUCK

- 1. Arc Runner (Fixed Contact Side)
- 2. Arc Runner (Moving Contact Side)
- 3. Horizontal Front Link
- 4. Horizontal Center Link
- 5. Horizontal Center Link
- 6. Opening Spring
- 7. Mechanism Adjustment Bracket
- 8. Mechanism Adjustment Shims
- 9. Horizontal Center Link
- 10. Prop Link
- ll. Center Link
- 12. Front Link
- 13. Guide Link
- 14. Prop Arm
- 15. Solenoid Link
- 16. Manual Close Roller
- 17. Guide Roller
- 18. Solémoid Coil
- 19. Solenoid Fixed Core
- 20. Buffer Washer
- 21. Solenoid Moving Core
- 22. Bolt
- 23. Spacing Pillar
- 24. Adjustment Shim
- 25. Nut
- 26. Truck

- 27. Bottom Fixed Contact
- 28. Flexible Connection
- 29. Top Fixed Contact
- 30. Breaker Side Panel
- 42. Pin
- 181. Split Pin
- 182. Split Pin
- 198. Puffer Drive Link
- 199. Puffer Nozzle
- 200. Insulation Plate

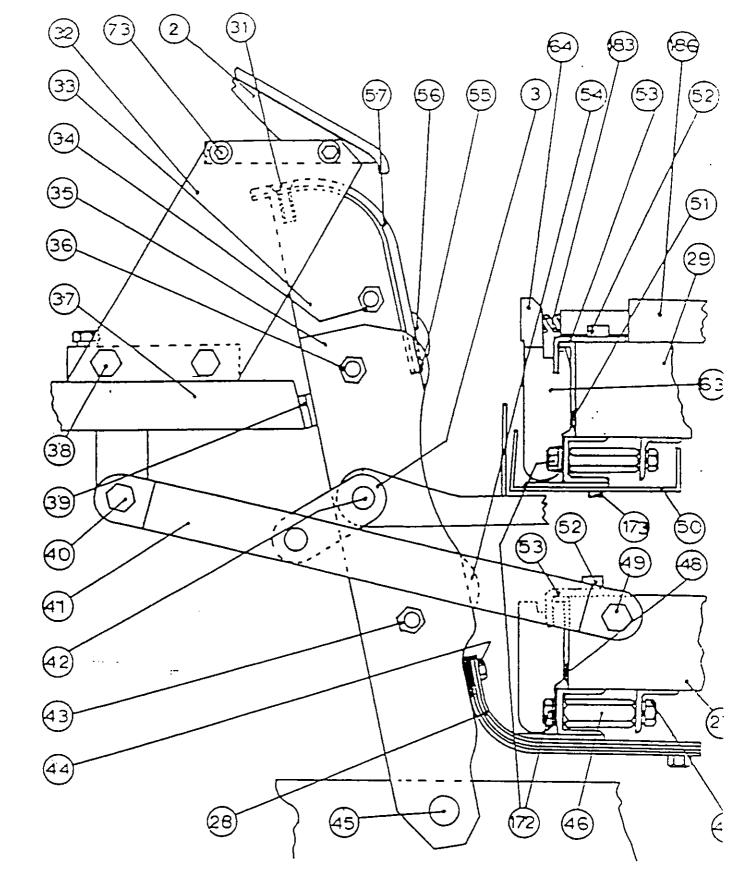
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201. Fixing Screw



FIXED AND MOVING CONTACTS

- Arc Runner (Moving Contact Side)
- 3. Horizontal Front Link
- 27. Bottom Fixed Contact
- 28. Flexible Connection
- 29. Top Fixed Contact
- 30. Breaker Side Panel
- 31. Countersunk Screw
- 32. Support Plate
- 33. Extended Moving Contact
- 34. Nut
- 35. Moving Contact
- 36. Nut
- 37. Stop Panel
- 38. Screw
- 39. Buffer Bar
- 40. Bolt
- 41. Insulated_Return Connection
- 42. Pin
- 43. Nut
- 44. Screw
- 45. Pin
- 46. Pillar
- 47. Screw
- 48. Silver Contact Tip
- 49. Bolt
- 50. Finger Shield
- 51. Silver Contact Tip
- 52. Socket Screw
- 53. Contact Guide
- 54. Silver Contact Tip
- 55. Silver Contact Tip
- 56. Silver Cadmium Oxide Contact Tip
- 57. Moving Arcing Contact
- 63. Contact Finger
- 64. Auxiliary Arcing Contact Finger
- 73. Countersunk Screw
- 172. Screw :--
- 173. Nylon Screw
- 183. Spring
- 184. Spring Support Block

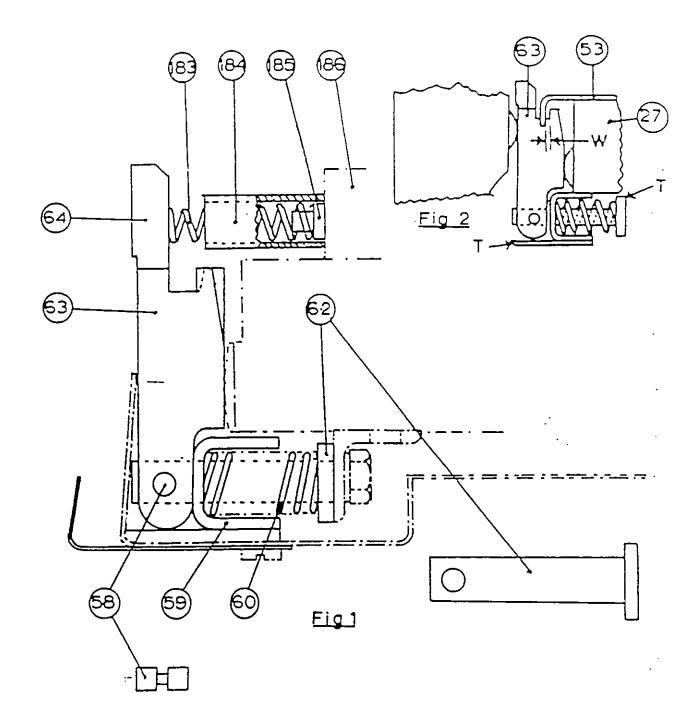


FIXED AND MOVING CONTACTS

KEY TO COMPONENT NUMBERS ON ILLUSTRATION S778C

FIGURES 1 AND 2 FIXED CONTACT ASSEMBLY

- 53. Contact Guide
- 58. Grooved Pin
- 59. Spring Channel
- 60. Spring
- 62. Spring Holder
- 63. Contact Finger
- 64. Auxiliary Arcing Contact Finger
- 183. Spring
- 184. Spring Guide
- 185. Spring Holder
- 186. Spring Support Block

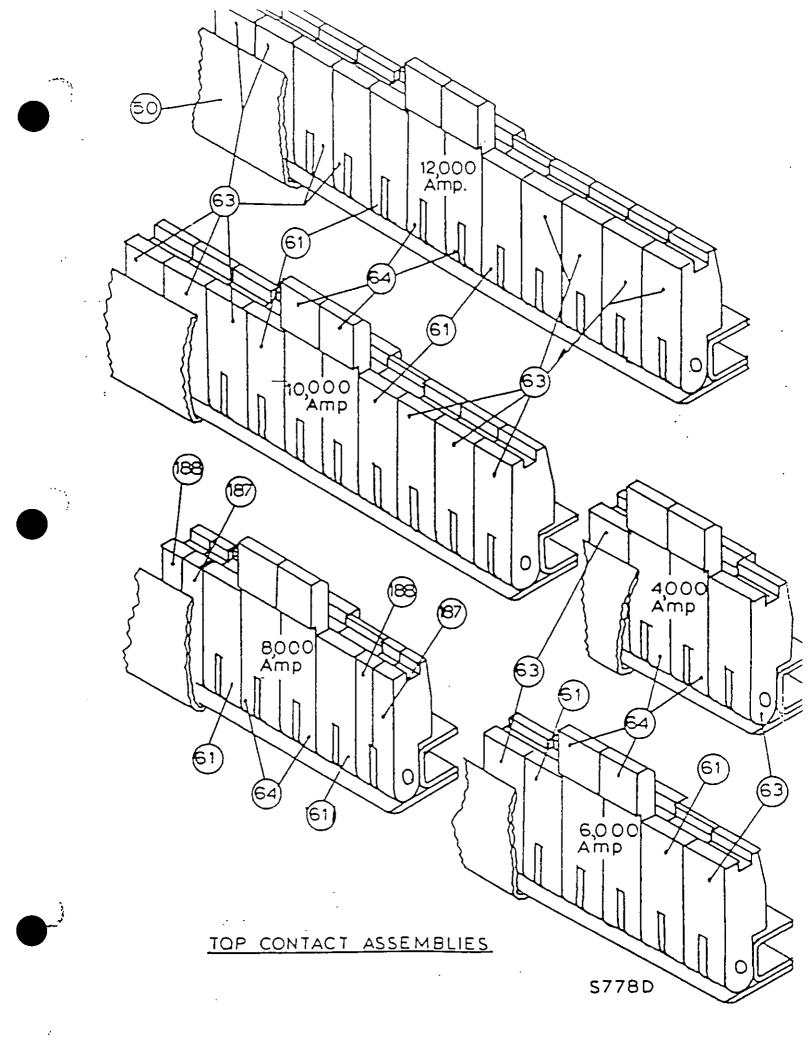


FIXED CONTACT ASSEMBLY

KEY TO COMPONENT NUMBERS ON ILLUSTRATION S776D

TOP CONTACT ASSEMBLIES

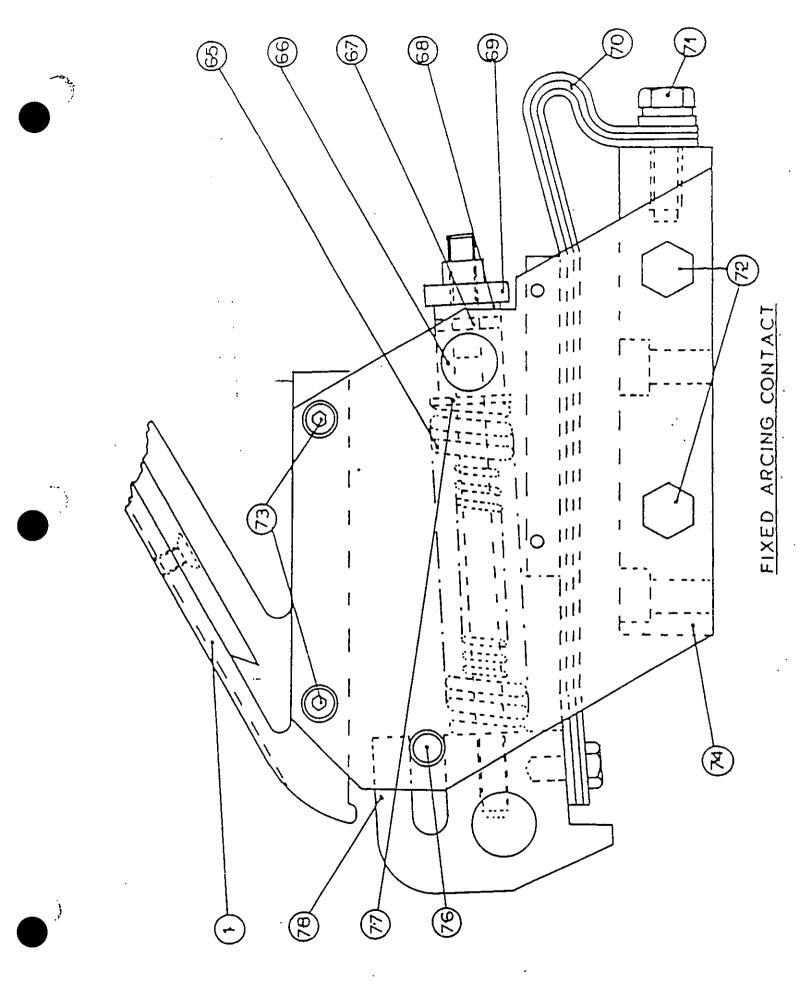
- 50. Finger Shield
- 61. Advanced Contact Finger
- 63. Contact Finger
- 64. Auxiliary Arcing Contact Finger
- 187. L.H. Half Contact Finger
- 188. R.H. Half Contact Finger



KEY TO COMPONENT NUMBERS ON ILLUSTRATION S778E

FINED ARCING CONTACT

- 1. Arc Runner (Fixed Contact Side)
- 65. Springs
- 66. Trunnion
- 67. Buffer
- 68. Buffer Plate
- 69. Arcing Contact Nut
- 70. Flexible Connection
- 71. Screw
- 72. Screw
- 73. Countersunk Screw
- 74. Support Plate
- 76. Arcing Contact Guide Pin
- 77. Spring Retainer
 - 78. Fixed Arcing Contact



KEY TO COMPONENT NUMBERS ON ILLUSTRATION S778F

FIGURE 1 - HALF SHAFT AND LOWER MECHANISM

FIGURE 2 - HALF SHAFT AND TRIPPING LINKAGES

- 10. Prop Link
- 11. Centre Link
- 12. Front Link
- 13. Guide Link
- 14. Prop Arm
- -35. Moving Contact
- .43. Nut
- 79. Bolt
- 80. Washers
- 81. Trip Knife
- 82. Half Shaft
- 83. Striker Nut
- 84. Locknut
- 85. Safety Screw
- 86. Limit Screw
- 87. Trip Lever
- 88. Locknut
- 89. Striker Nut
- 145. Trip Drive Rod
- 153. Reverse Trip Rod

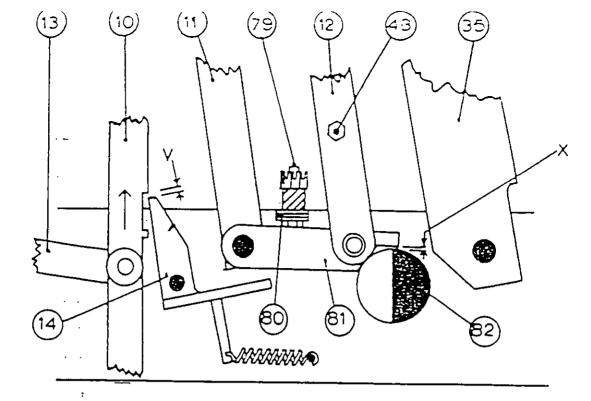


FIG1: HALF SHAFT AND LOWER MECHANISM

FRONT PANEL

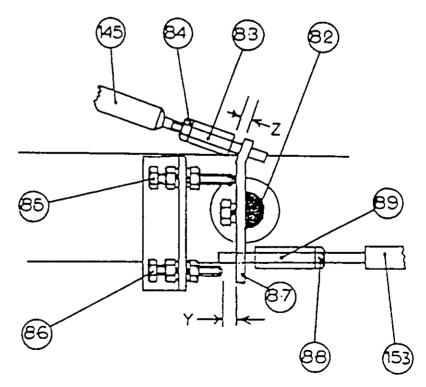
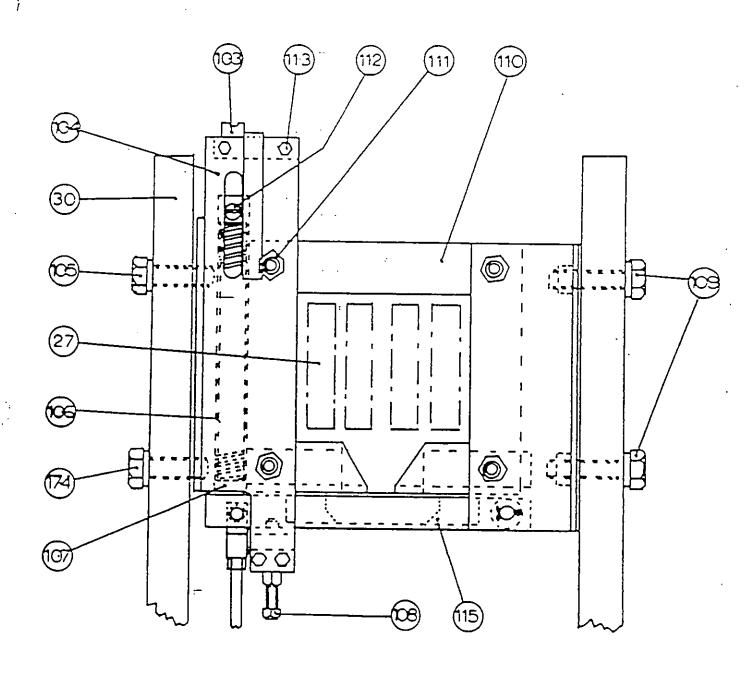


FIG2: HALF SHAFT AND TRIPPING LINKAGES

KEY TO COMPONENT NUMBERS ON_ILLUSTPATION S77EG

OVERLOAD UNIT

- 27. Bottom Fixed Contact
- 30. Breaker Side Panel
- 103. Calibration Screw
- 104. Support Bracket
- 105. Screw
- 106. Overload Springs
- 107. Armature Pressure Plate
- 108. Screw
- 109. Screw
- 110. Magnetic Yoke
- 111. Nut
- 112. Trunnion
- 113. Screw
- 115. Trip Armature
- 174. Screw

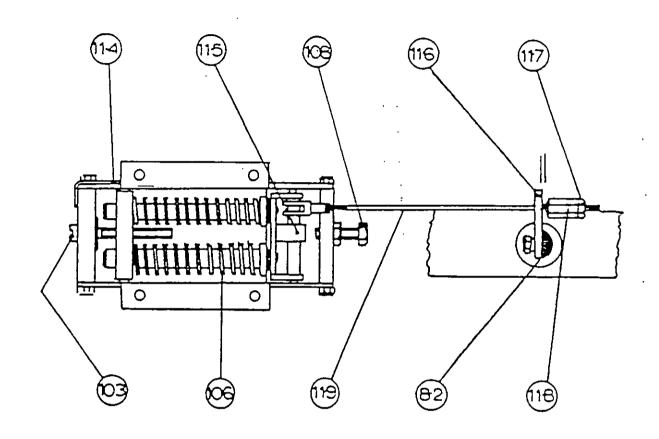


OVERLOAD UNIT

KEY TO COMPONENT NUMBERS ON ILLUSTRATION S778H

CVERLOAD UNIT AND TRIP LINKAGE

- 82. Half Shaft
- 103. Calibration Screw
- 106. Overload Springs
- 108. Screw
- 114. Calibration Plate
- 115. Trip Armature
- 116. Trip Lever
- 117. Adjusting Nut
- 118. Striker Nut
- 119. Overload Trip Rod



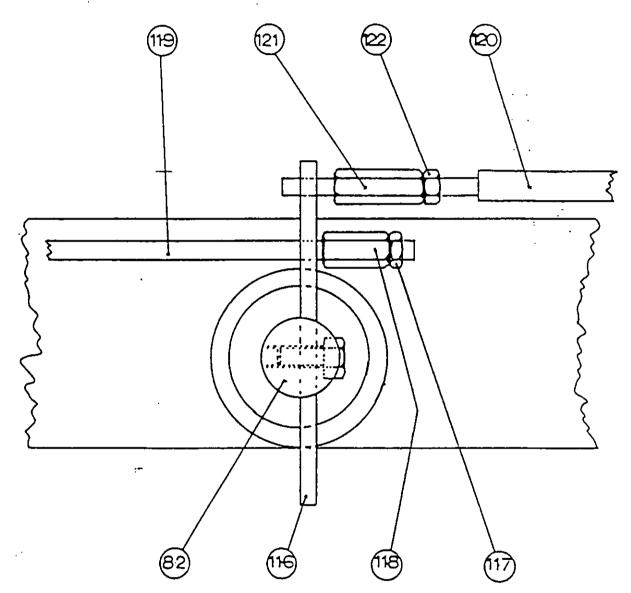
. OVERLOAD UNIT AND TRIP LINKAGE

Viewed from Left Hand Side of C.B.

KEY TO COMPONENT NUMBERS ON ILLUSTRATION STREET

OVERLOAD AND UNDERVOLTAGE PELEASE OPERATING RODS

- 82. Half Shaft
- 116. Trip Lever
- 117. Locknut
- 118. Striker Nut
- 119. Overload Operating Rod
- 120. Undervoltage Release Operating Rod
- 121. Striker Nut
- 122. Locknut



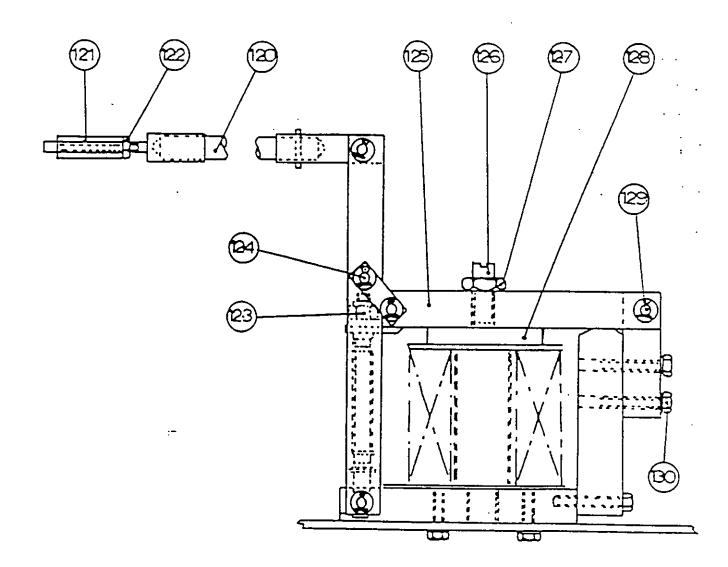
OVERLOAD AND UNDERVOLTAGE OPERATING RODS

NEY TO COMPONENT NUMBERS ON ILLUSTRATION S778K

UNDERVOLTAGE RELEASE

- 120. Undervoltage Release Operating Rod
- 121. Striker Nut
- 122. Adjusting Nut
- 123. Nut
- 124. Pin
- 125. Armature
- 126. Screw
- 127. Locknut
- 128. Core
- 129. Pin
- 130. Screws

BREAKER FRONT PANEL

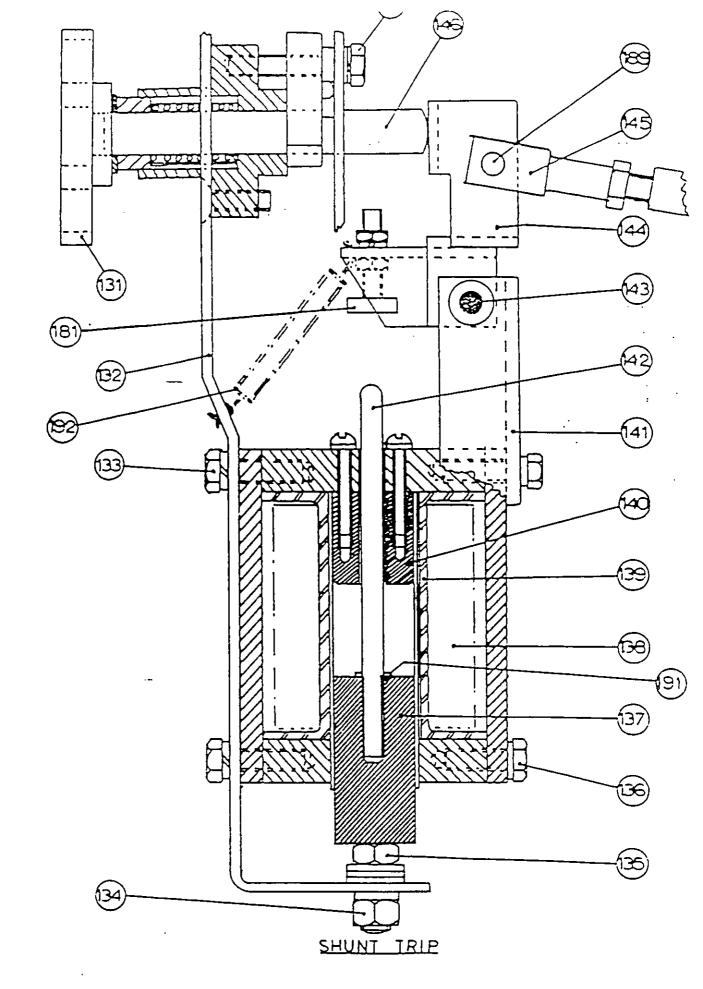


UNDERVOLTAGE RELEASE

KEY TO COMPONENT NUMBERS ON ILLUSTRATION S77EL

SHUNT TRIP

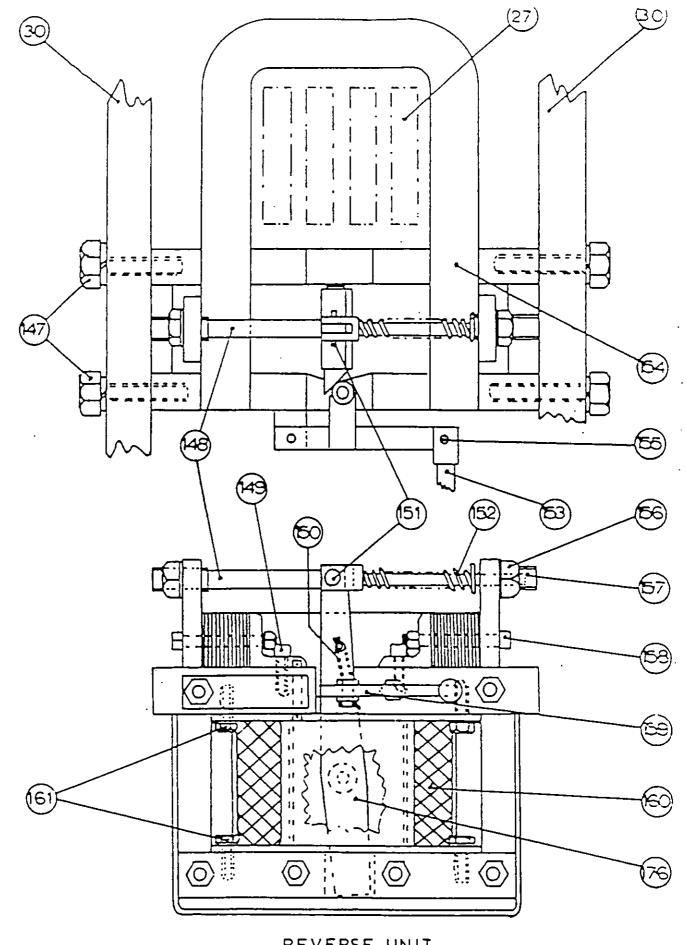
- 131. Hand Trip Knob
- 132. Inner Panel
- 133. Screw
- 134. Nut
- 135. Screw
- 136. Screw
- 137. Moving Core
- 138. Shunt Trip Coil
- 139. Spool
- 140. Fixed Core
- 141. Support Bracket
- 142. Trip Poker
- 143. Pivot Pin
- 144. Trip Bracket
- 145. Clevis
- 146. Trip Shaft
- 181. Trip Button
- 189. Clevis Pin
- 190. Pivot Screw
- 191. Anti-cling Washer
- 192. Spring



KEY TO COMPONENT NUMBERS ON ILLUSTRATION S77EM

REVERSE UNIT

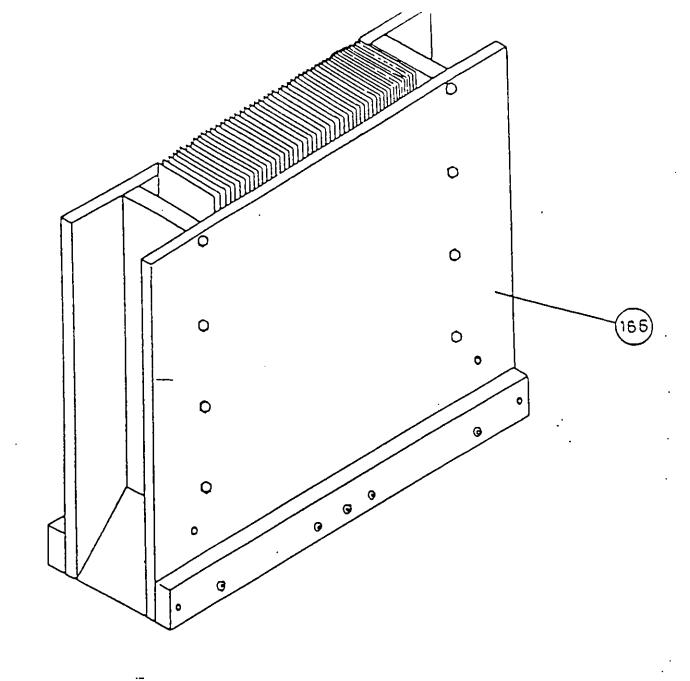
- 27. Bottom Fixed Contact
- 30. Breaker Side Panel
- 147. Screw
- 148. Stop Screw
- 149. Socket Screw
- 150. Re-set Spring
- 151. Clevis Pin
- 152. Return Spring
- 153. Reverse Trip Rod
- 154. Yoke
- 155. Clevis Pin
- 156. Nut
- 157. Spring Adjuster
- 158. Screw
- 159. Link
- 160. Coil
- 161. Screw
- 176. Trip Armature



REVERSE UNIT

ARC CHUTE

166. Arc Chute



ARC CHUTE

KEY TO COMPONENT NUMBERS ON ILLUSTRATION S778P

FIGURE 1 - L.T. CONTACTS

FIGURE 2 - OPENING SPRING AND MECHANISM ADJUSTMENT

- 6. Opening Spring
- 7. Mechanism Adjustment Bracket
- 8. Mechanism Adjustment Shims
- 170. Insulated Base
- 171. Spring Contact
- 177. Spring Block
- 178. Nut
- 179. Bolt
- 180. Spring Retainer
- 193. Spacer :

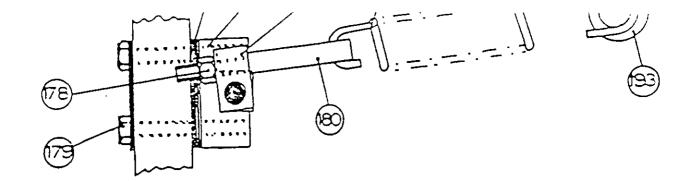


FIG 2 OPENING SPRING AND MECHANISM ADJUSTMENT

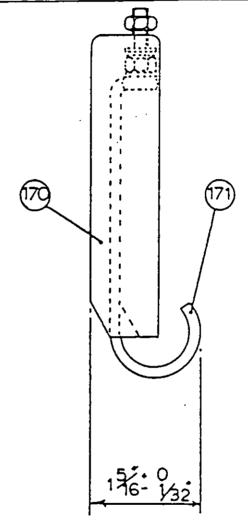
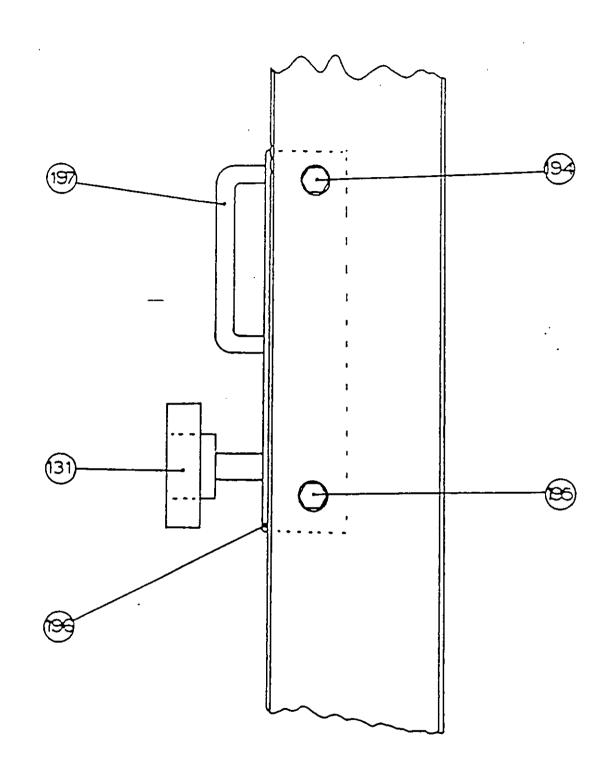


FIG 1 L.T. CONTACTS

KEY TO COMPONENT NUMBERS ON ILLUSTRATION 577EQ

SUB-PANEL

- $1\overline{3}1$. Hand Trip Knob
- 194. Bolt
- 195. Bolt
- 196. Sub-Panel
- 197. Manoeuvering Handle

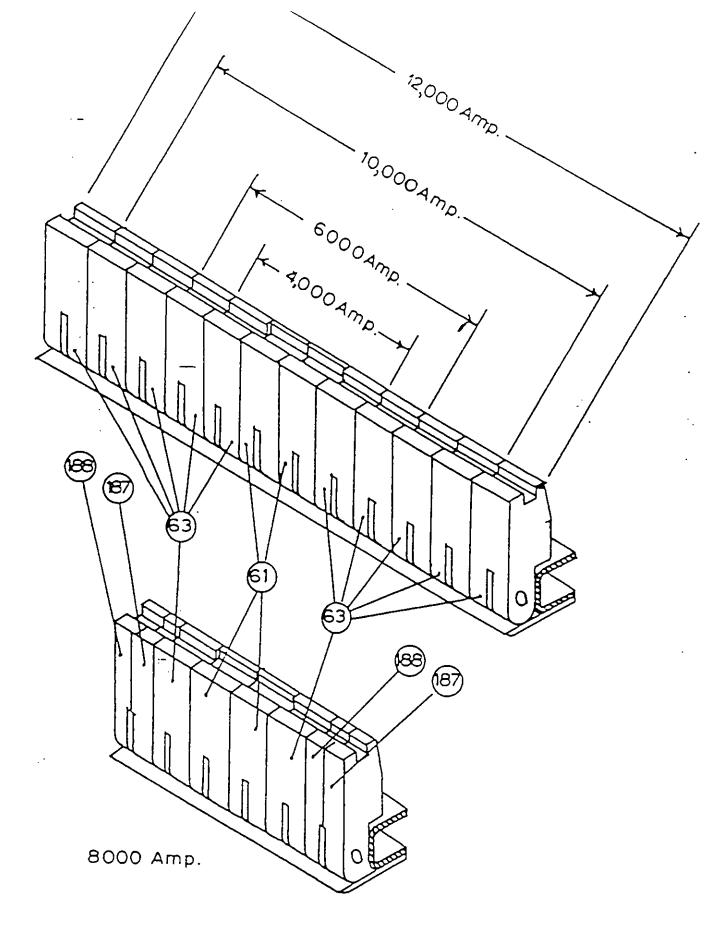


SUB - PANEL

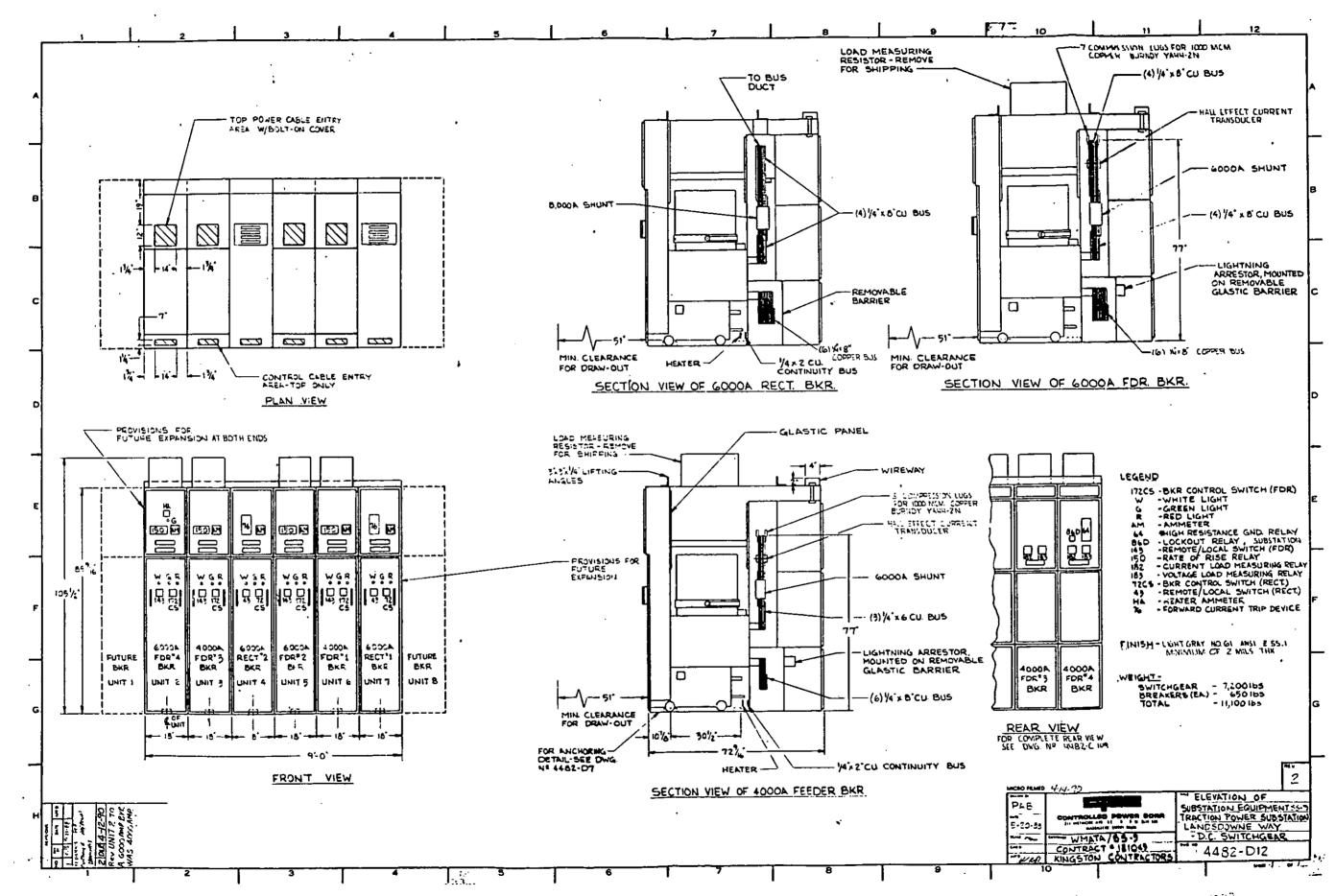
KEY TO COMPONENT NUMBERS ON ILLUSTRATION S77ER

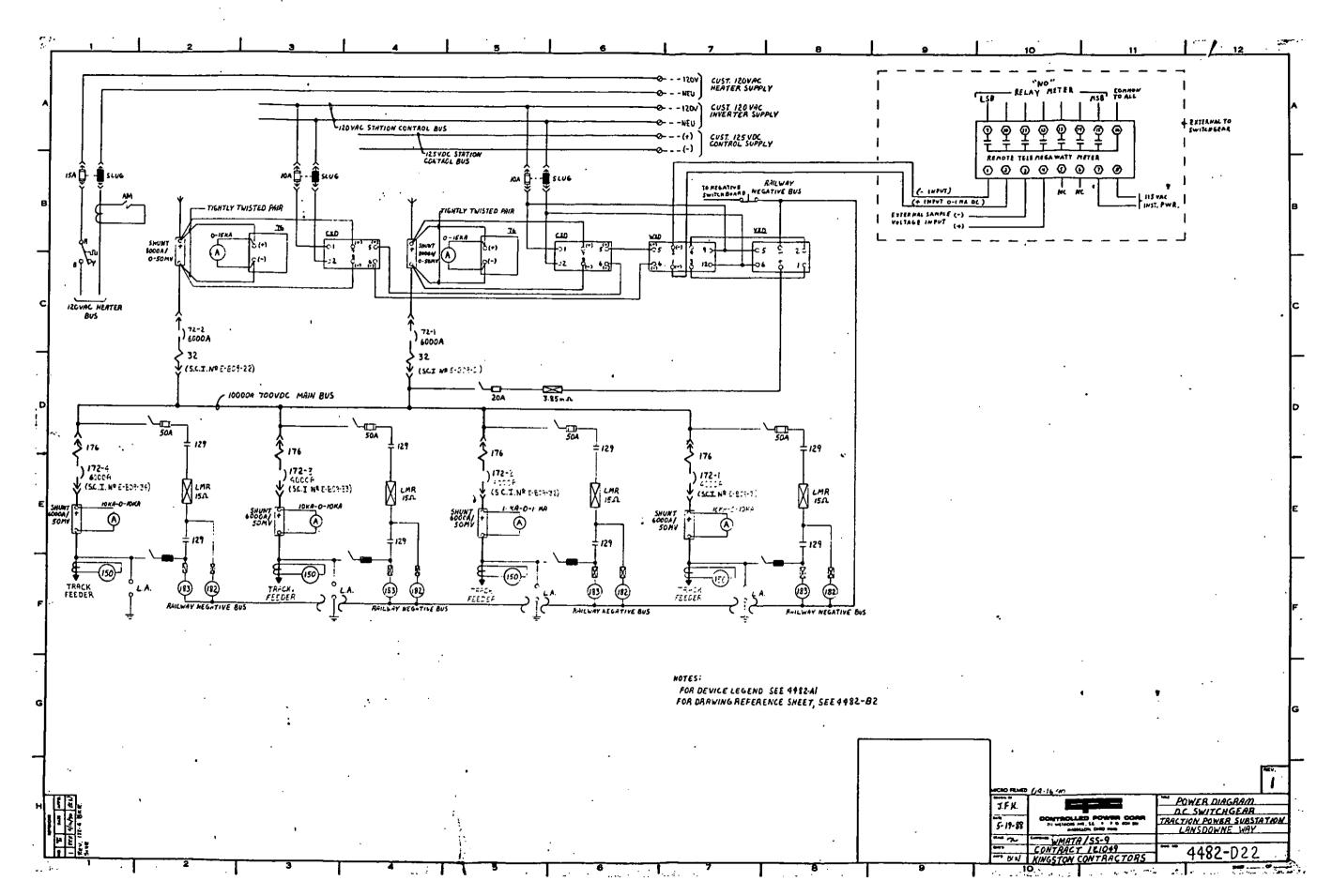
BOTTOM CONTACT ASSEMBLIES

- 61. Advanced Contact Finger
- 63. Contact Finger
- 187. L.H. Half Contact Finger
- 188. R.H. Half Contact Finger

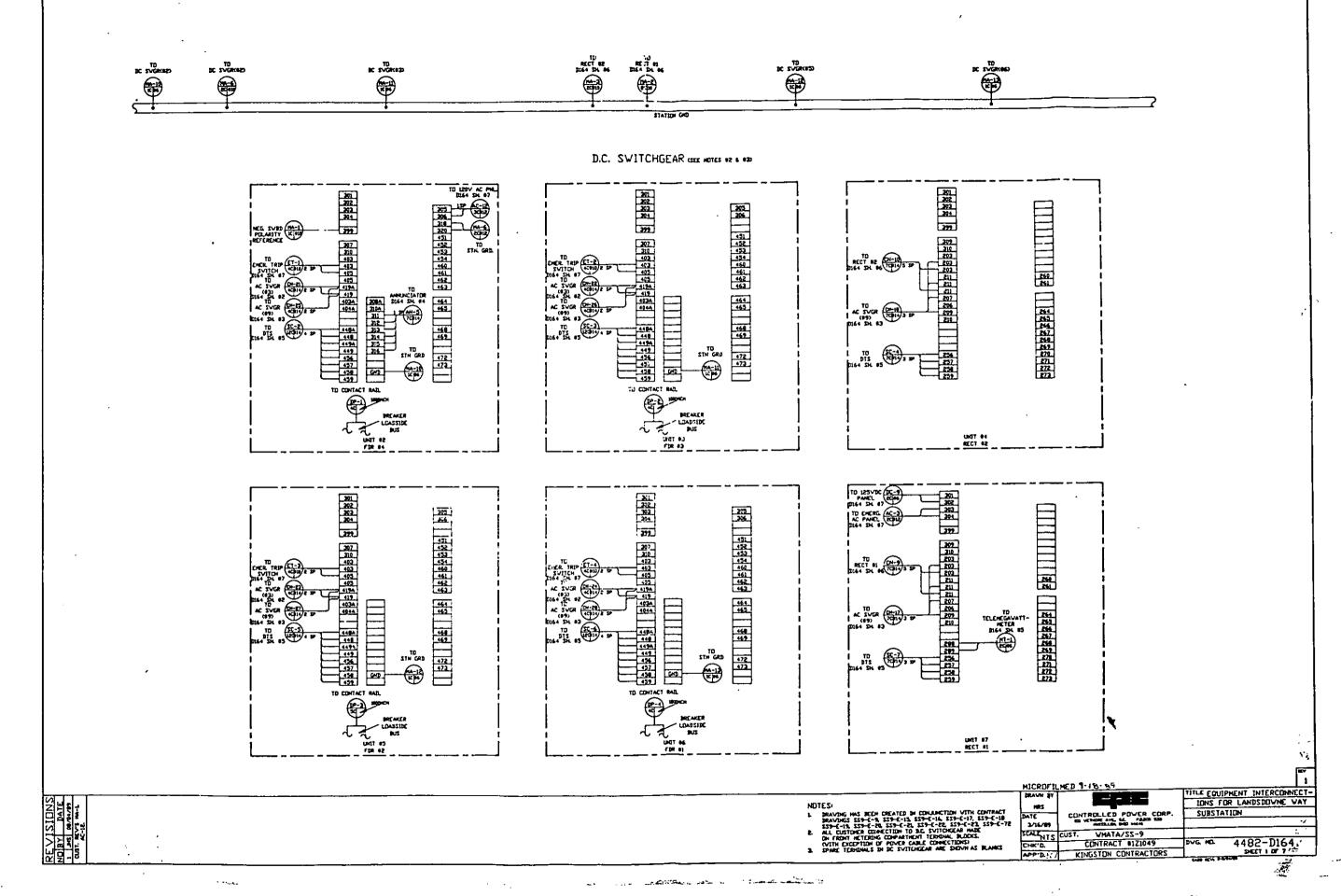


BOTTOM CONTACT ASSEMBLIES

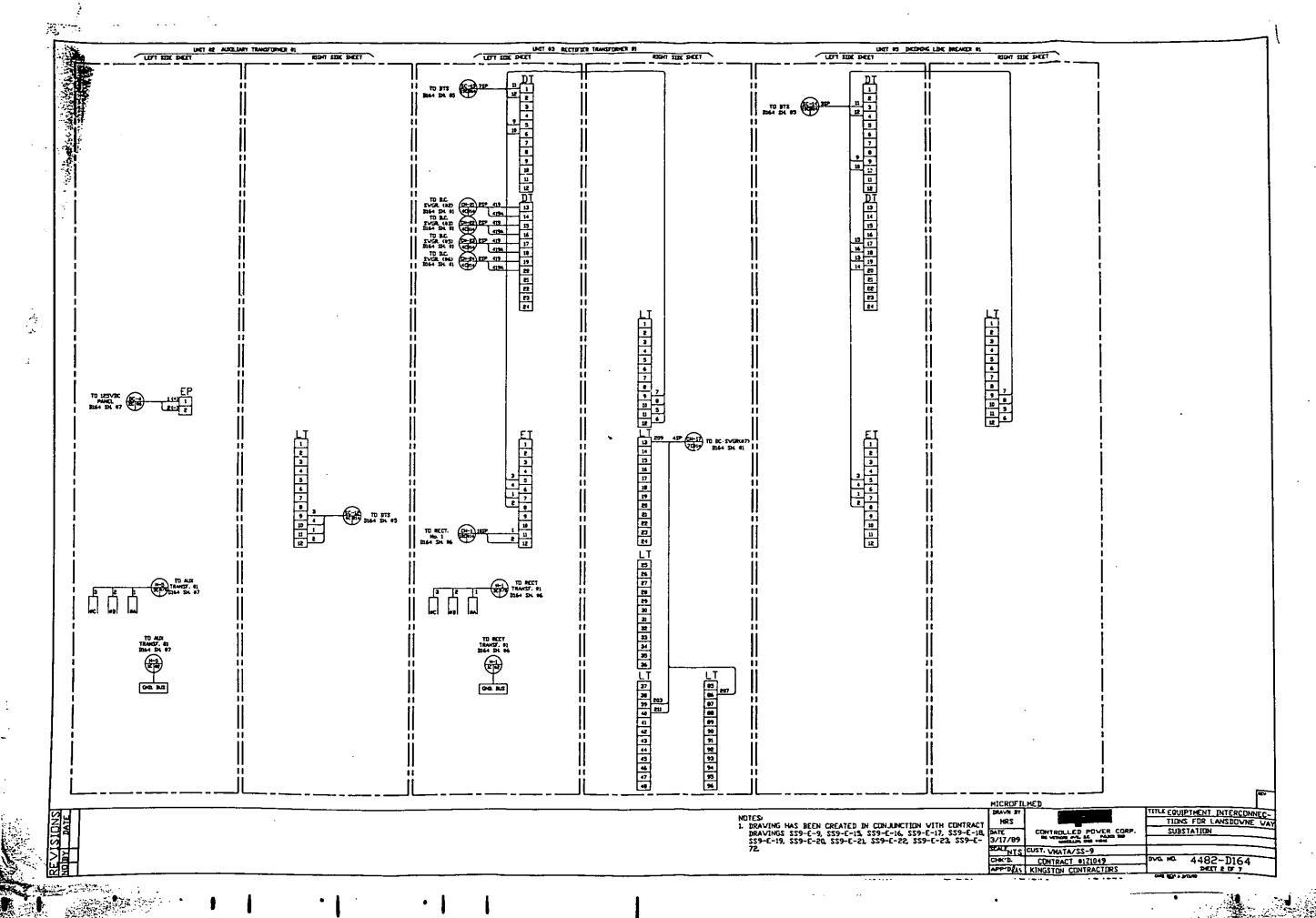




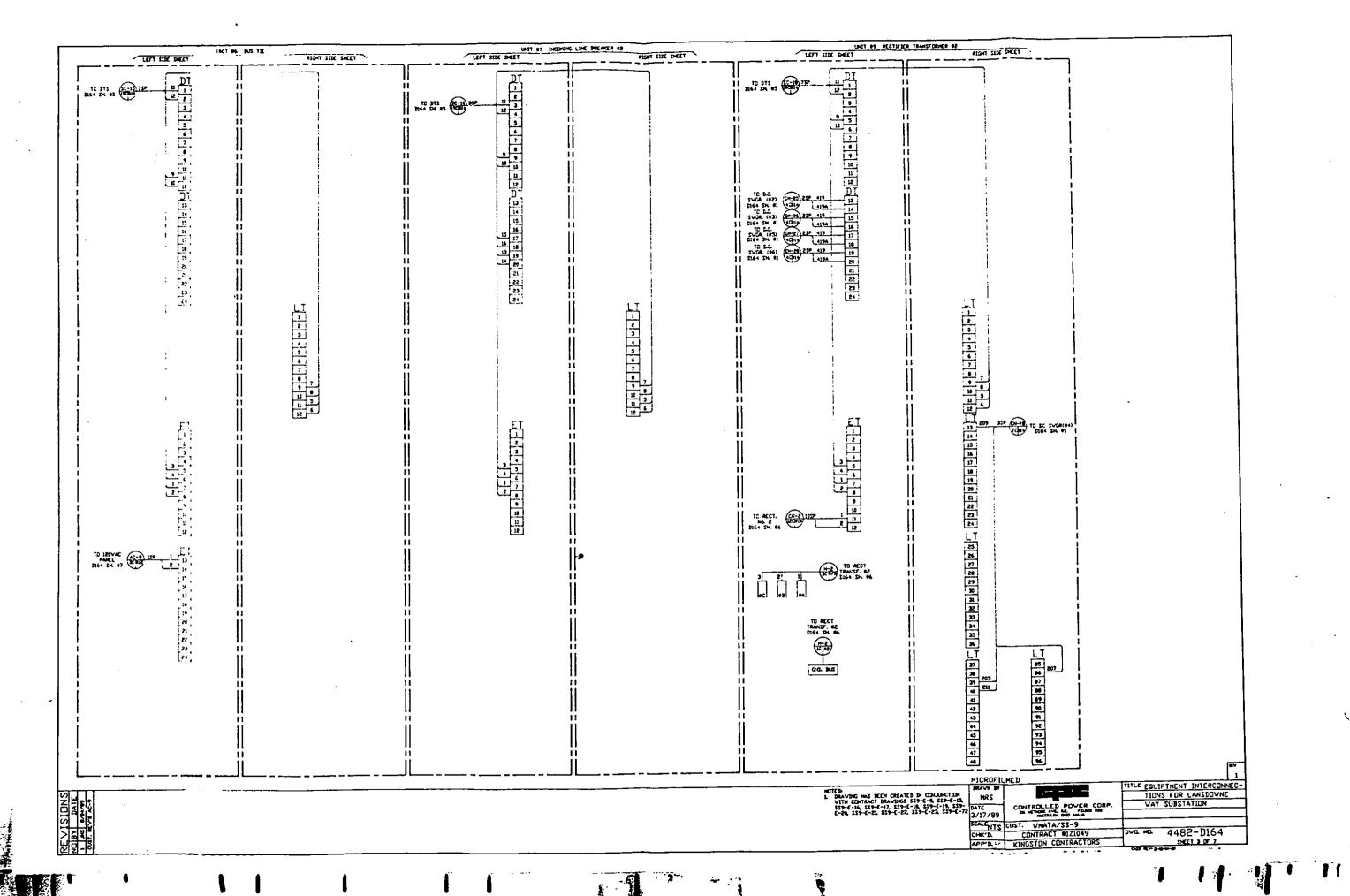
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UNIT CONNECTION DAG	UNIT COMECTON DWG	UNIT CONNECTION DWG	UNIT CONNECTION DWG	INIT CONNECTION EWG	Just connection DWG	•	
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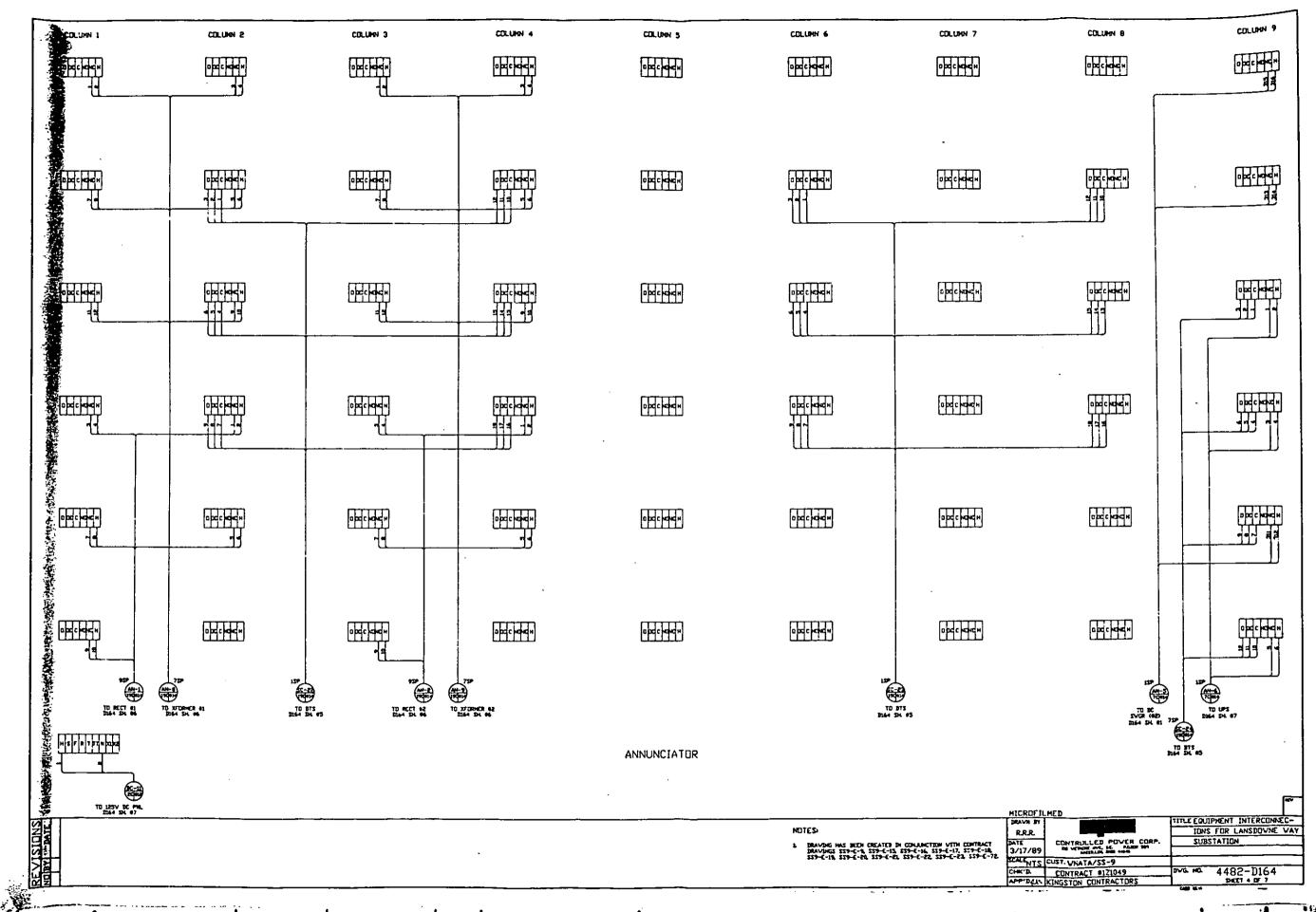


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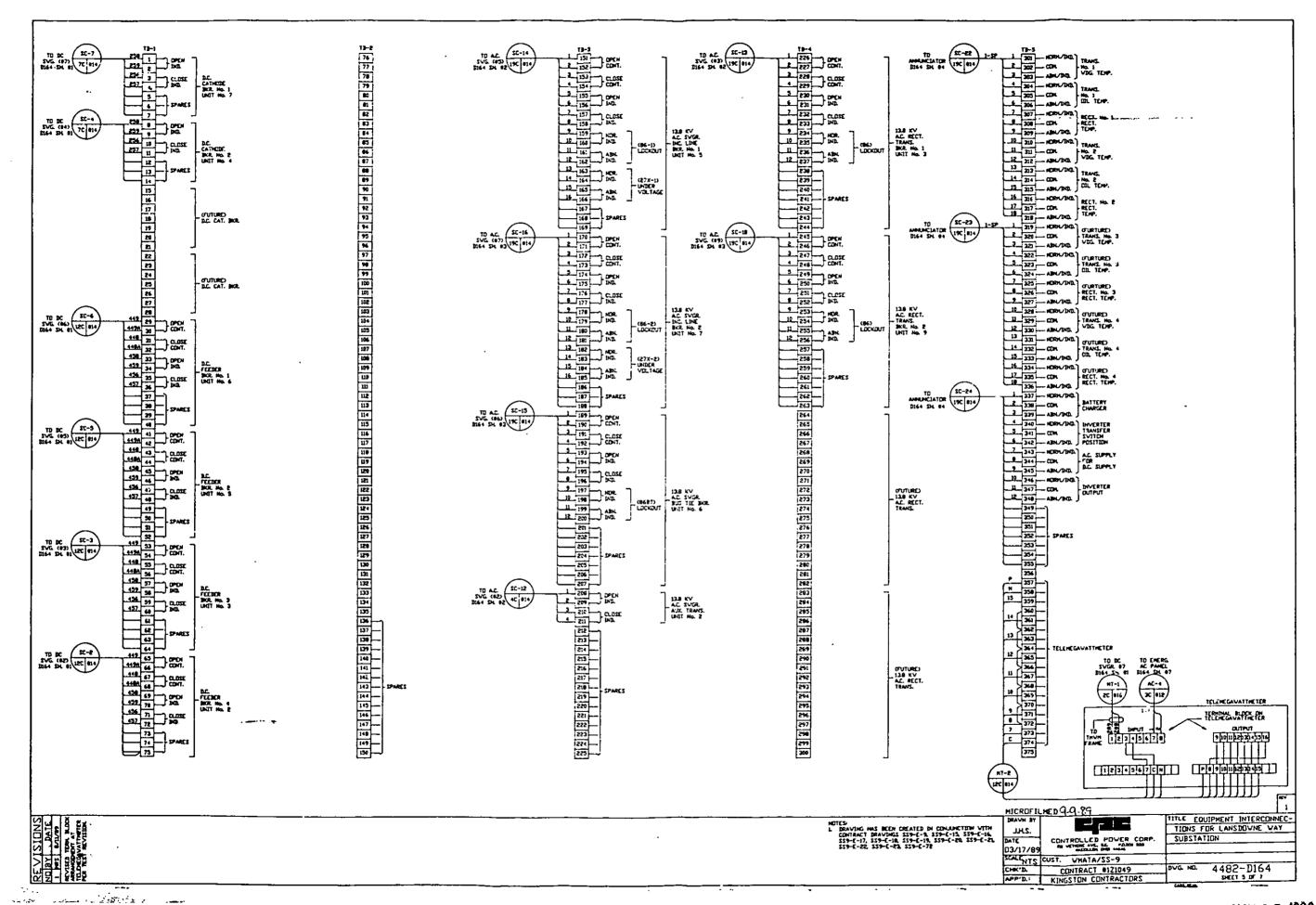


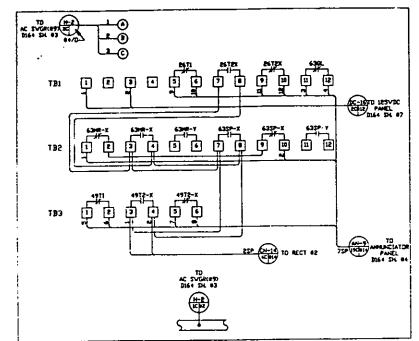


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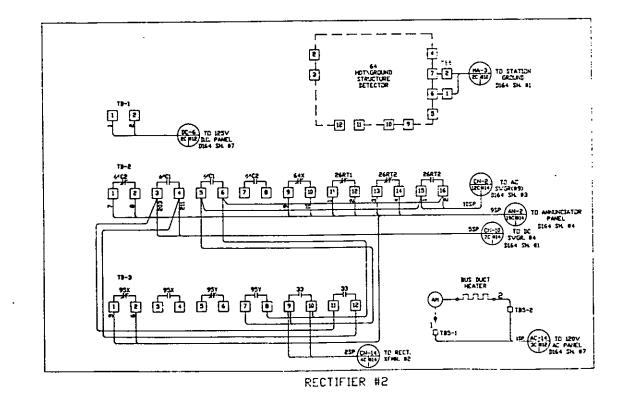
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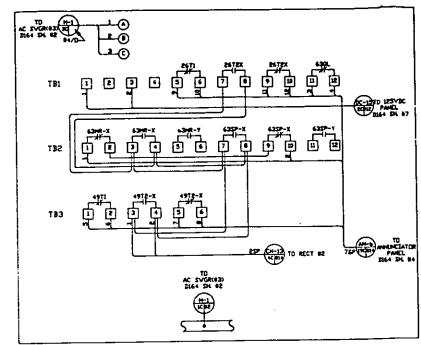
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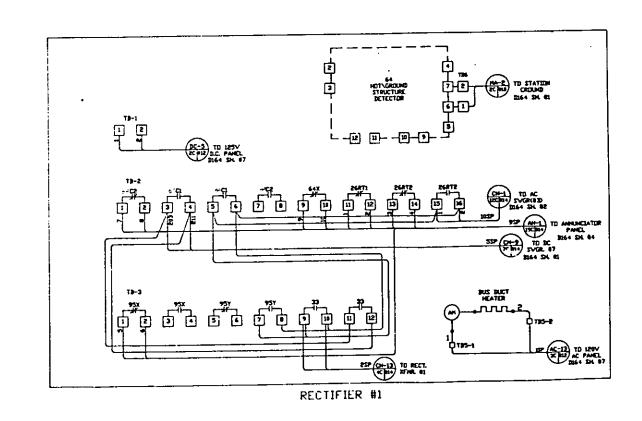


RECTIFIER TRANSFORMER #2





RECTIFIER TRANSFORMER #1

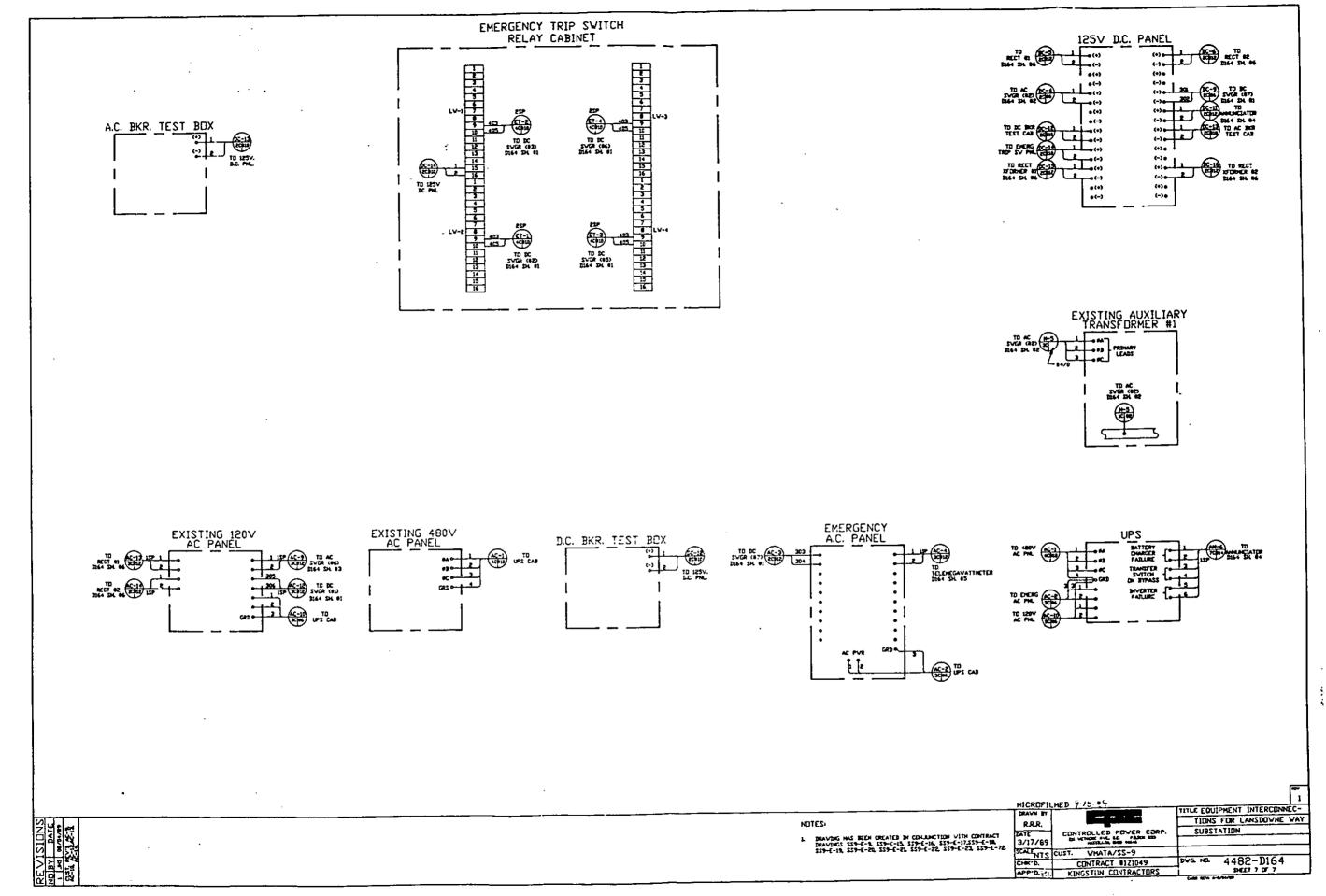


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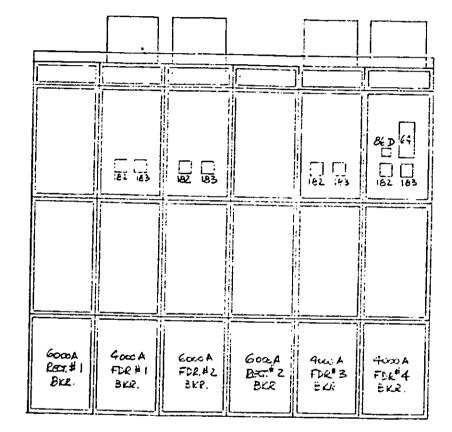
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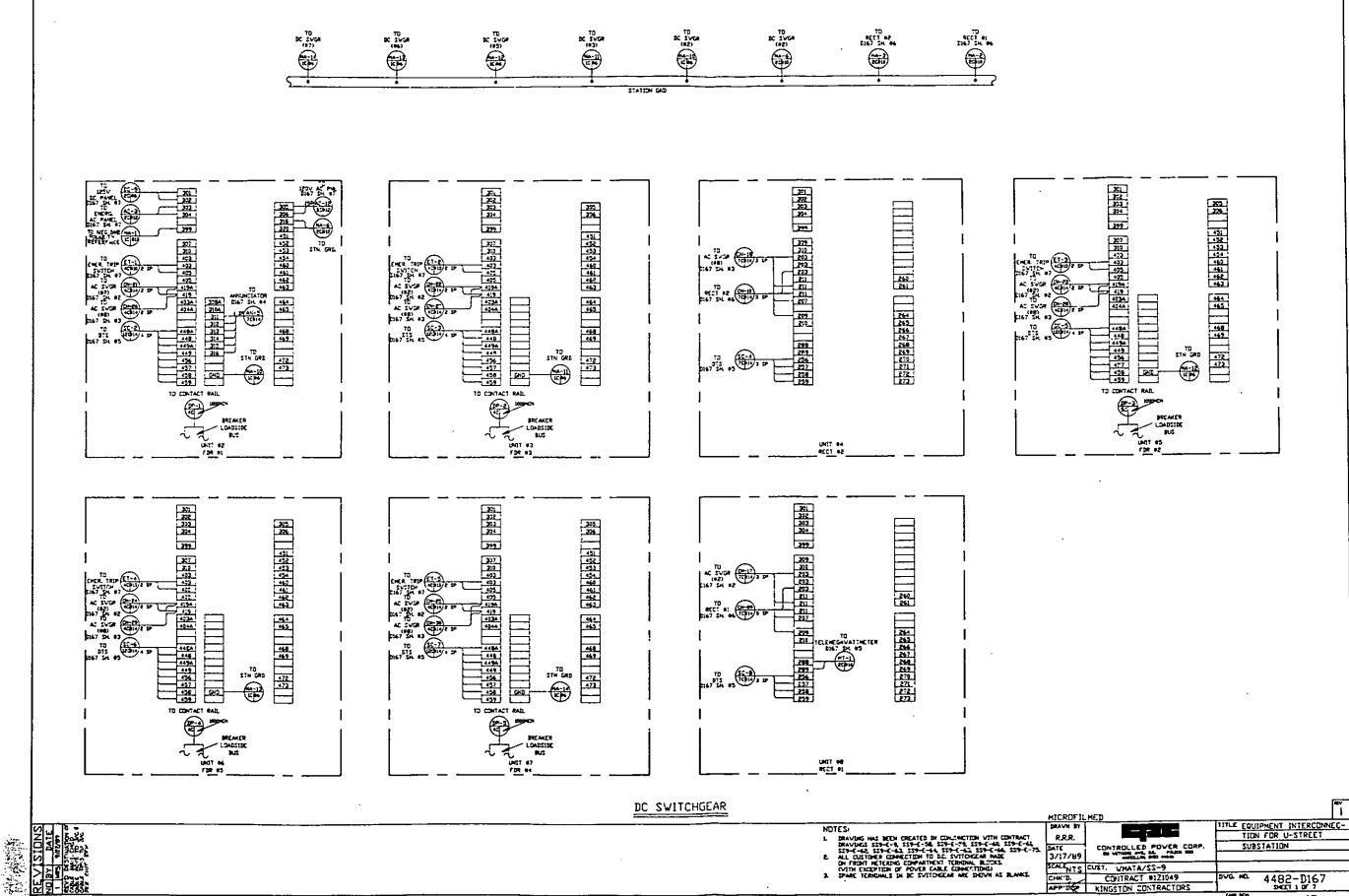


REAR VIEW

FOR BLEVATION & SECTION VIEW
SEE DWG Nº 4482-D 12

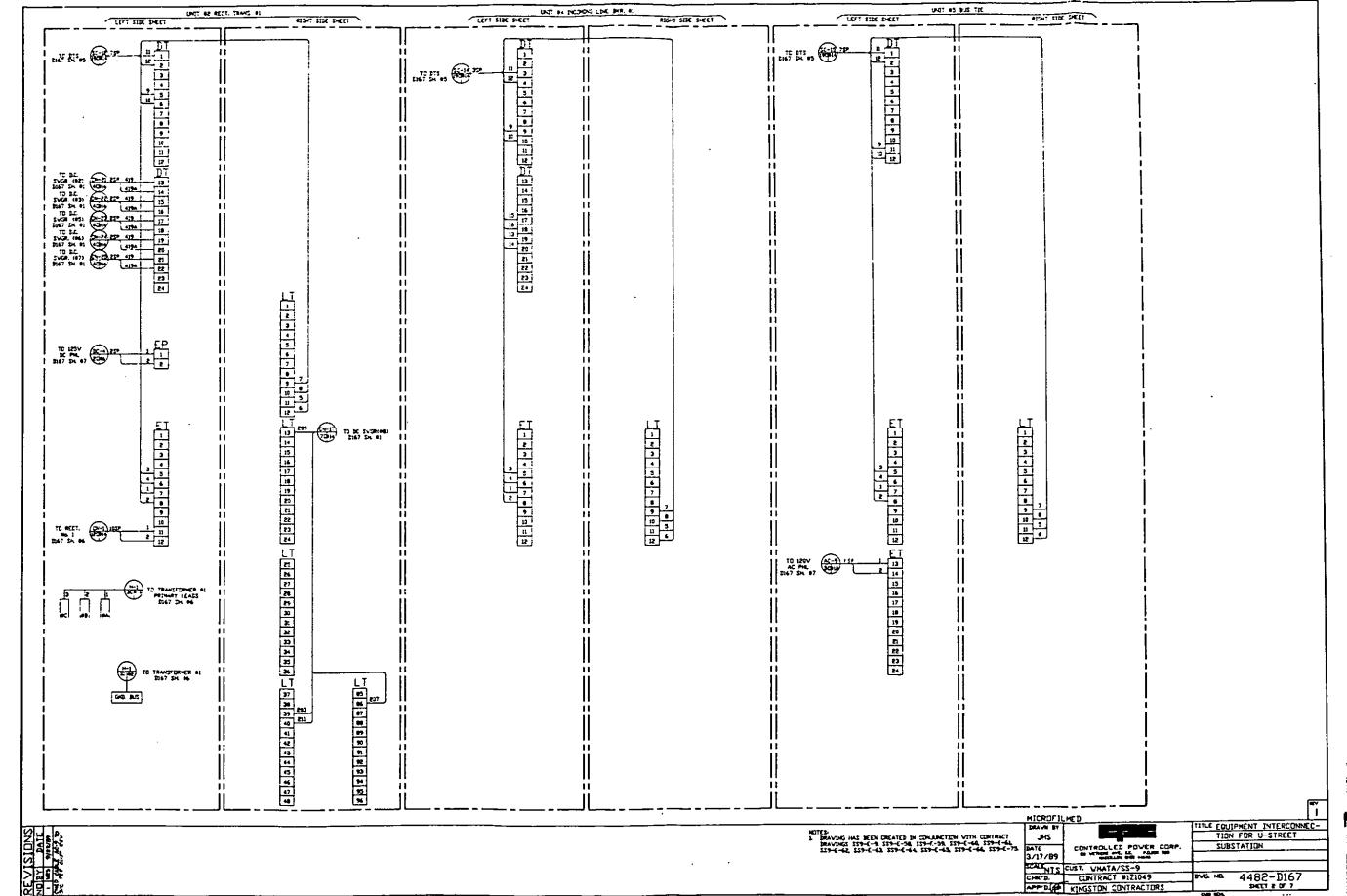
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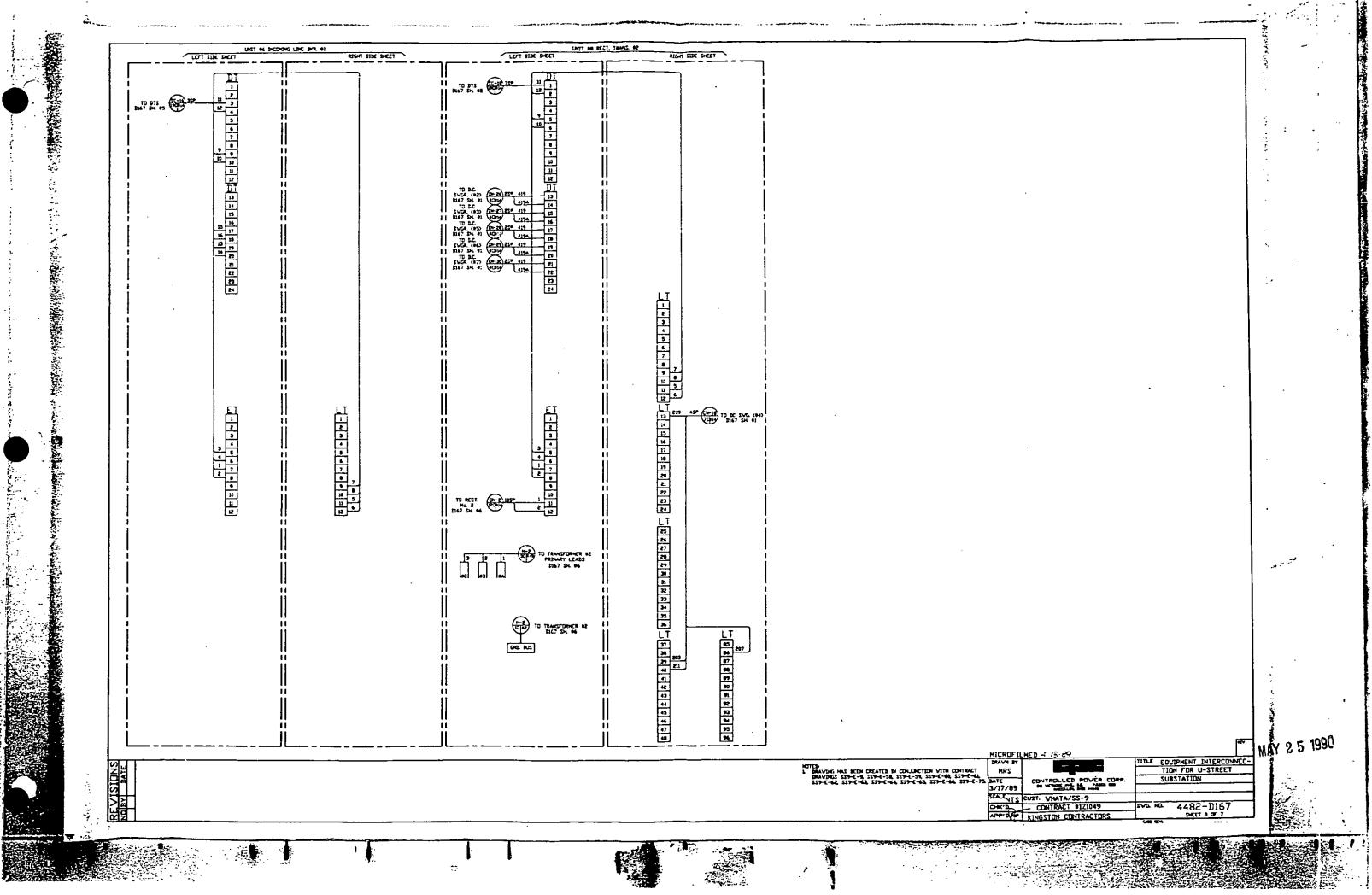
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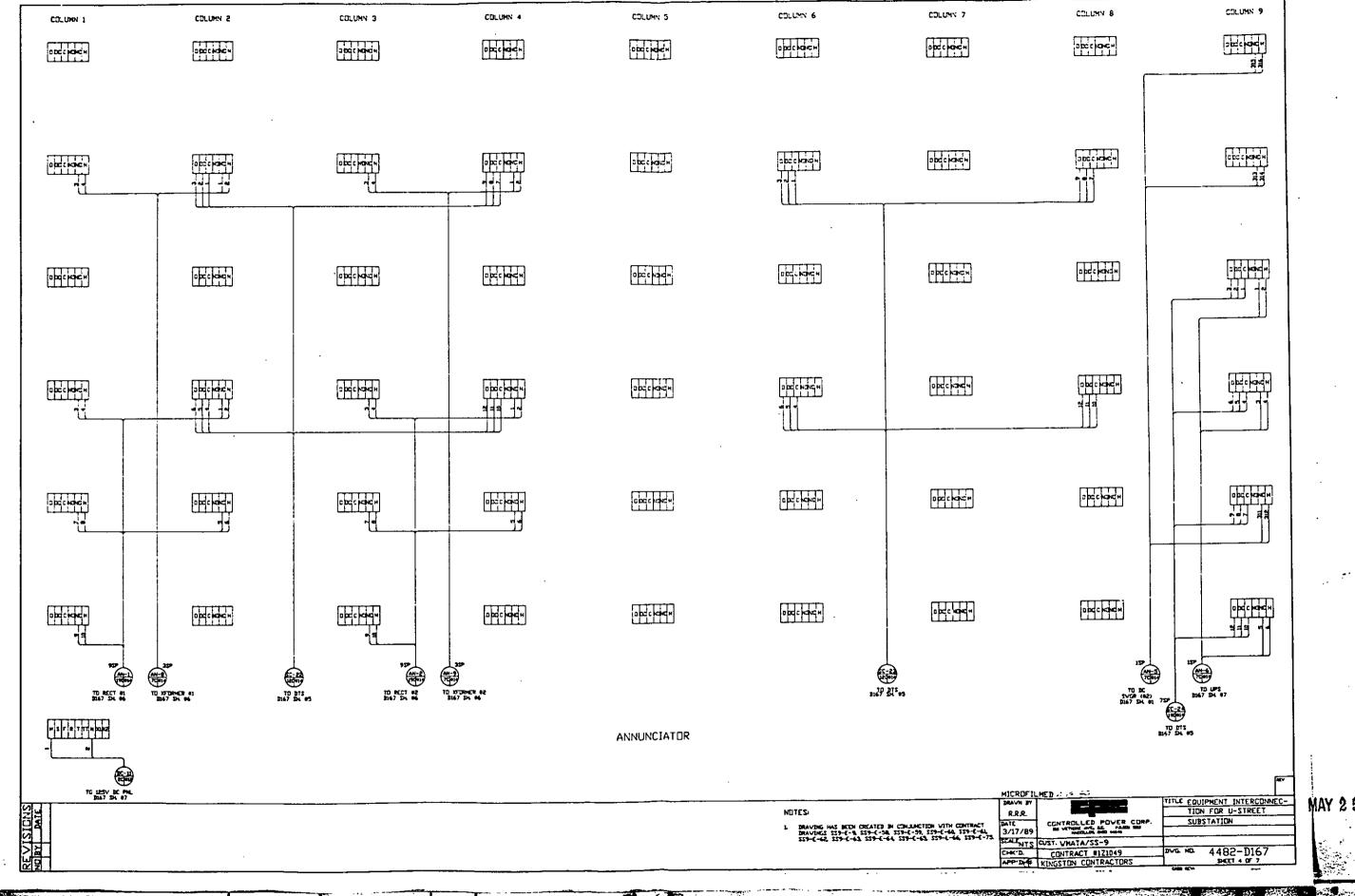
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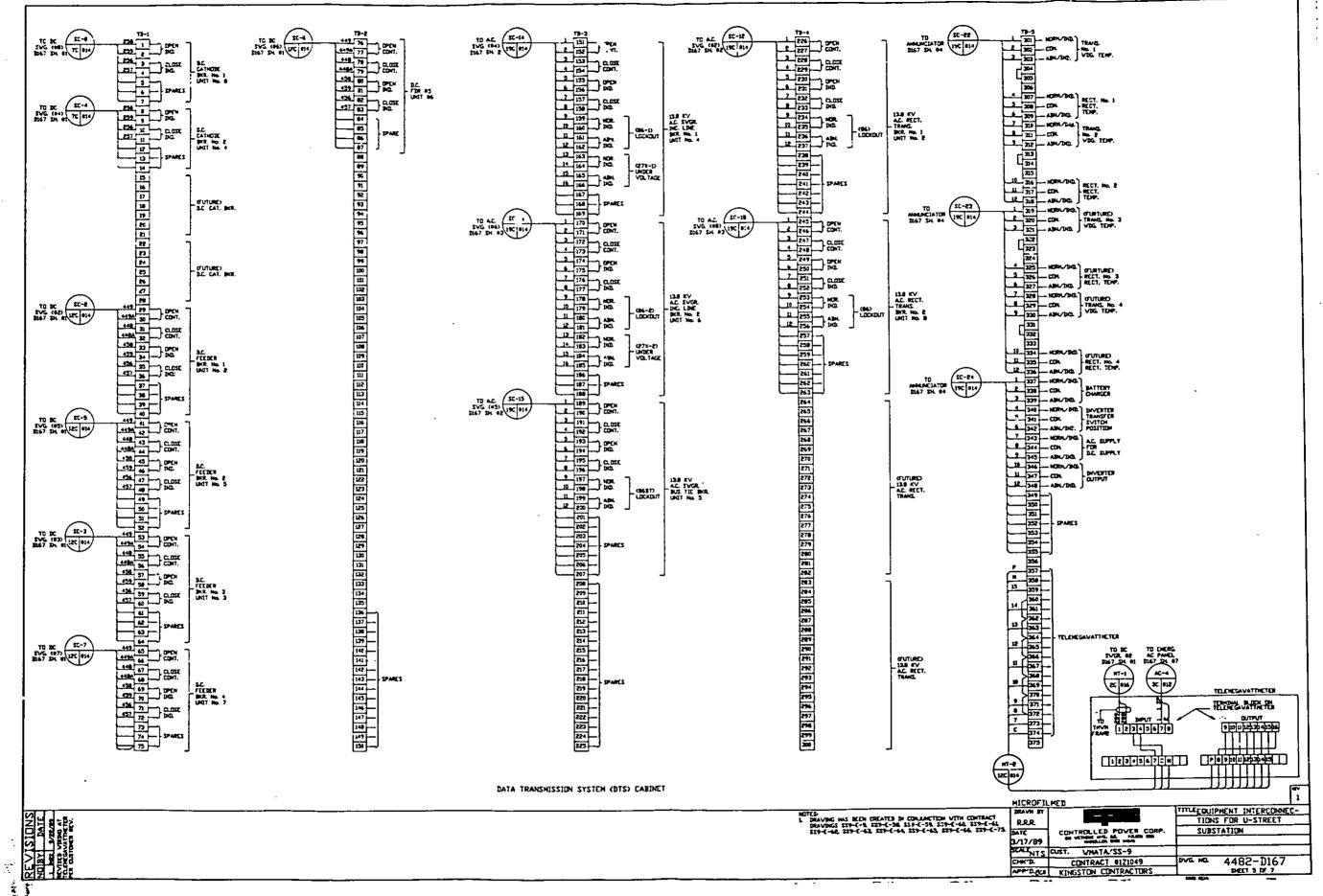


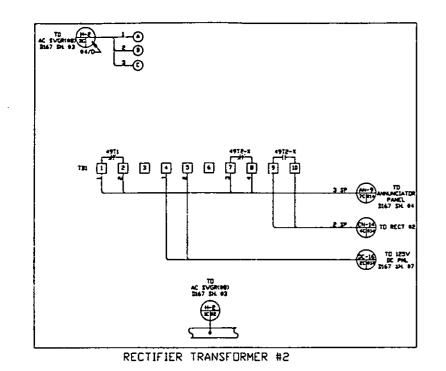
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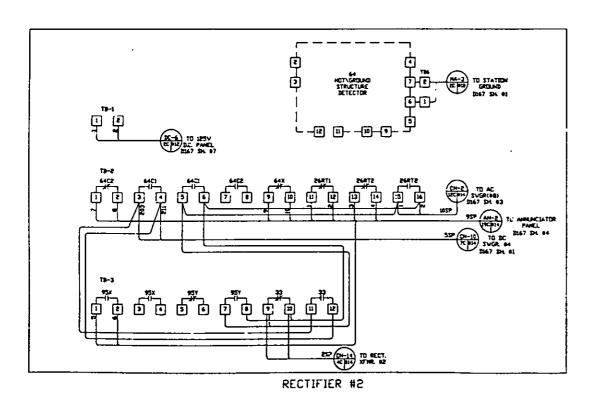
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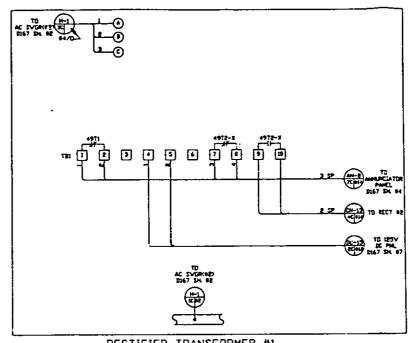




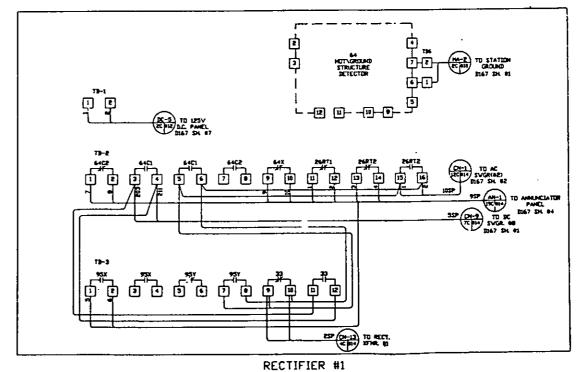




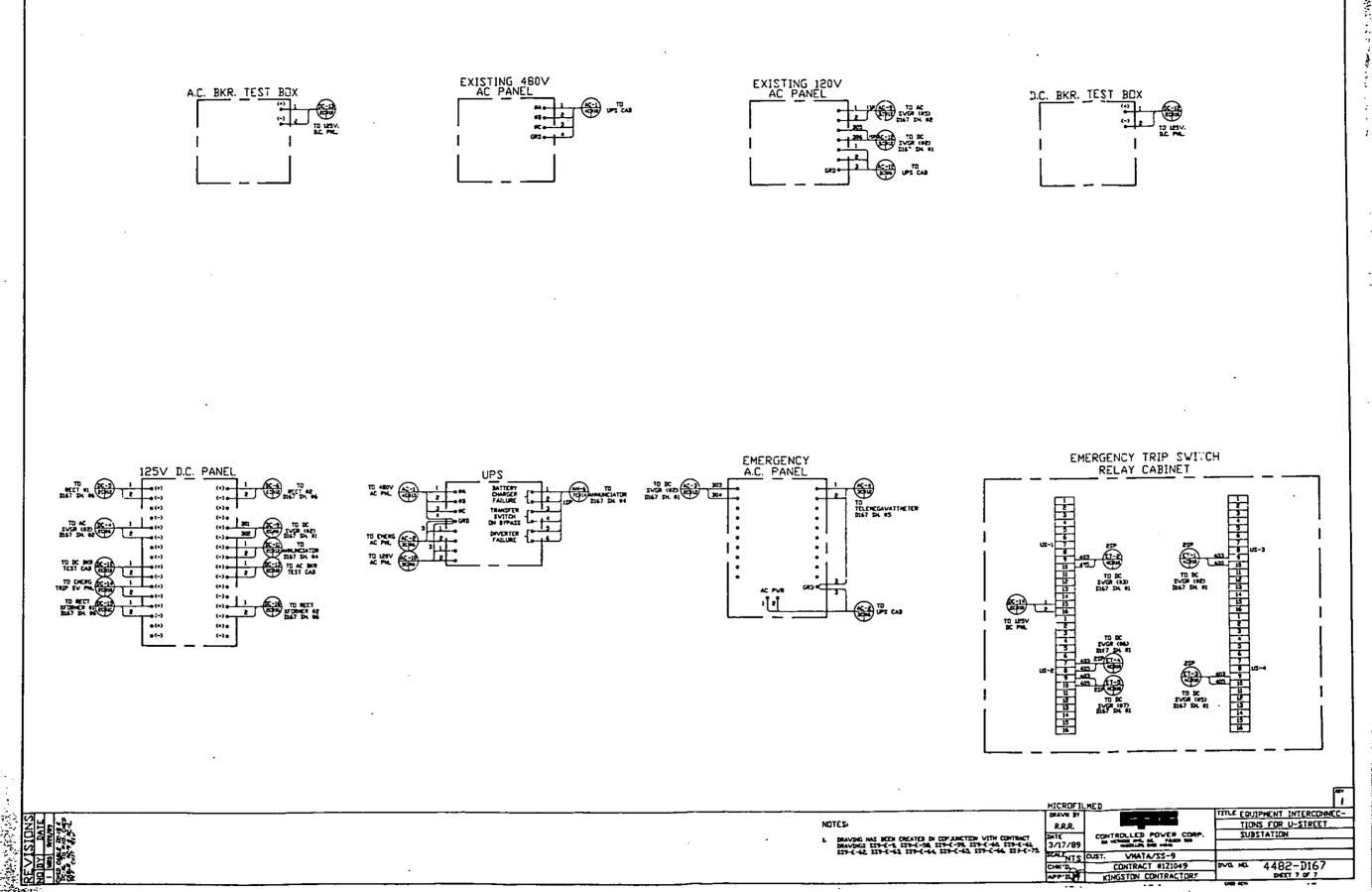




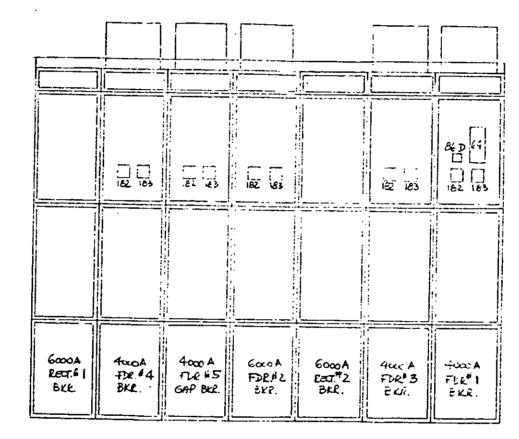
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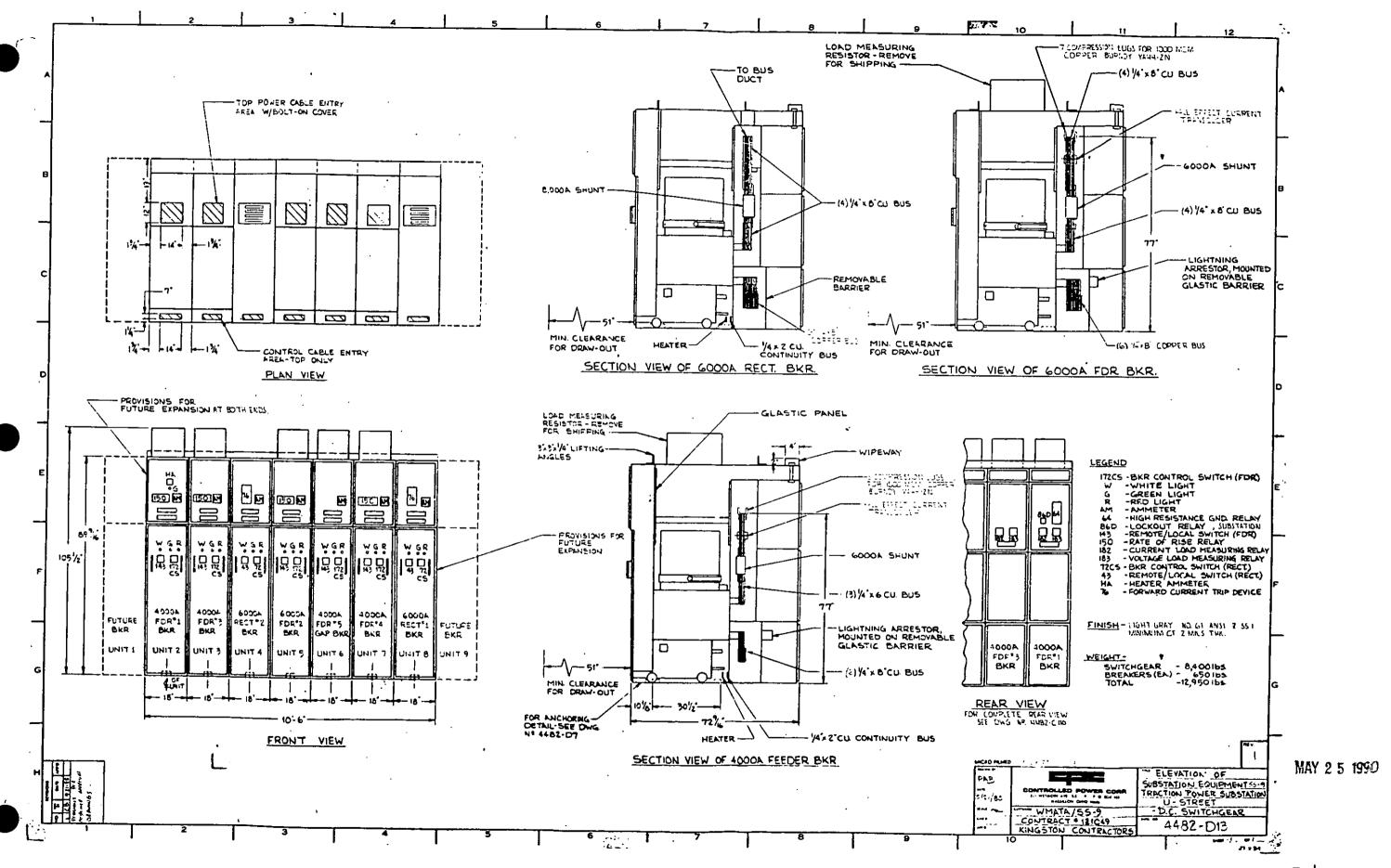
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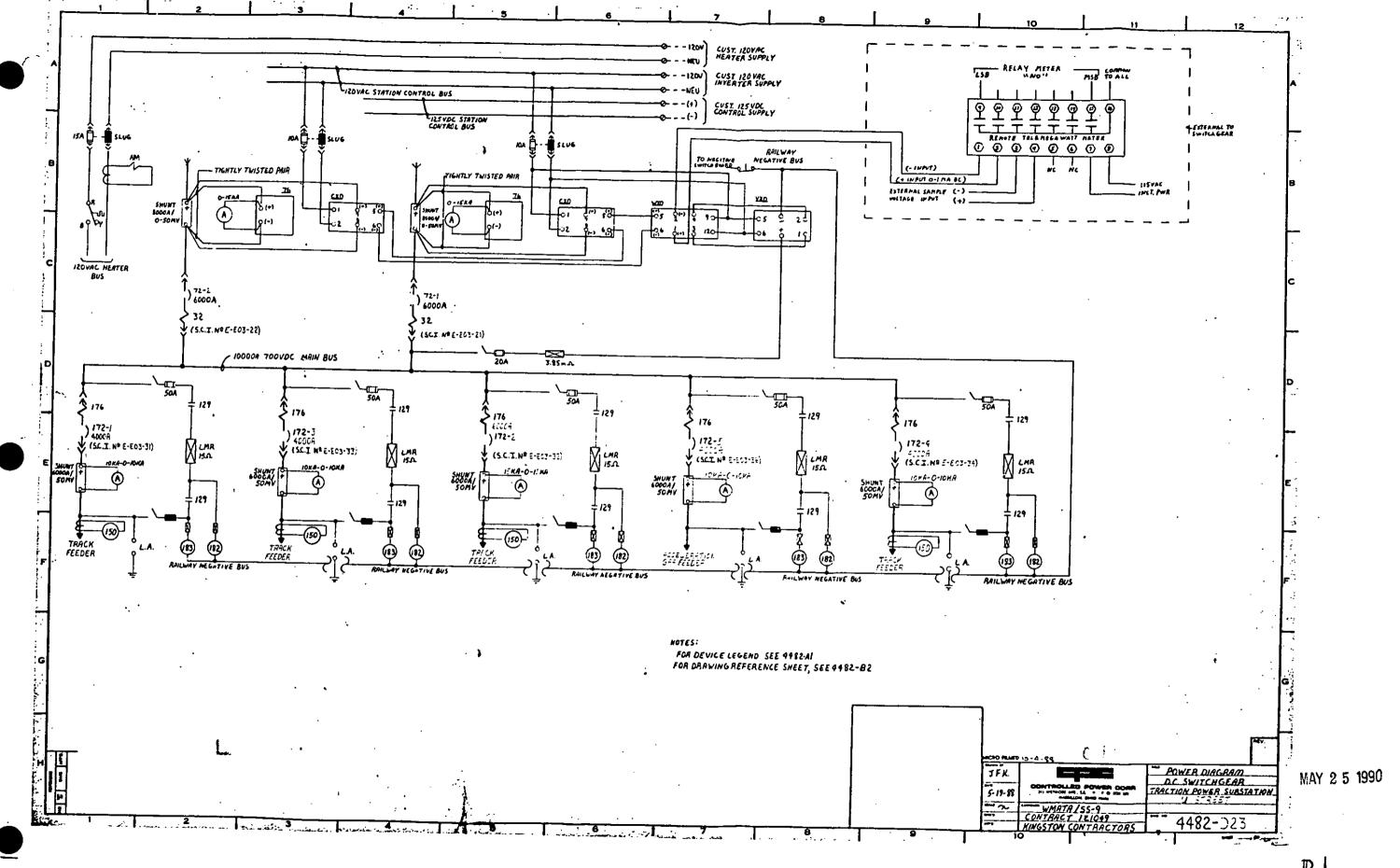
REAR VIEW

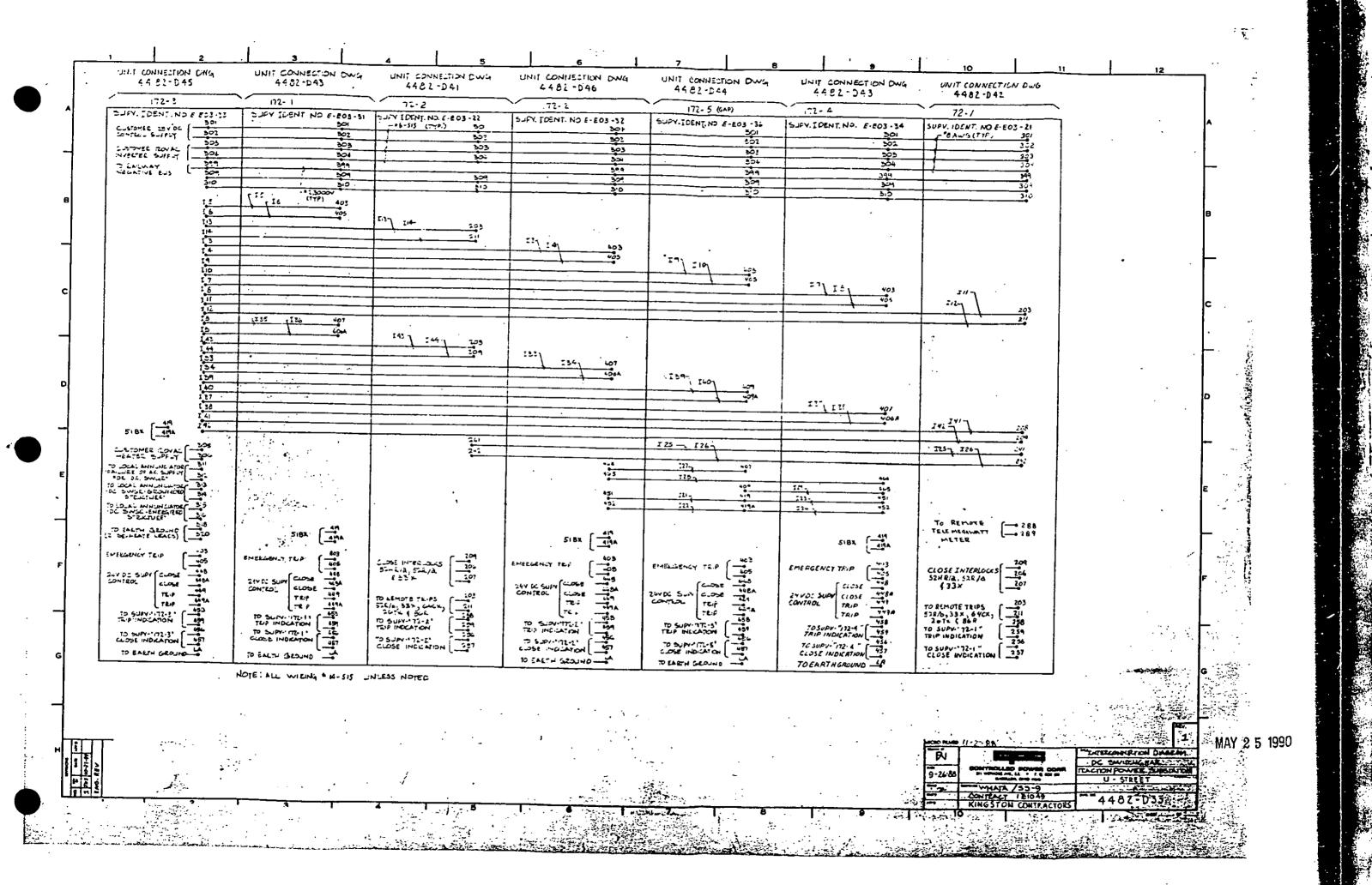
FOR ELEVATION & SECTION VIEW
SEE JUG. Nº 4482-13

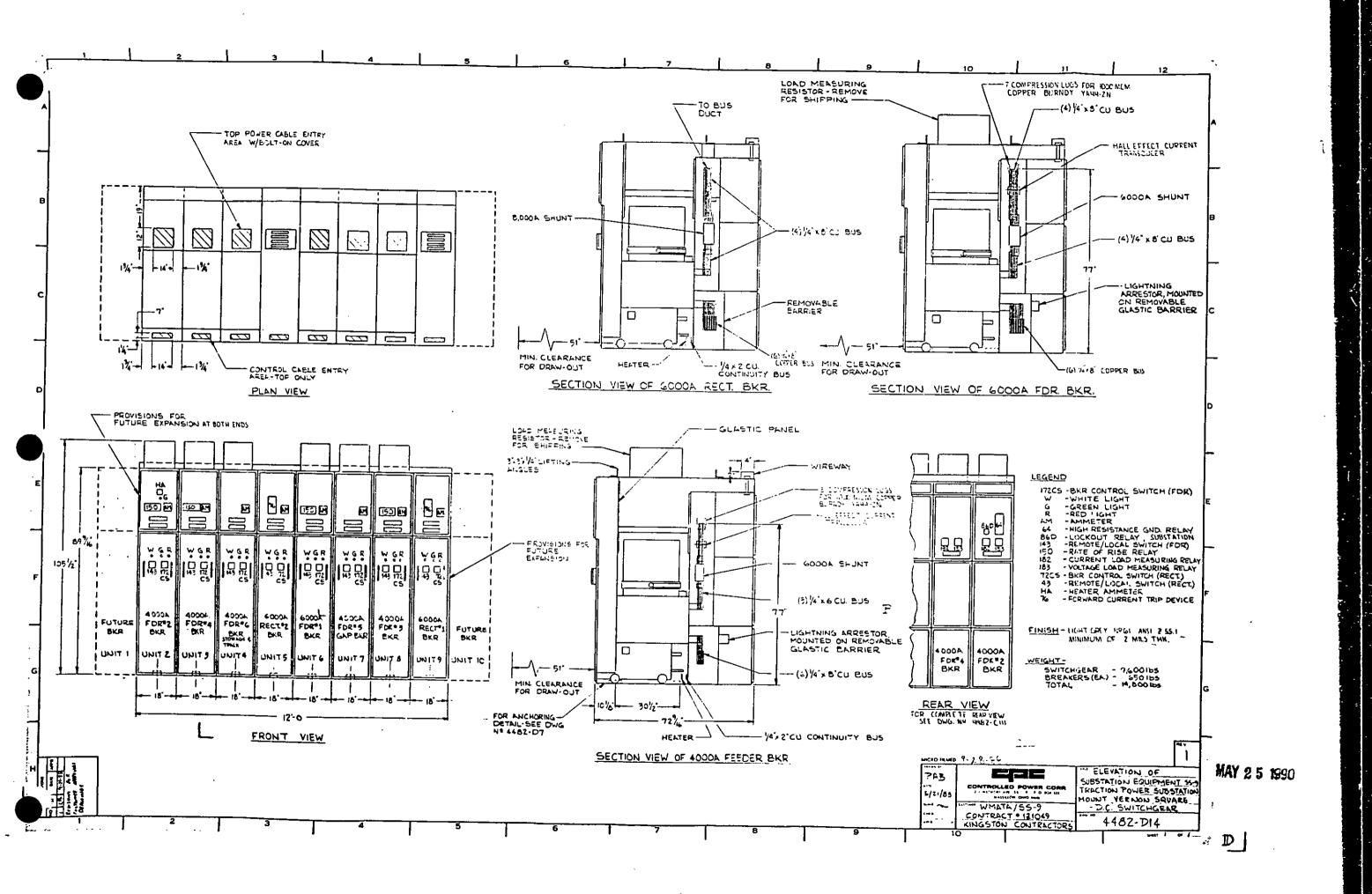
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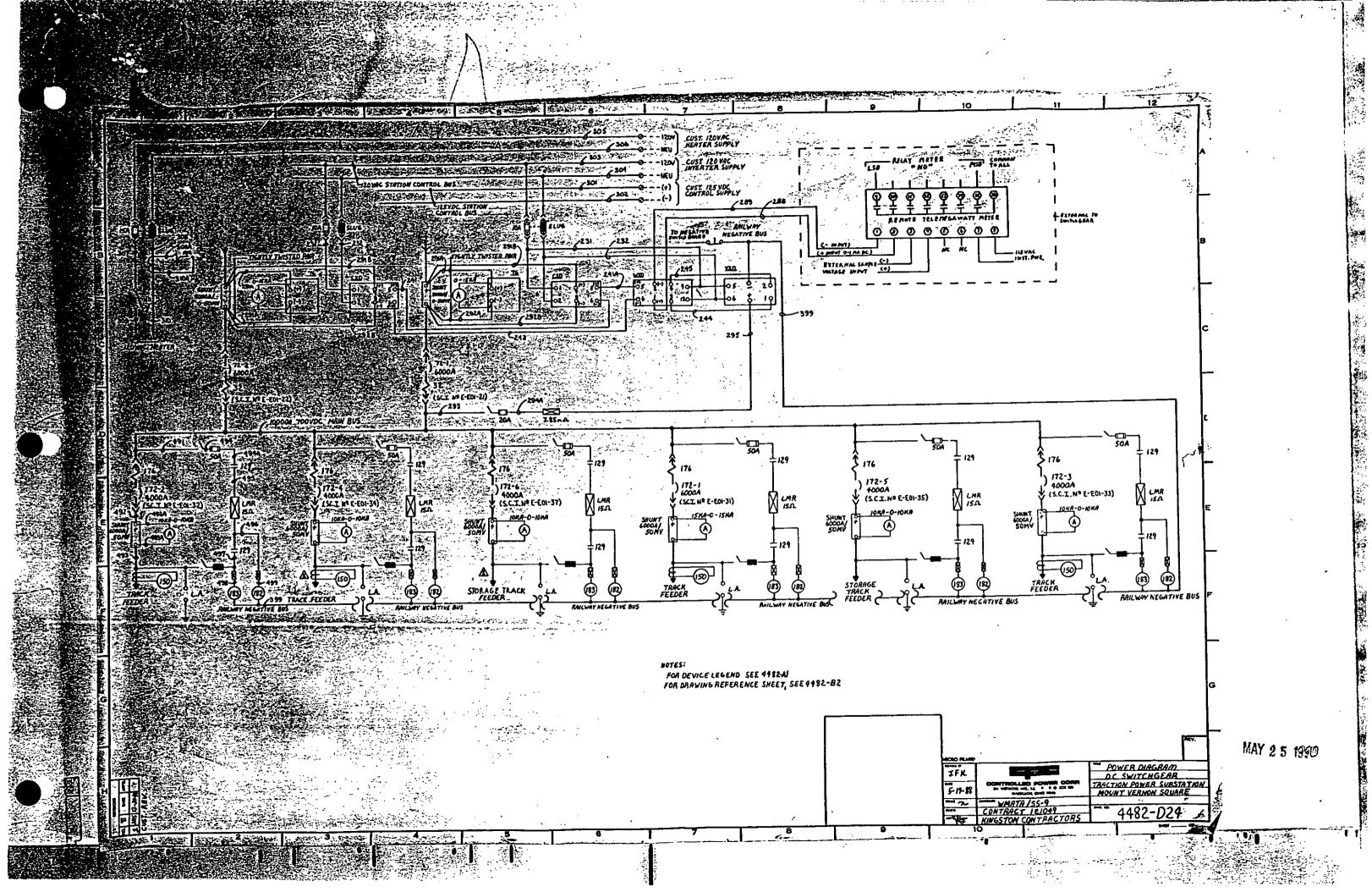


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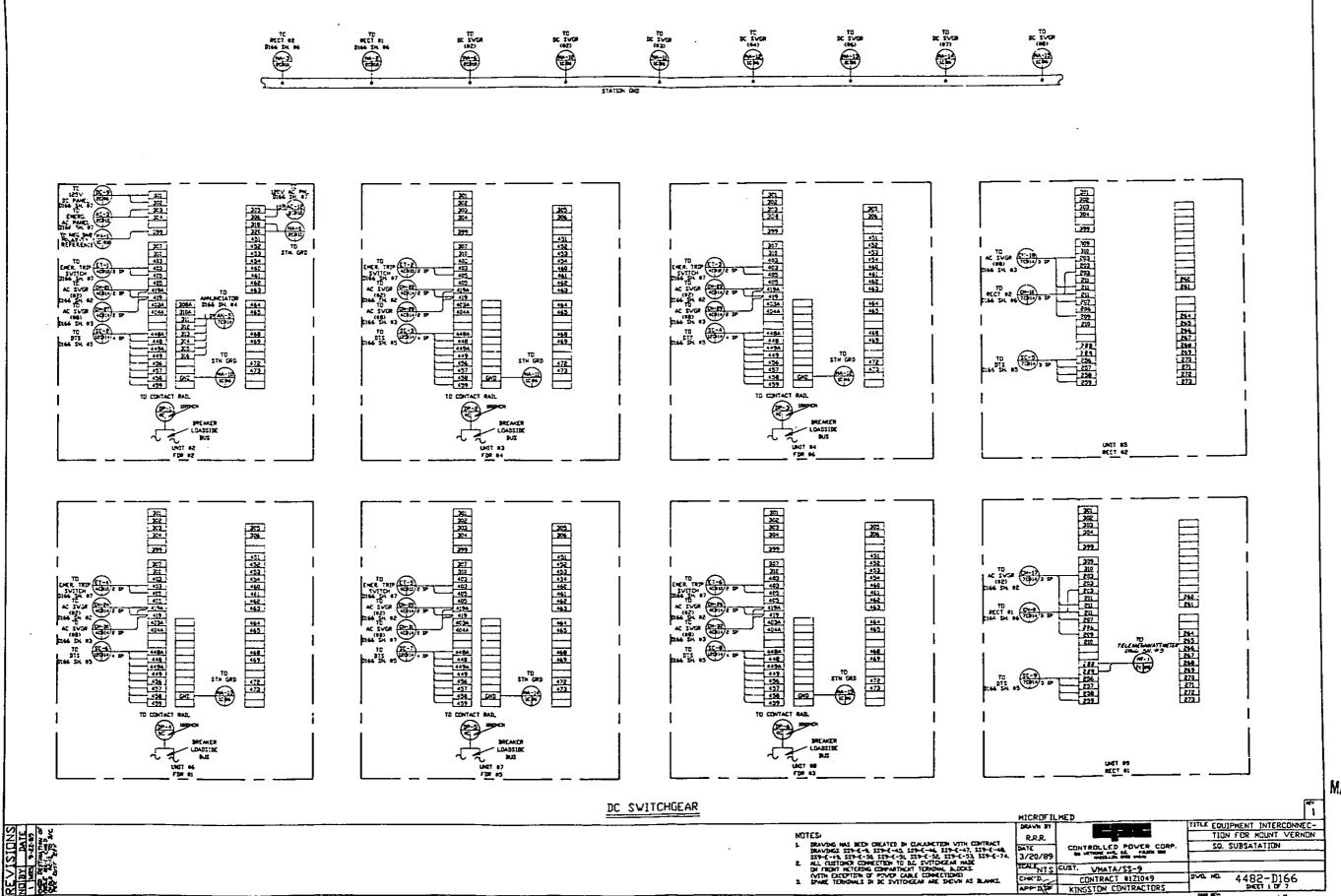
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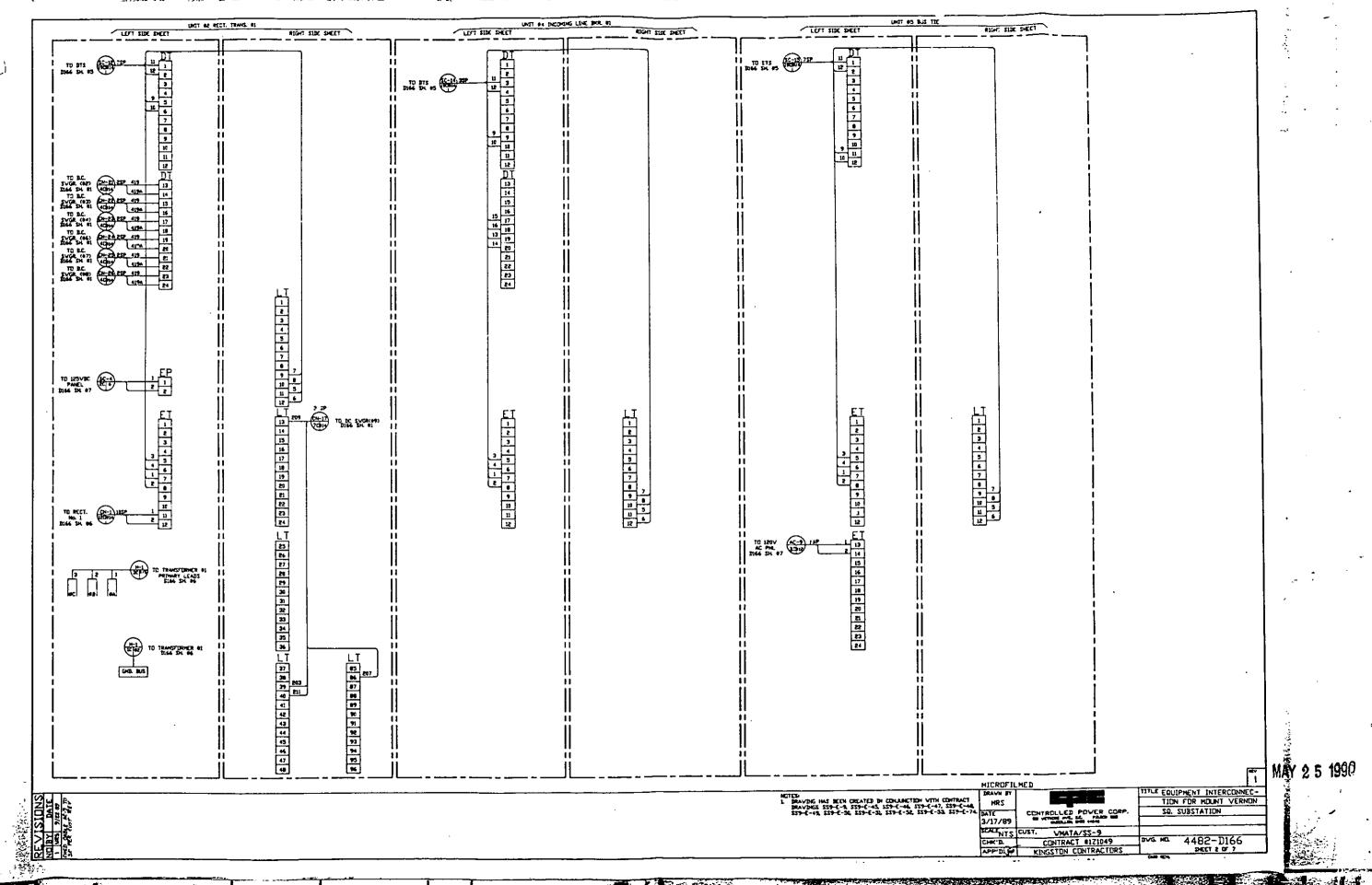


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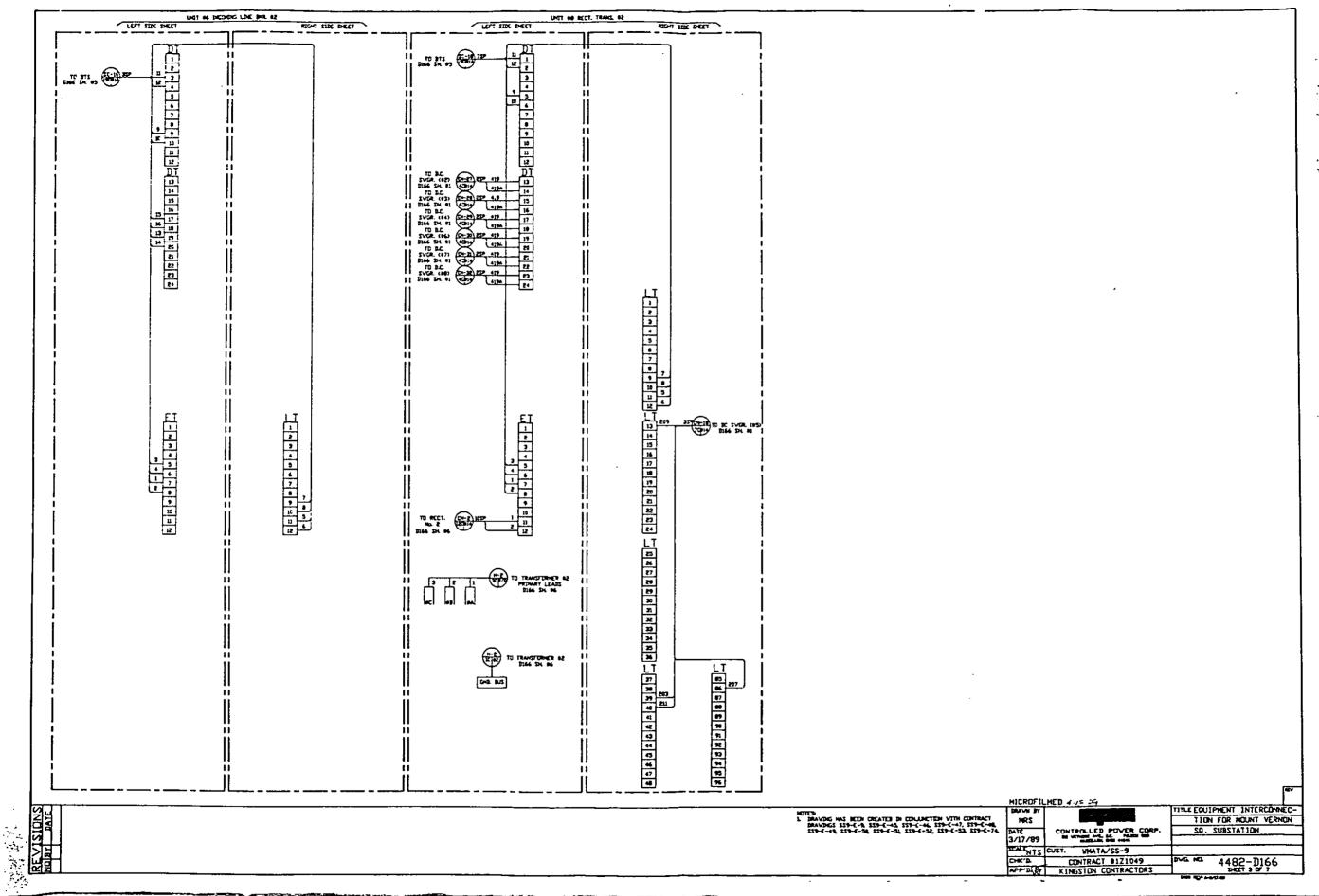
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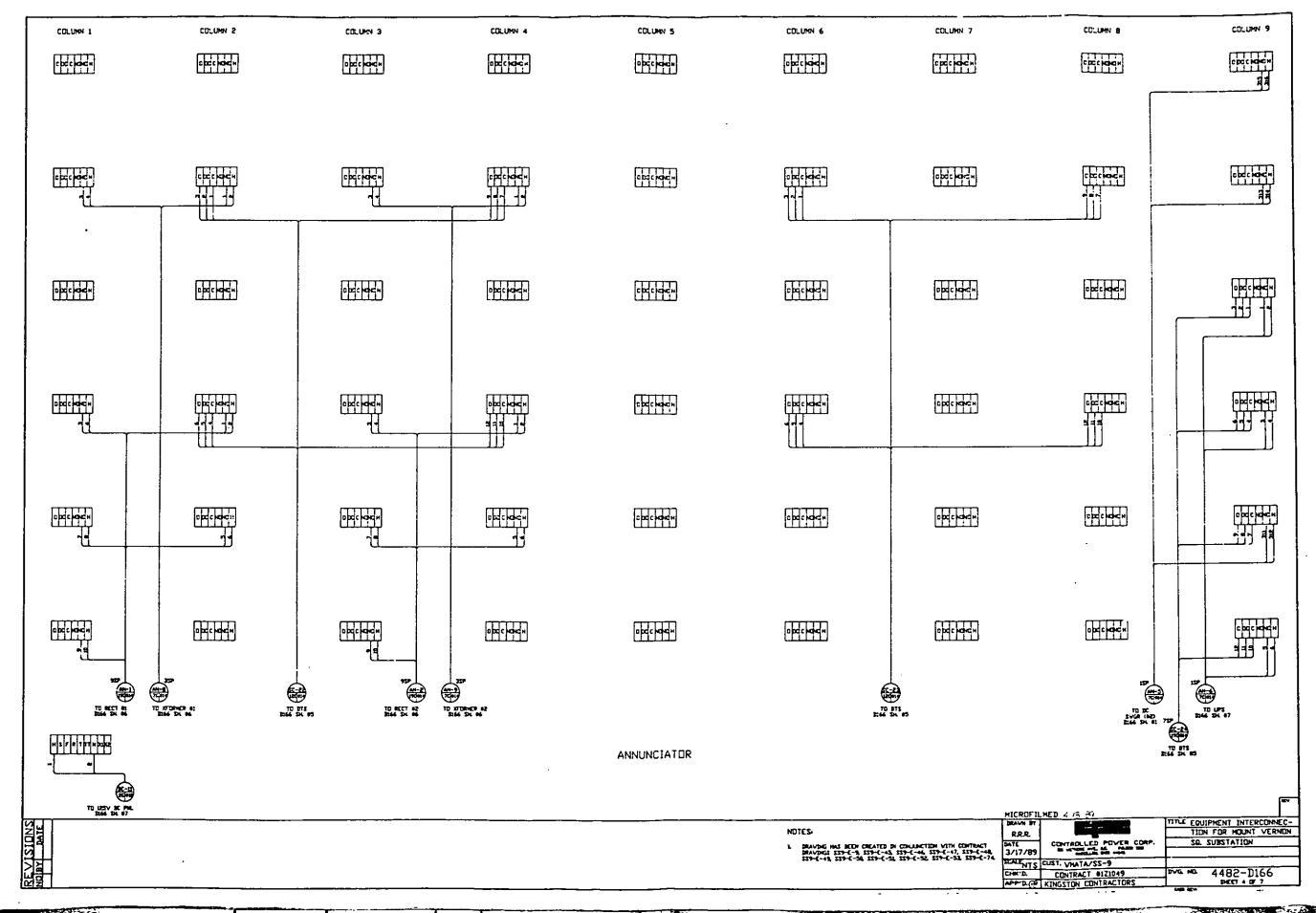
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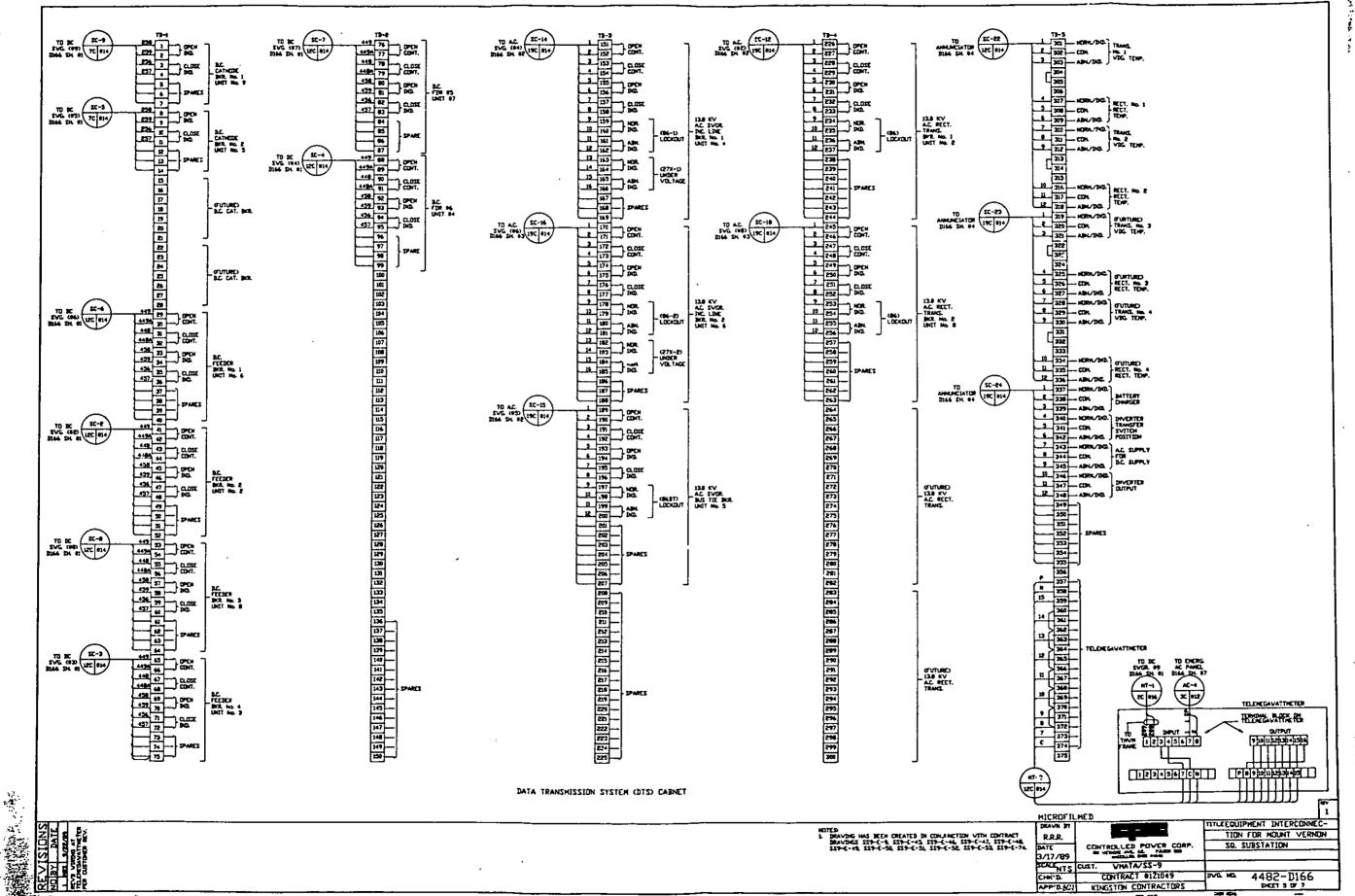
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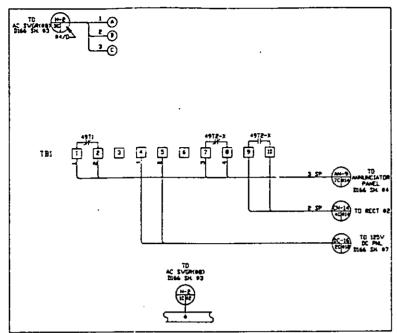




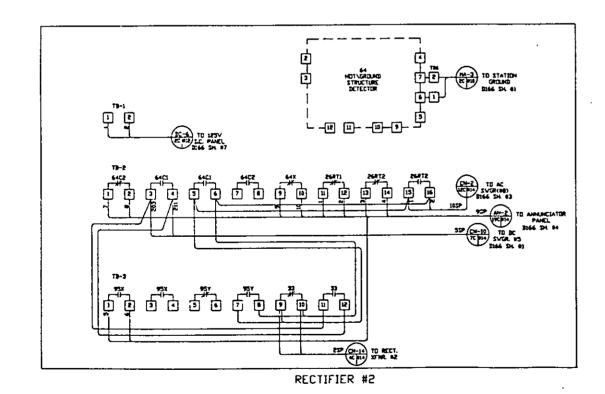
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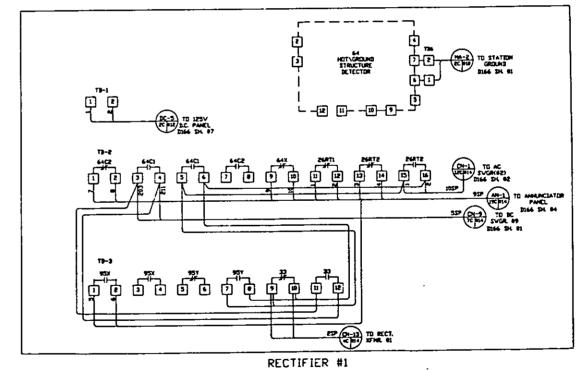
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RECTIFIER TRANSFORMER #2

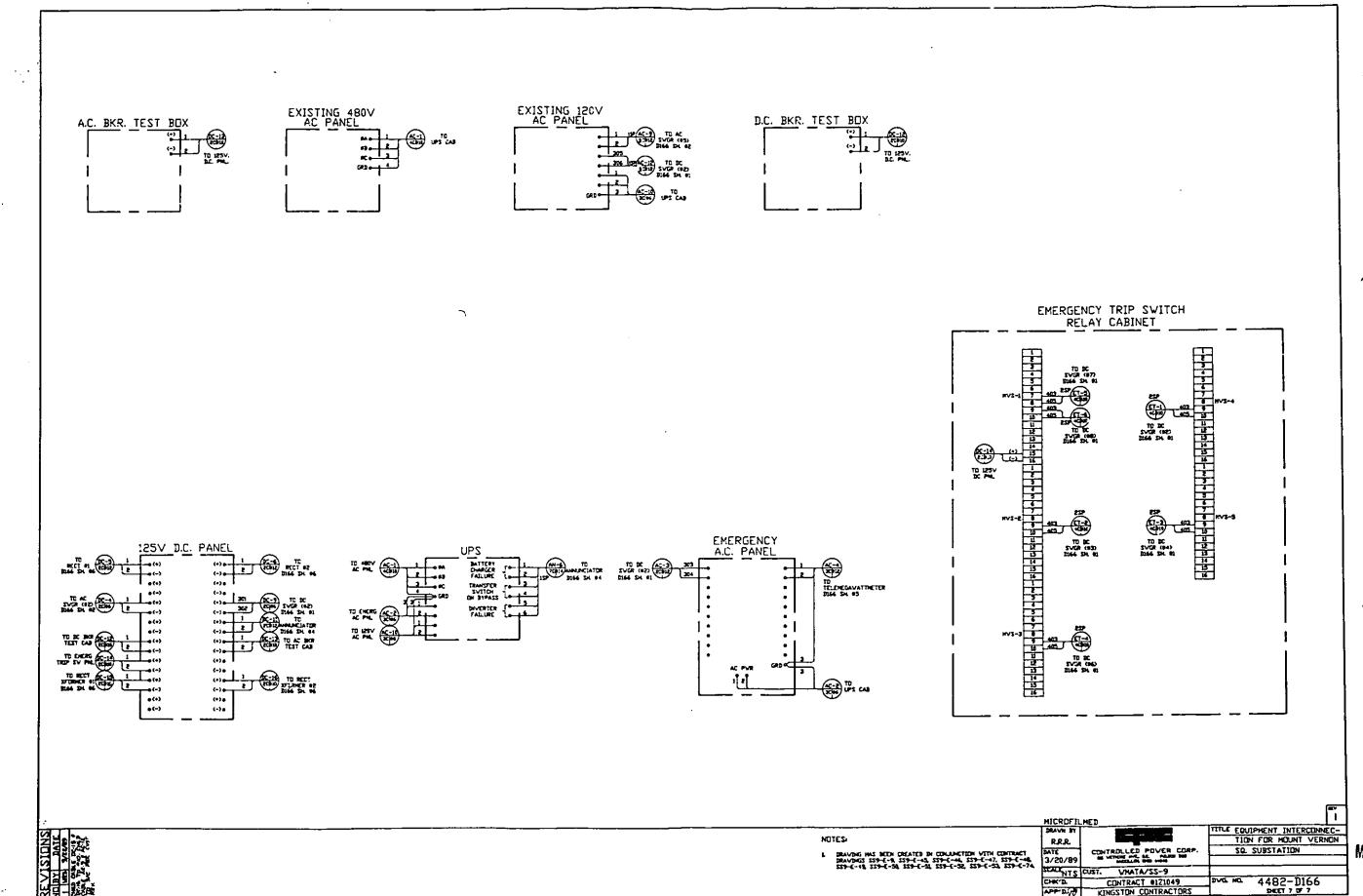


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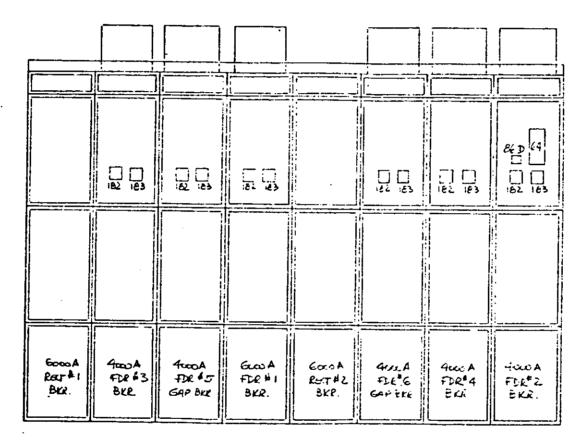
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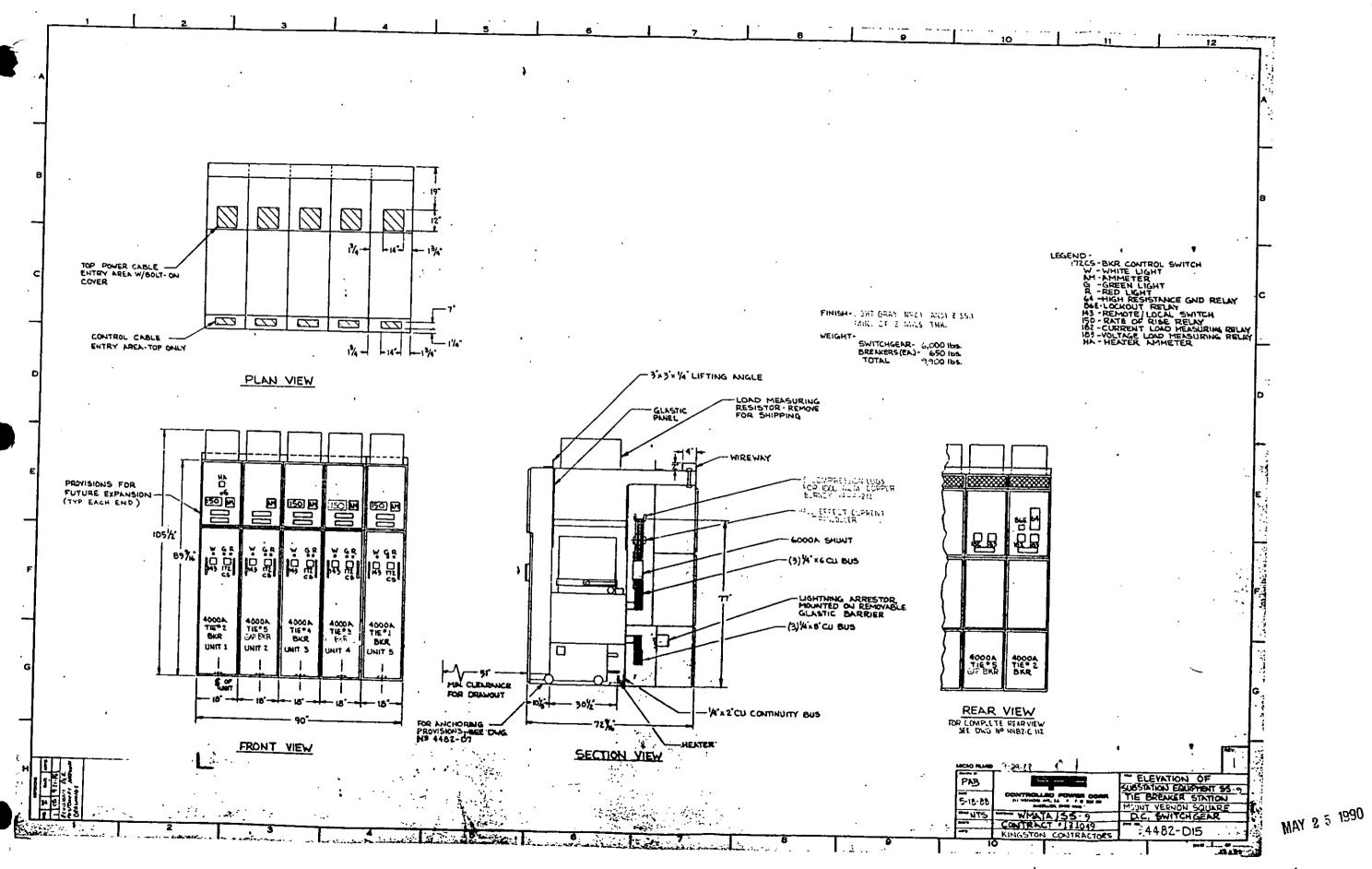


REAR VIEW

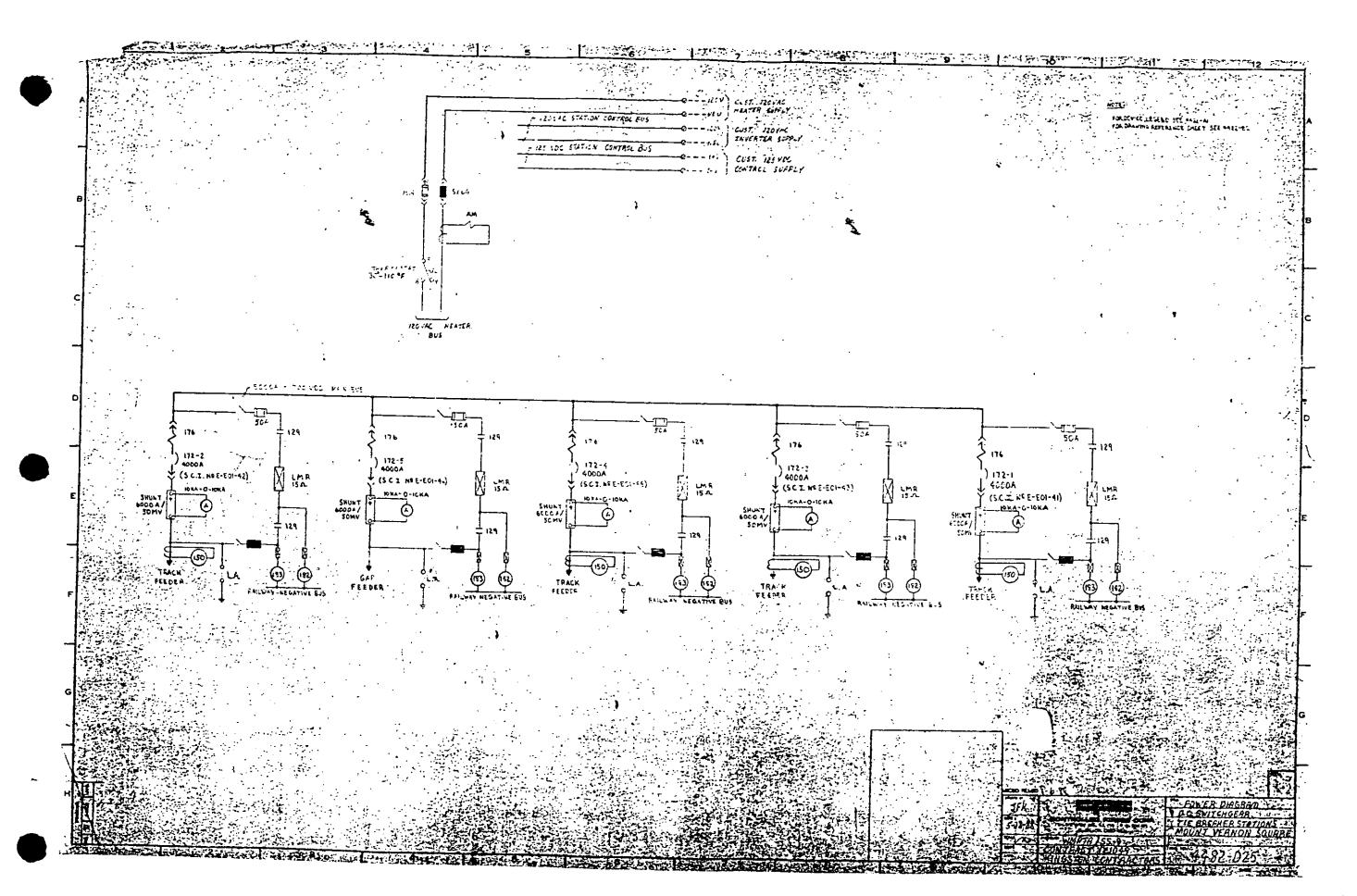
FOR ELEVATION & SECTION VIEW SEE JWG. Nº 4482-D14

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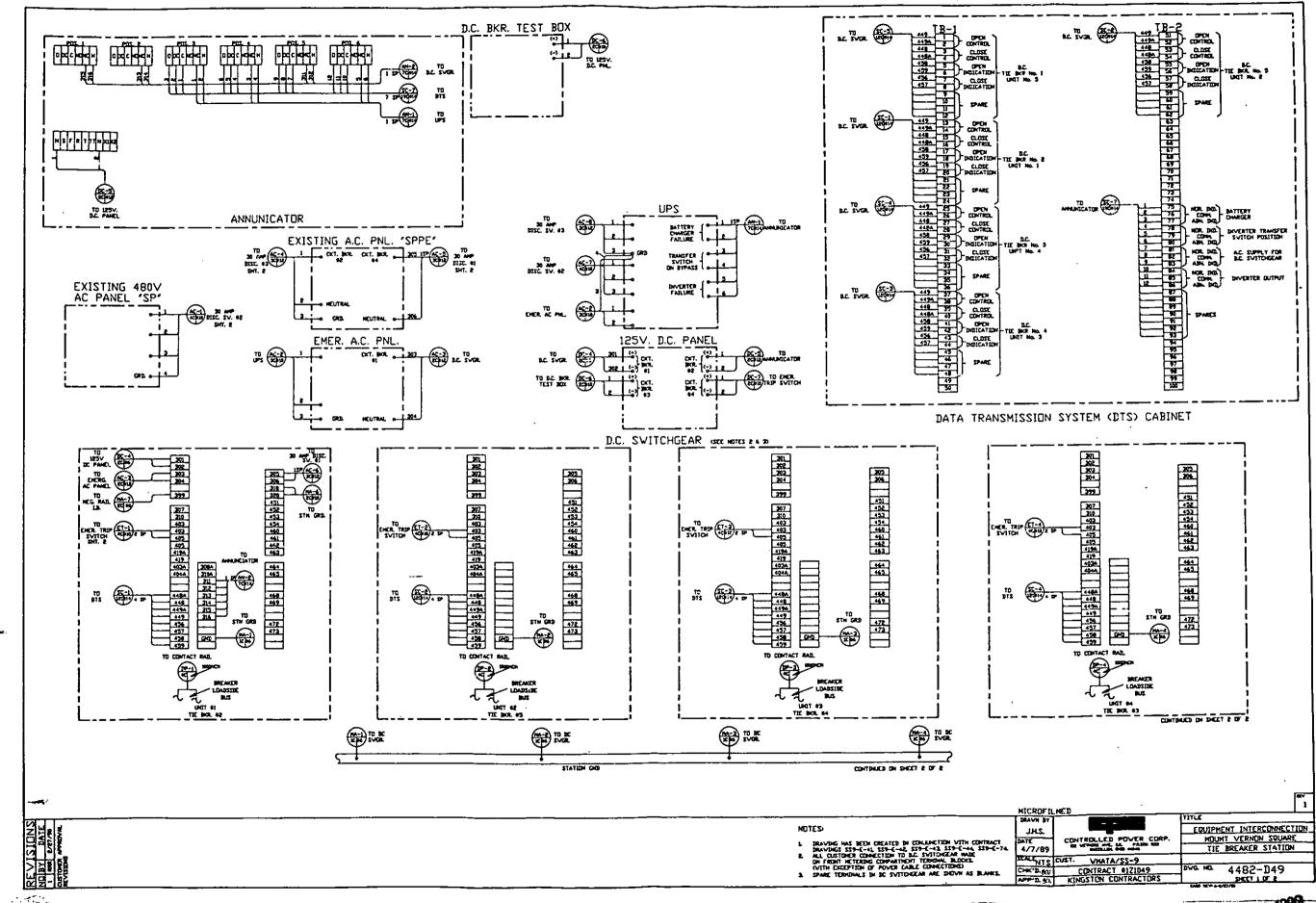
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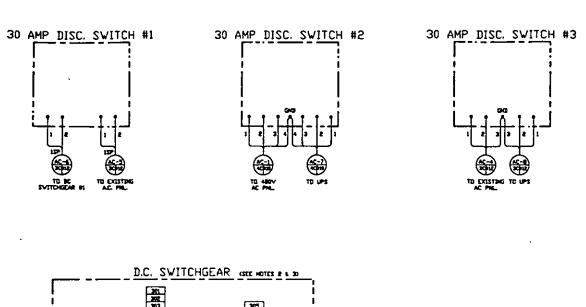
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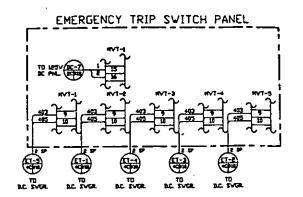


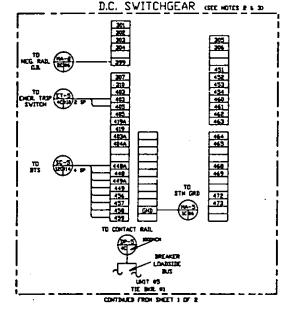
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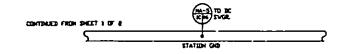


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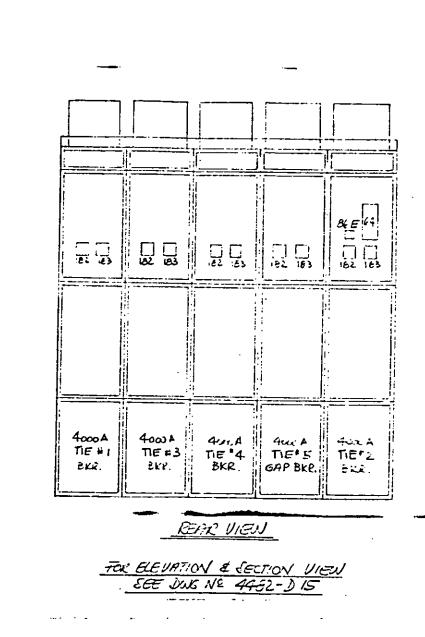


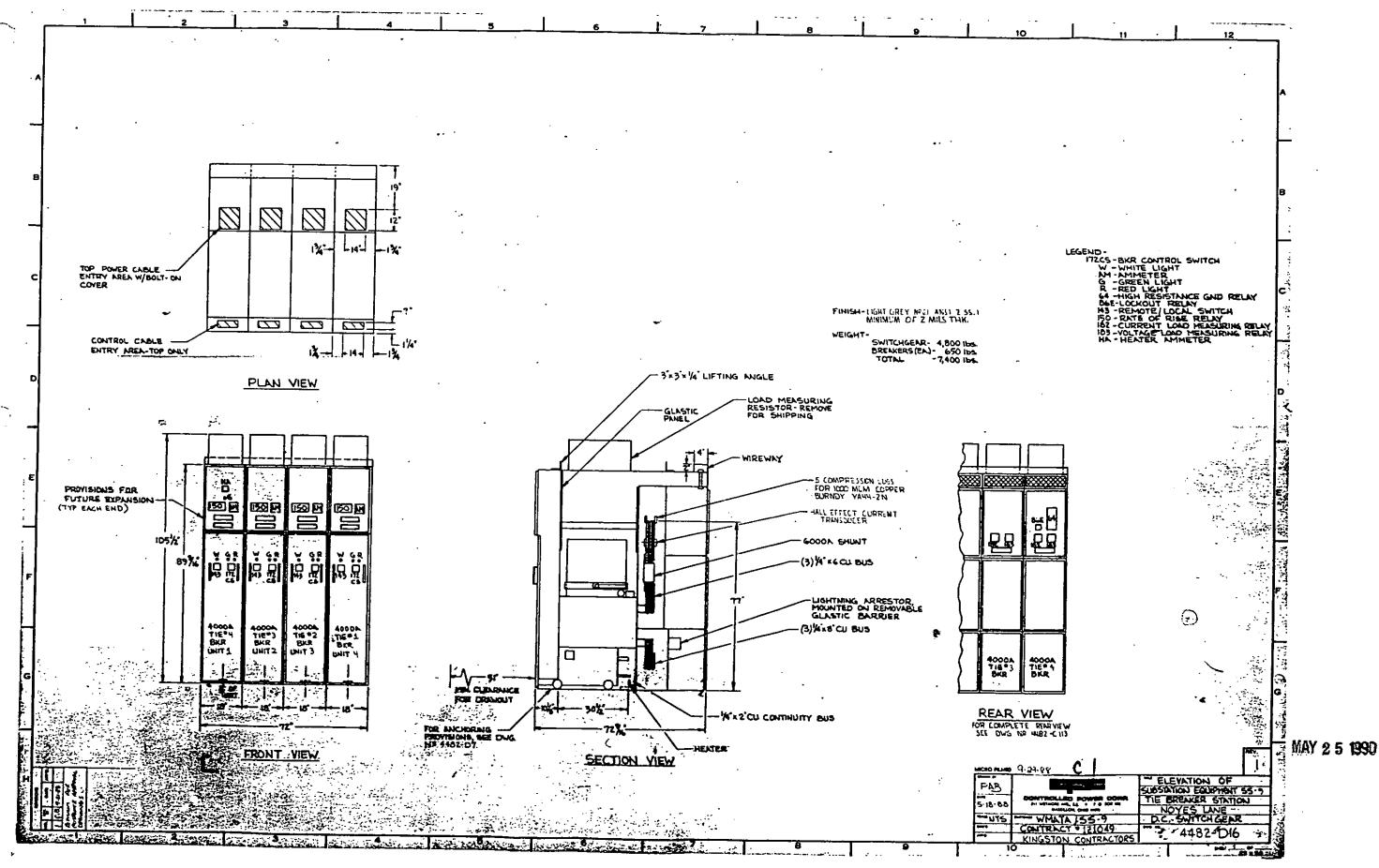


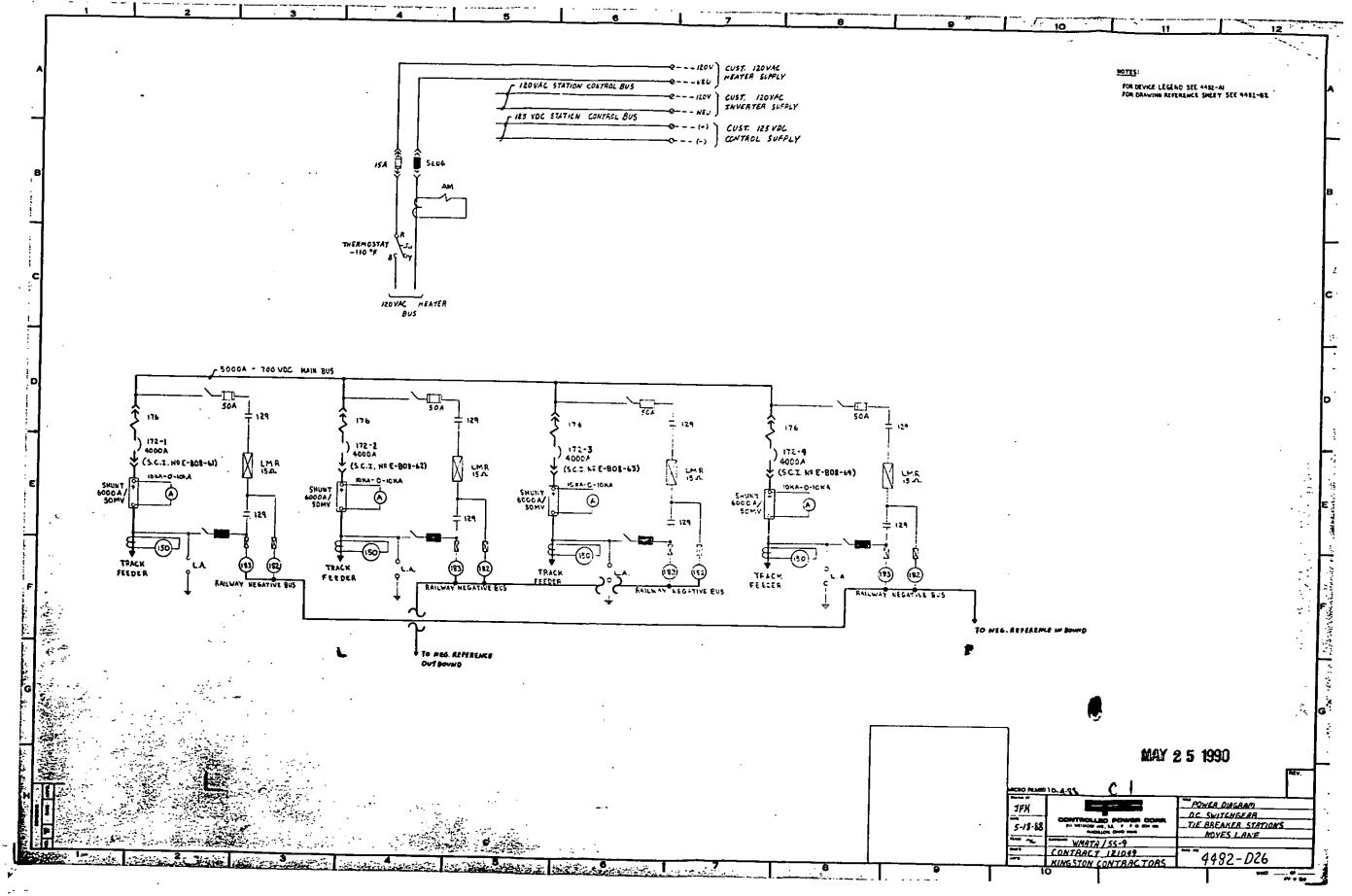


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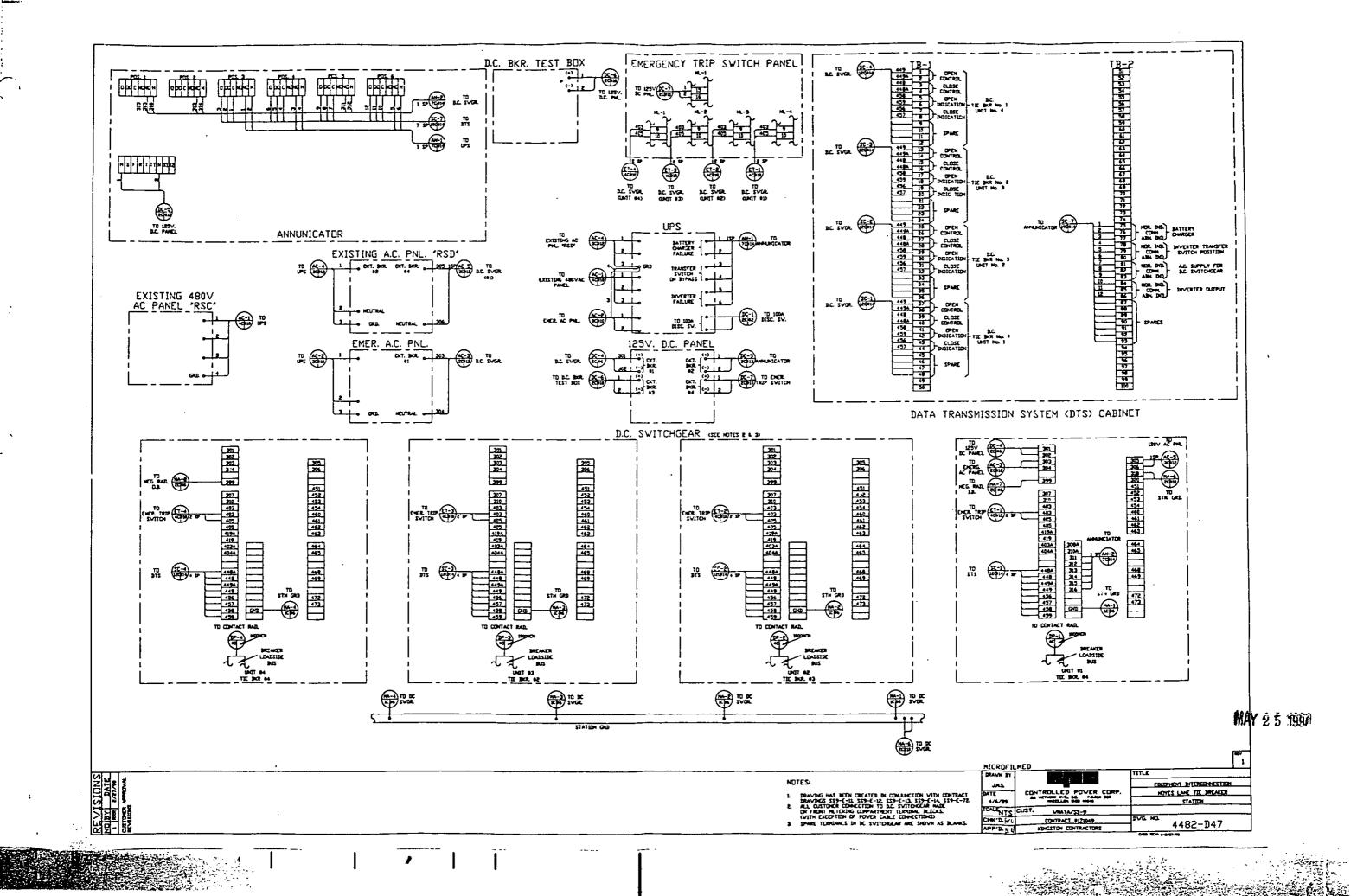
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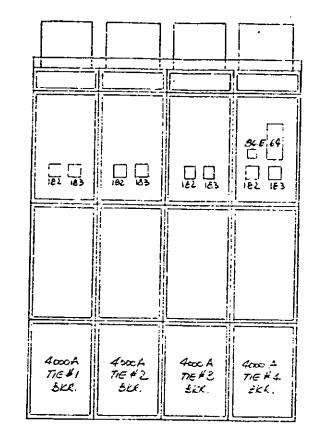
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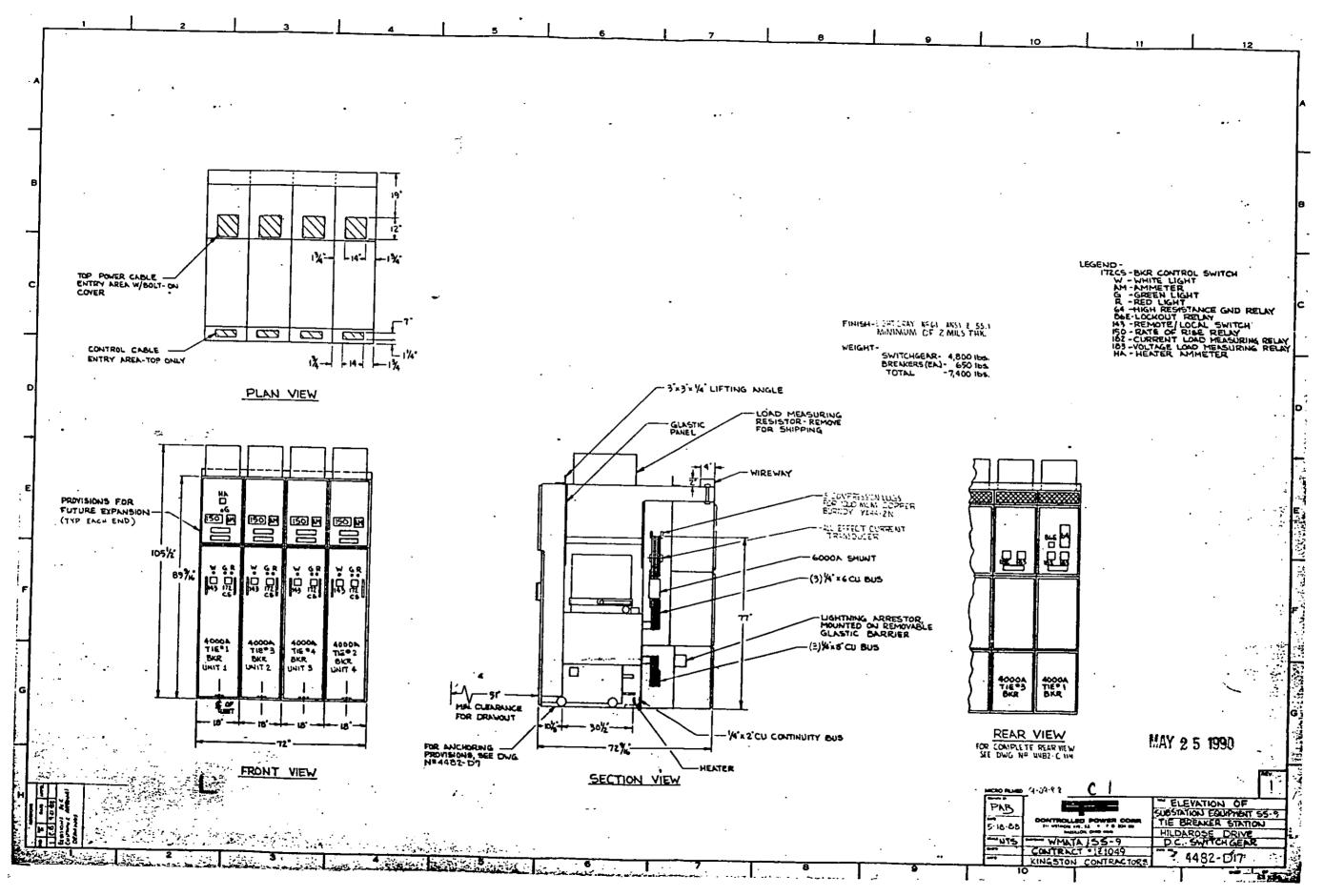


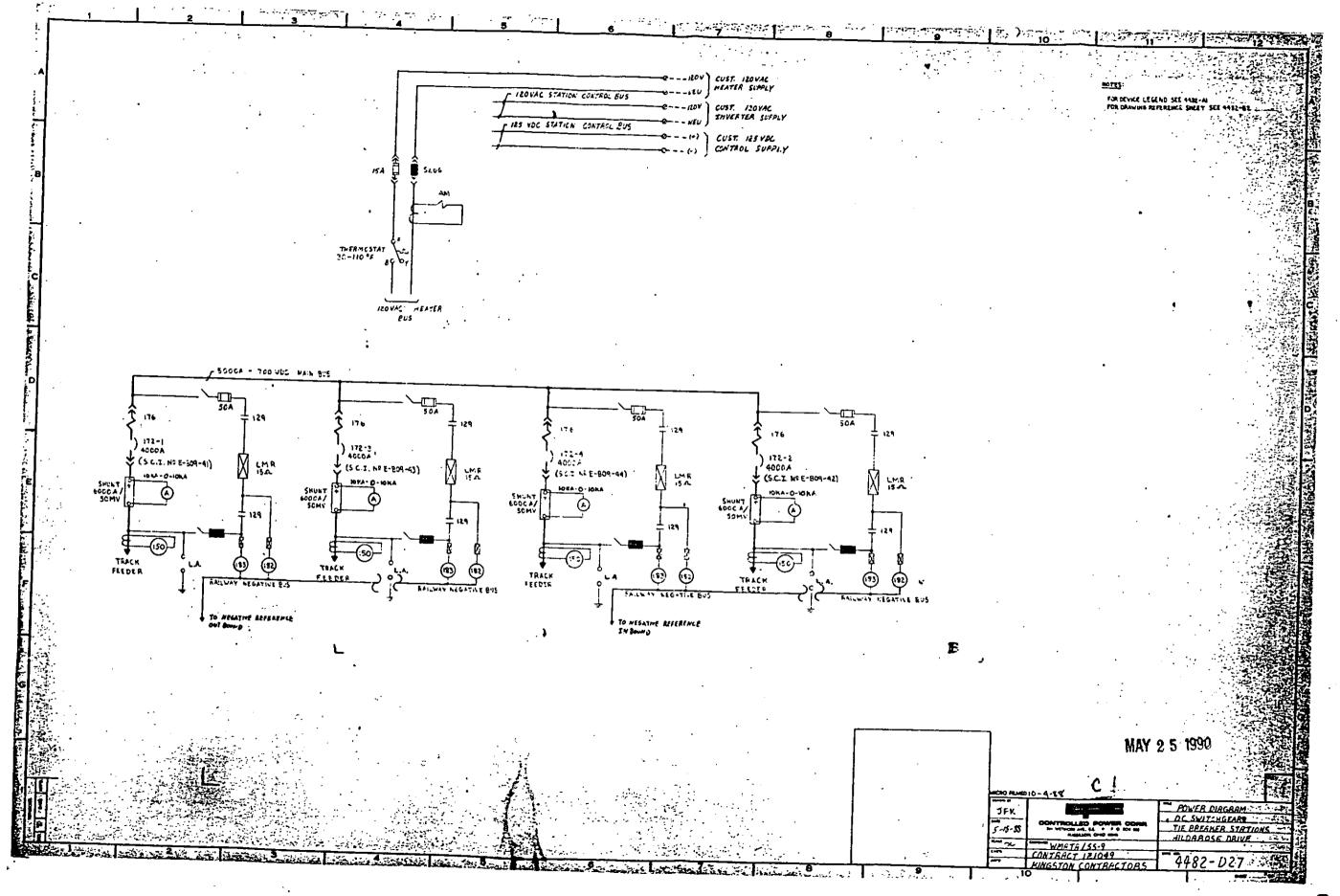


REAK VIEW

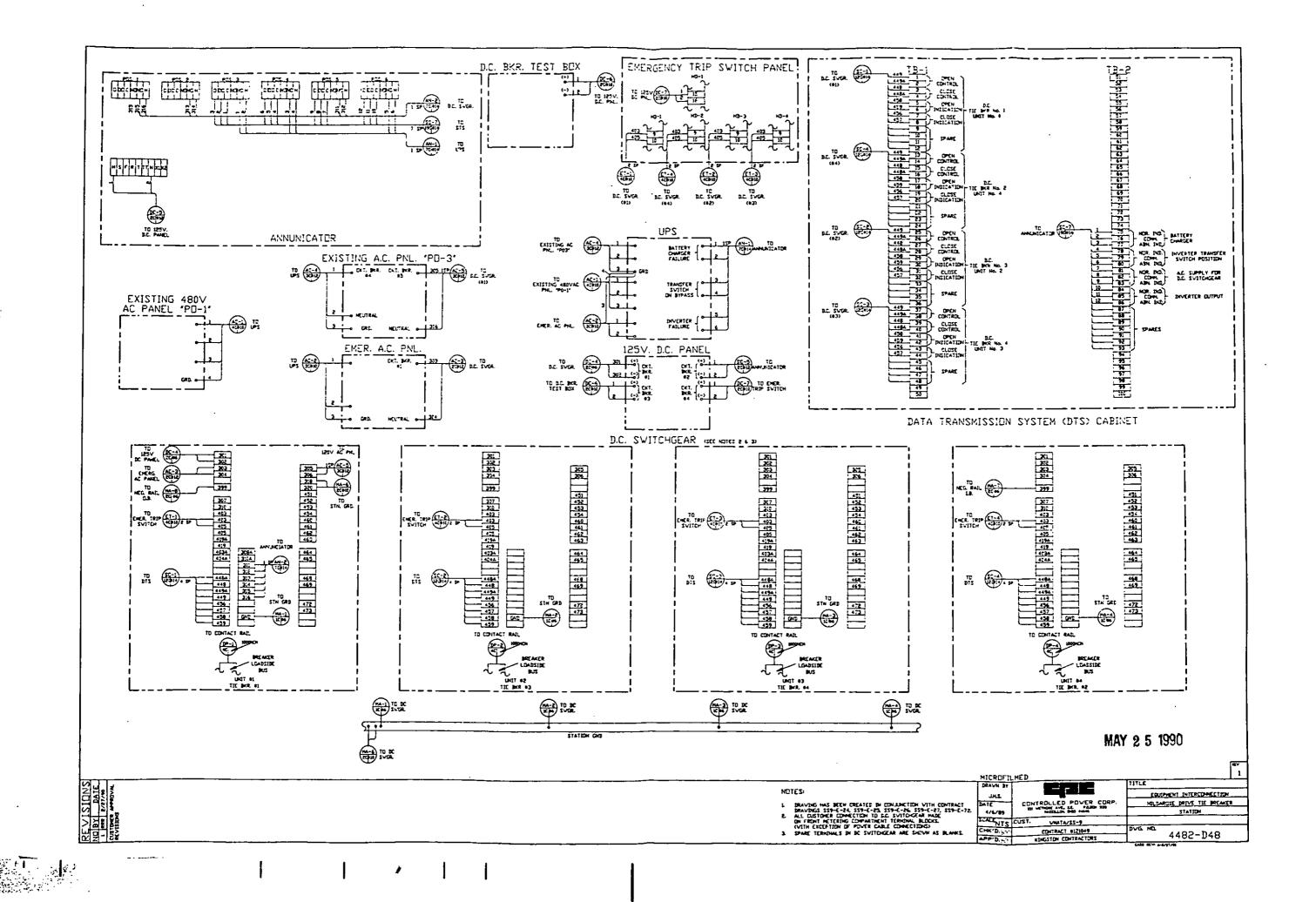
FOR ELEVATION & SECTION VIEW SEE DUG Nº 4482-D16

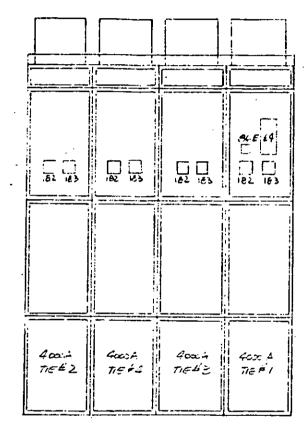
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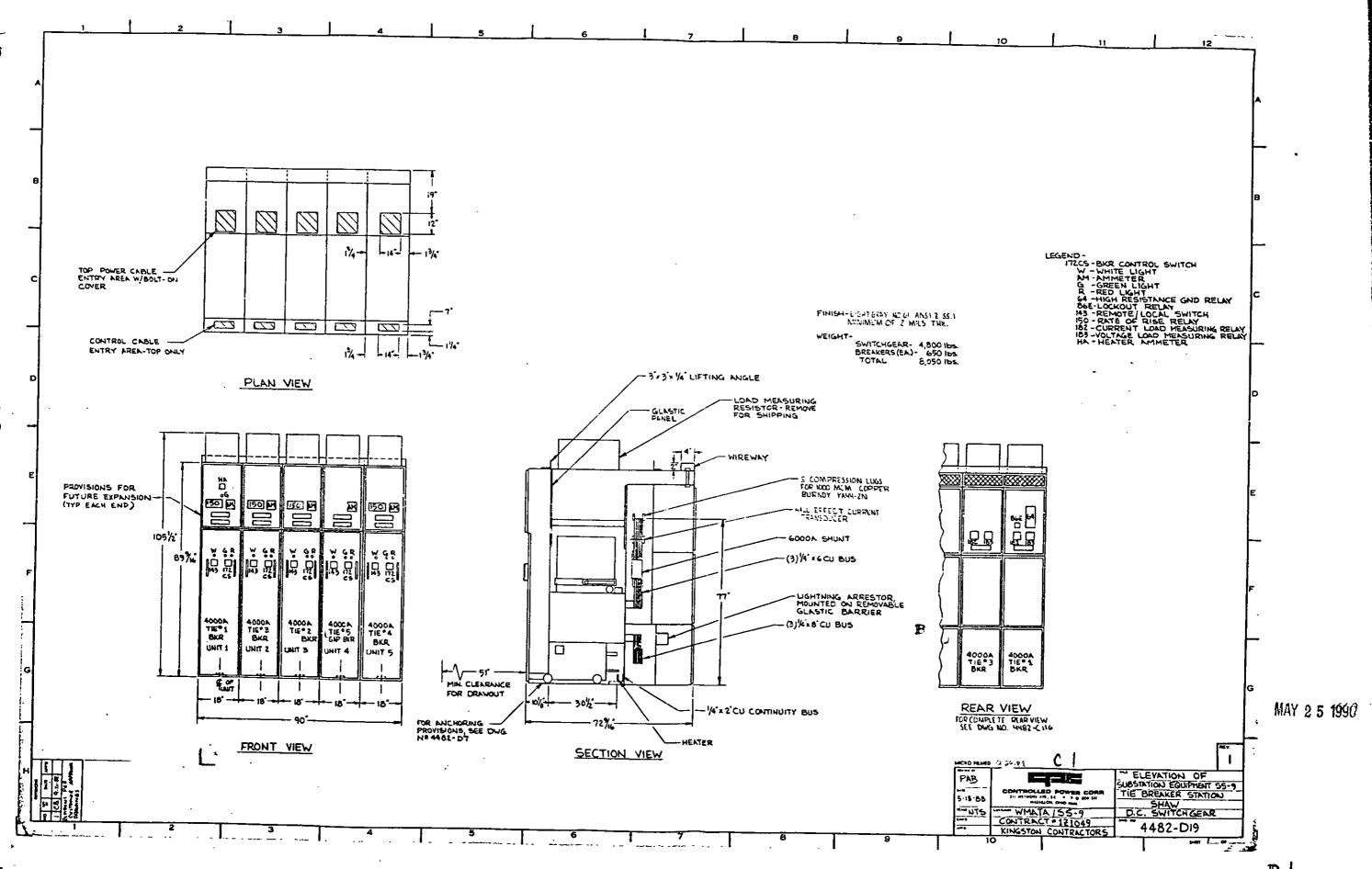
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FOR ELEVATION & SETTION VIEW SEE DUG Nº 4482-D17

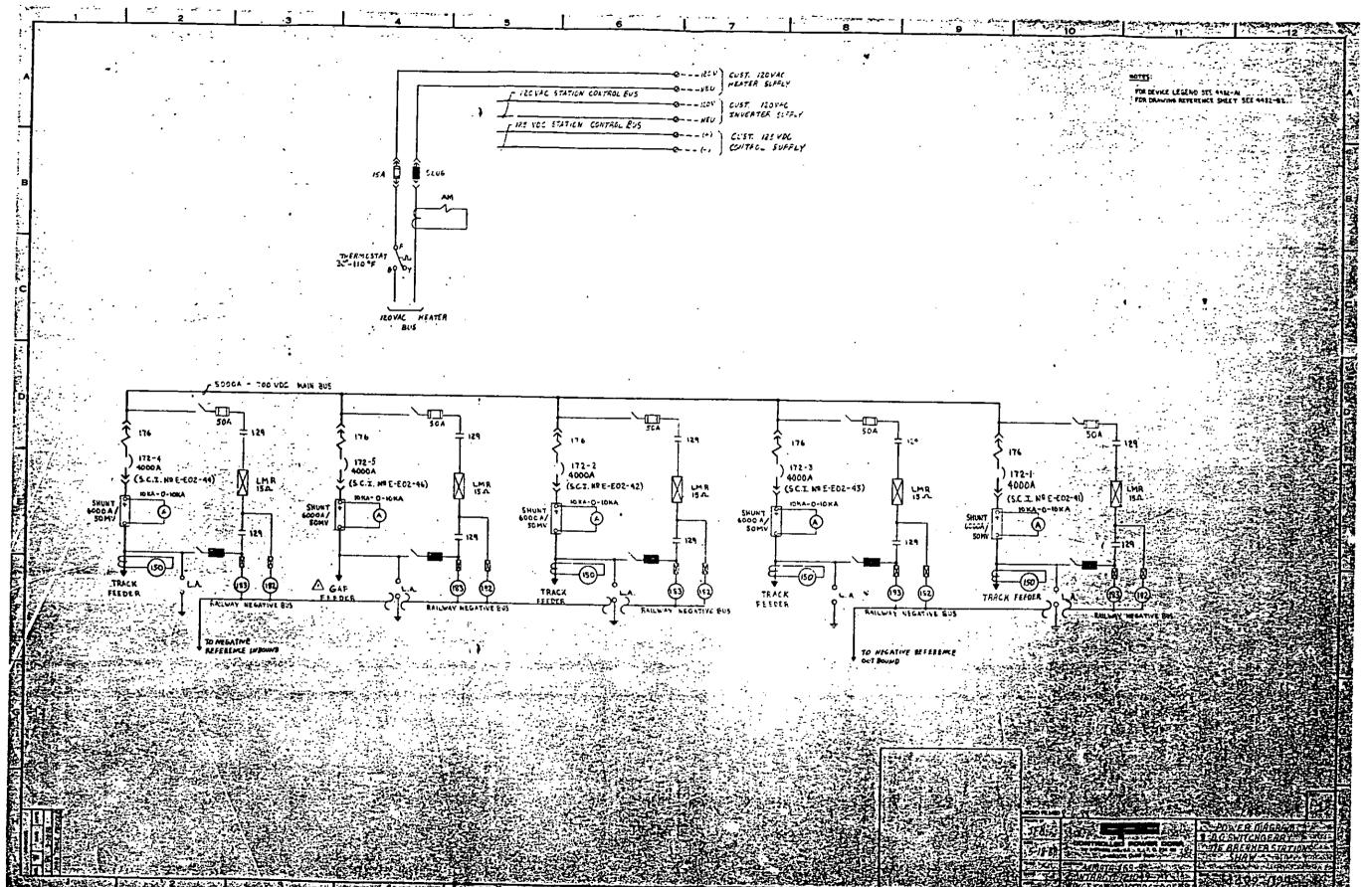
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MAY 2 5 1990

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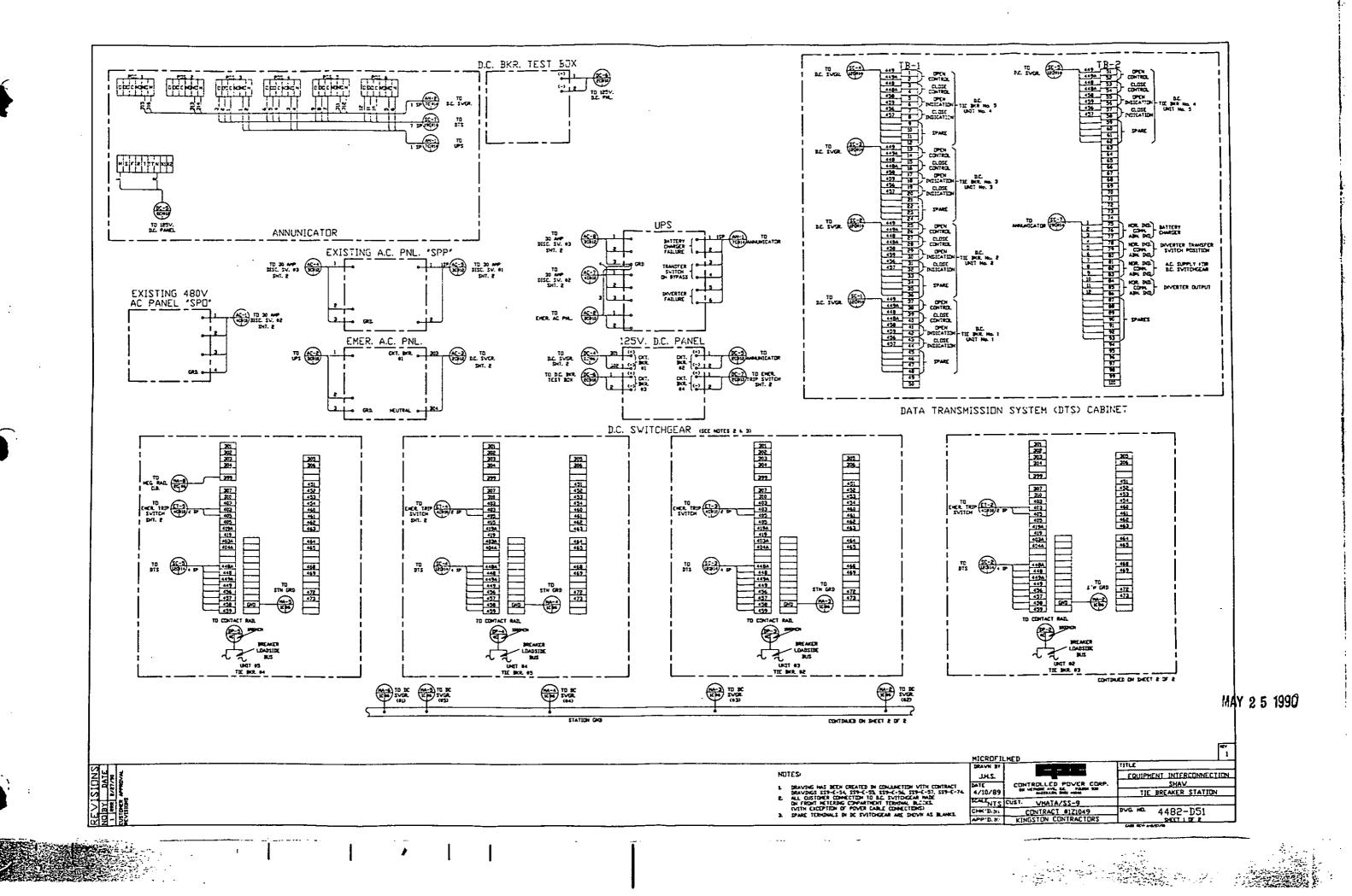
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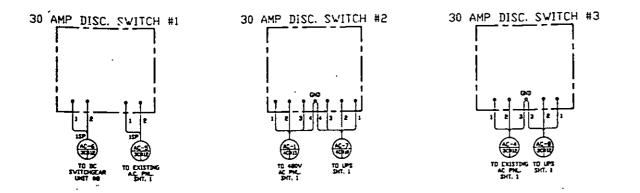
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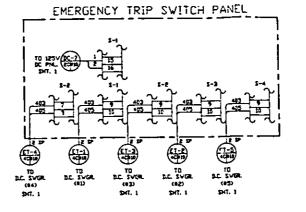
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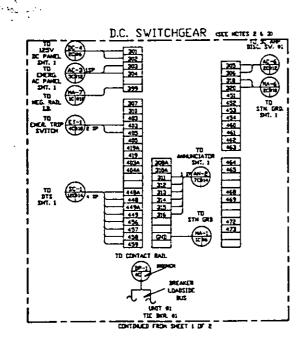
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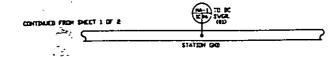
KINGSTON CONTRACTORS 4482-039











MAY 2 5 1990

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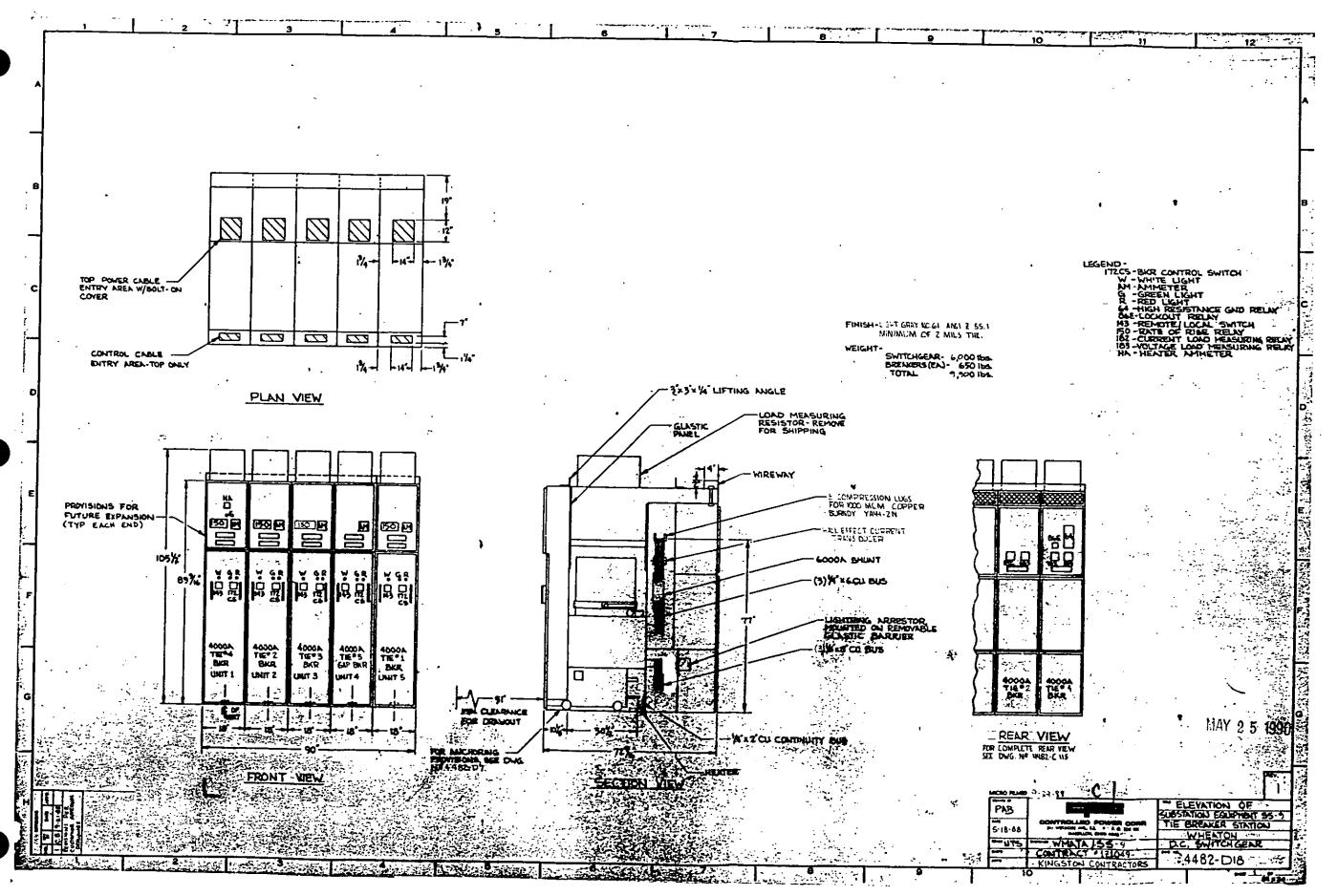
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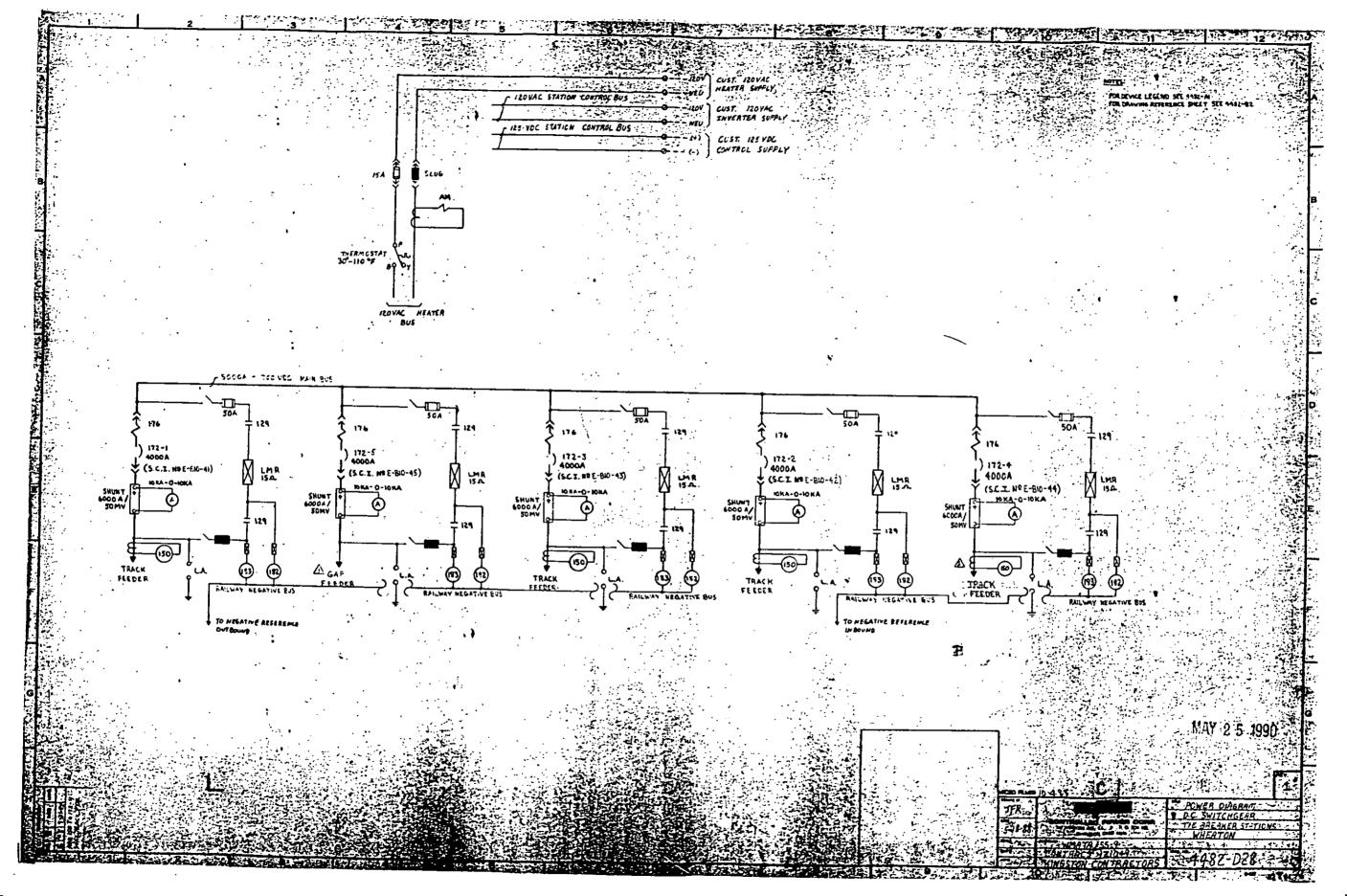
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FOR ELEVATION & SECTION VIEW
SEE DUG Nº 4482-D 19

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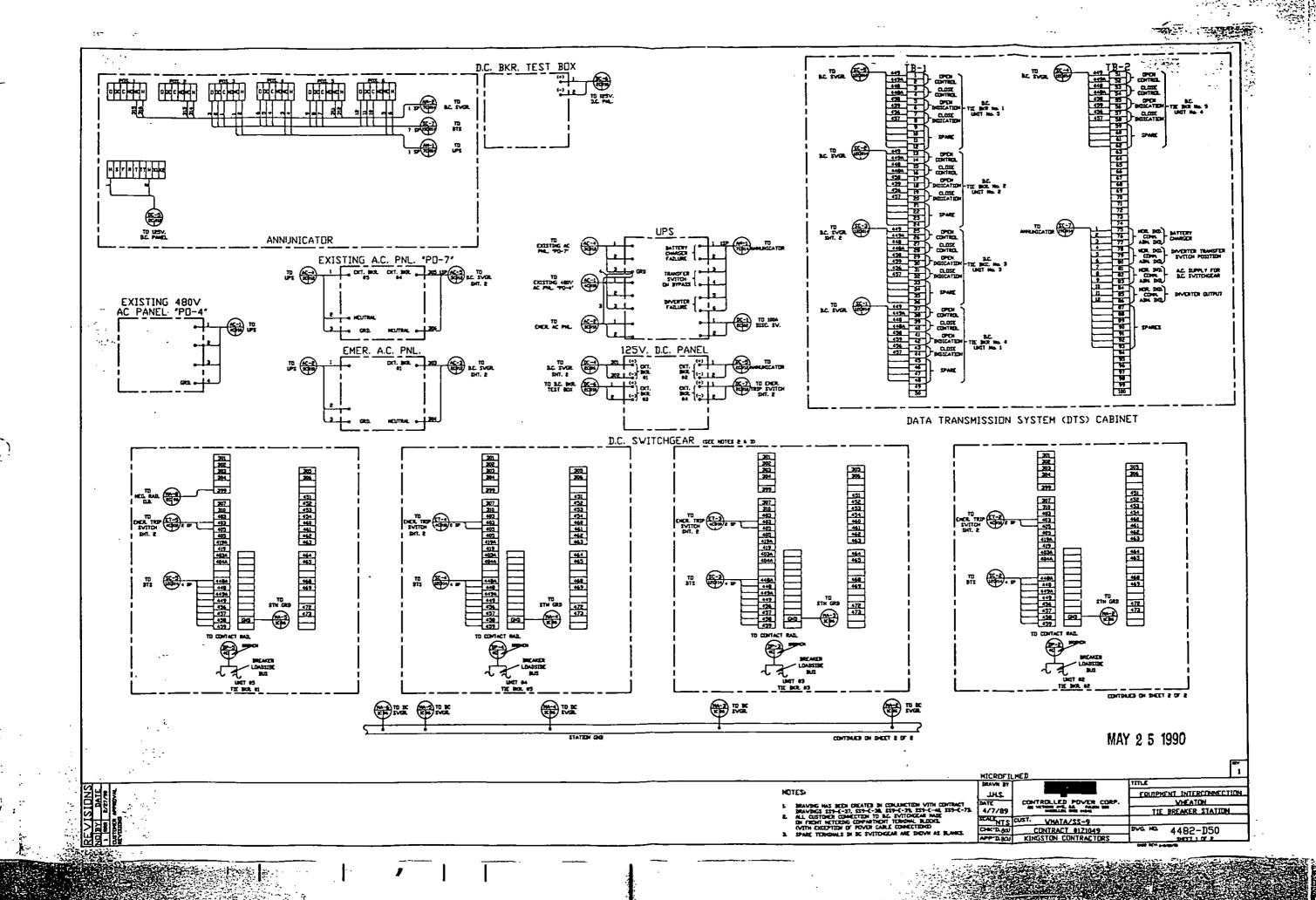
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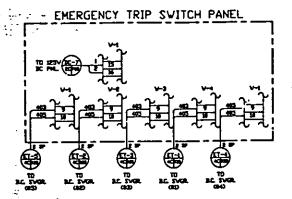
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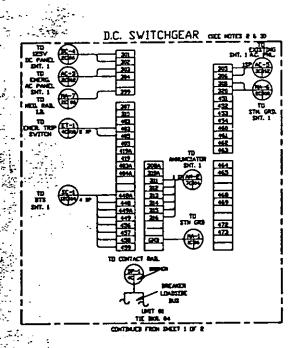
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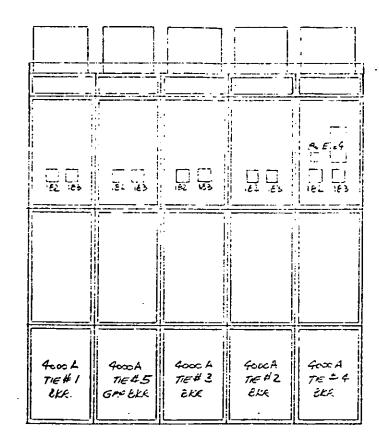
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REAX VIEW

FOR ELEVATION & SECTION VIEW SEE DWG Nº 4482-D 18

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PEND TO THE POWER CORP.

111 WEINOSE AVE. SE. 9. 2 DOI ST.

MASSELON CHO MASSELON CORP.

212 WEINOSE AVE. SE. 9. 2 DOI ST.

224 D.C. SWITCHGEAR.

2440.

RENEWAL PARTS 800 VOLT DC METAL ENCLOSED SWITCHGEAR

for

WASHINGTON METROPOLITAN AREA TRANSIT AUTHORITY

Lansdowne Way Substation
Windham Lane Substation
Mount Vernon Square Substation
U Street Substation

WMATA Contract No. 1Z1049 SSE-9

Renewal Parts Manuals

Description	Mfr.	<u>Publication</u>
Indicating Light	G.E.	GEF-4326



Ordering Instructions

- Always specify the complete nameplate data of the equipment.
- Specify the quantity, catalog number (if listed), reference numbr (if listed), description, and this bulletin number.
- For prices, refer to the nearest office of the General Electric Company.

TABLE 1
INDICATING LAMP, COMPLETE ASSEMBLY
(REFERENCE A)

Rating, Volts	Catalog Number	
24	721-116B6708G1	
48	721-116B6708G2	
70	721-116B6708G7	
120	721-116B6708G5	
125	721-116B6708G3	
130	721-116B6708G8	
240	721-116B6708G6	
2501	721-11686708G4	

TABLE 2 COLOR CAPS (REFERENCE B)

Catalog No.	Color
721-208A3768P1	Cleart
721-208A3768P2	Redtt
721-208A3768P3	Greent t
721-208A3768P4	Yellowt t
721-208A3768P5	White† †
721-208A3768P6	Bluet
721-208A3768P7	Ambert
721-208A3768P8	Greent
721-208A3768P9	Redt

† transparent | † † translucent

TABLE 3 LAMP BULB (REFERENCE C)

Catalog No.	Volts
721-1819	Δ 24
721-1835	△ All Other

△ With proper resistor

TABLE 4 RESISTOR (REFERENCE D)

Rating, Volts	Catalog No.	Ohms, Total
24	721-165A7844P1	10
48	721-165A7844P2	200
70	721-165A7844P7	750
120	721-165A7844P5	1900
125	721-165A7844P3	2500
130	721-165A7844P8	2300
240	721-165A7844P6	4800
250	721-165A7844P4	5100

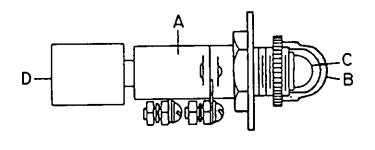


Fig. 1. Type ET-16 indicating lamps

Data is subject to change without notice.

GENERAL ELECTRIC COMPANY

METER AND CONTROL BUSINESS DEPT.

MALVERN, PA 19355





DRAWING LIST FOR 800 VOLT DC METAL ENCLOSED SWITCHGEAR

Bill of Material - Tab 1

Drawings Common to All Substations - Tab 2

DRAWING NO.	DESCRIPTION
4482-A1	Device Legend
4482-A2	Drawing Reference List
4482-D3	Cathode Breaker Elementary
4482-D4	Track Feeder Breaker Elementary
4482-D5	Gap & Storage Track Feeder Elementary
4482-D6	Common Circuits Elementary
4482-D7	Anchoring Detail
4482-D41	Wiring - Cathode w/ Current Transducer
1482-D42	Wiring - Cathode w/ Current, Voltage and Watt Transducer
4482-D43	Wiring - 4000A Track Feeder
4482-D44	Wiring - Gap of Storage Track Feeder
4482-D45	Wiring - Track Feeder w/ Aux. Circuits
4482-D46	Wiring - 6000A Track Feeder

Drawings for Particular Stations:

Windham Lane Substation - Tab 3

DRAWING NO.	DESCRIPTION
4482-D11	Elevation and Section Views
4482-D21	Power Diagram
4482-D31	Unit Interconnections
4482-D165	Substation Equipment Interconnections
\482-C108	Rear View

Lansdowne Way Substation - Tab 4

JRAWING NO.	DESCRIPTION
4482-D12	Elevation and Section Views
4482-D22	Power Diagram
4482-D32	Unit Interconnections
4482-D164	Substation Equipment Interconnections
4482-C109	Rear View
<u>U-Street Substation - Tab 5</u>	
DRAWING NO.	DESCRIPTION
4482-D13	Elevation and Section Views
4482-D23	Power Diagram
4482-D33	Unit Interconnections
4482-D167	Substation Equipment Interconnections

Mount Vernon Square Substation- Tab 6

4482-C110

DRAWING NO.	DESCRIPTION
4482-D14	Elevation and Section Views
4482-D24	Power Diagram
4482-D34	Unit Interconnections
4482-D166	Substation Equipment Interconnections
4482-C111	Rear View

Rear View

Mount Vernon Square Tie Breaker Station - Tab 7

DESCRIPTION DESCRIPTION

4482-D15 Elevation and Section Views

4482-D25 Power Diagram

4482-D35 Unit Interconnections

4482-D49 Substation Equipment Interconnections

4482-C112 Rear View

Noyes Lane Tie Breaker Station - Tab 8

DRAWING NO. DESCRIPTION

4482-D16 Elevation and Section Views

4482-D26 Power Diagram

4482-D36 Unit Interconnections

4482-D47 Substation Equipment Interconnections

4482-C113 Rear View

DRAWING NO. DESCRIPTION

4482-D17 Elevation and Section Views

4482-D27 Power Diagram

4482-D37 Unit Interconnections

4482-D48 Substation Equipment Interconnections

4482-C114 Rear View

Shaw Tie Breaker Station - Tab 10

DRAWING NO. DESCRIPTION

4482-D19 Elevation and Section Views

4482-D29 Power Diagram

4482-D39 Unit Interconnections

4482-D51 Substation Equipment Interconnections

1482-C116 Rear View

Wheaton Tie Breaker Station - Tab 11

DRAWING NO.	DESCRIPTION
4482-D18	Elevation and Section Views
4482-D28	Power Diagram
4482-D38	Unit Interconnections
4482-D50	Substation Equipment Interconnections
4482-C115	Rear View

CUSTOMER: WMATA/SS-9 CONTRACT 121049 TITLE:750V DC METAL ENCLOSED

WRITTEN BY:SIL DATE TYPED:05/26/88 CUSTOMER ORDER #22967PB

CONTRACT 121049 SWITCHGEAR.
KINGSTON CONTRACTORS

REVISION #: 4 REV. DATE:12/27/88

Tue Dec	27 1988	3	CPC BILL OF MATERIAL JOB # 4482			PAGE 1							a	T'Y. P	ER LOC	ATION					
ITEM #	SYMBOL	P.O.# & LTEN	DESCRIPTION	MFR C'CODE	TYPE & CATALOG #	CLASS CPC 1.0.#	QTY.	1	2	3	4	5	6	N I T/CUI 7	BICLE S	NO. 9	10	11	12	13	14
1	n	4482-Y	CIRCUIT BREAKER, 800V DC, 6000 AMP, SINGLE POLE, 125V DC CONTROL, HIGH SPEED WITH: CONTROL SWITCH, LOCAL/REMOTE SWITCH, 12 STAGE AUXILIARY SWITCH, RED, WHITE & GREEN LIGHTS, 125V DC SHUNT TRIP, REVERSE CURRENT TRIP, OPERATION COUNTER	PAHCO 005	HSNP	5R BR-018	8	1	1	0	0	0	0	0	0	0	0	0	0	0	0
2	172	4482-Y 3	CIRCUIT BREAKER, 800V DC, 6000 AMP, SINGLE POLE, 125V DC CONTROL, HIGH SPEED WITH: CONTROL SWITCH, LOCAL/REMOTE SWITCH, 12 STAGE AUXILIARY SWITCH, RED, WHITE & GREEN LIGHTS, 125V DC SHUNT TRIP, BIDIRECTIONAL OVERCURRENT TRIP, OPERATION COUNTER AND U.V. RELEASE	PAMCO 005	HSHP	BR BR-019		O	0	0	0	0	1	0	0	0	0	0	0	C	0
3	172	4482-Y · 2	CIRCUIT BREAKER, 800V OC, 4000 AMP, SINGLE POLE, 125V DC CONTROL, HIGH SPEED WITH: CONTROL SWITCH, LOCAL/REMOTE SWITCH, 12 STAGE AUXILIARY SWITCH, RED, WHITE & GREEN LIGHTS, 125V DC SHUNT TRIP, BIDIRECTIONAL OVERCURRENT TRIP, OPERATION COUNTER AND U.V. RELEASE	PAHCO 005	HSNP	8R 8R-020	38	0	. 0	1	1	1	0	0	0	'o	0	0	0	0	Q
4		4482-T 7	CIRCUIT BREAKER CELL, 6000 AMP	CPC	HSNP	EN - 135	12	1	1	0	0	0	1	0	C	0	0	0	0	0	0
5		4482-Y 8	CIRCUIT SREAKER CELL, 4000 AMP	СРС	HSNP	EN EN-136	38	0	0	1	1	1	0	0	0	0	0	0	0	0	0
6	SHUNT	4482-C 1	SHUNT, 8000 AMP, 50 MV, SWITCHBOARD TYPE	CROMPTON 053	886 886-92UU-UVEC	AC AC-0219	8	1	1	0	C	0	0	0	0	C	0	0	O	0	0
7	SHUNT	4482-C 2	SHUNT, 6000 AMP, 50 MV, SWITCHBOARD TYPE	CROMPTON 053	886 886-92UU-UPEC	AC-0220	42	0	0	1	1	1	1	0	0	0	0	0	0	O	O

PAGE 1 REVISION #: 4 REVISION DATE:12/27/88

JC8: 4482

CUSTOMER:WMATA/SS-9

TITLE:750V DC METAL ENCLOSED

WRITTEN BY:SIL DATE TYPED:05/26/88

4482

J08:

KINGSTON CONTRACTORS

CONTRACT 121049 CUSTOMER ORDER #22967PB SWITCHGEAR. REVISION #: 4 REV. DATE: 12/27/88

Tue Dec 27 1988 CPC BILL OF MATERIAL JOB # 4482 PAGE 2 QT'Y. PER LOCATION MFR TYPE & CLASS UNIT/CUSICLE NO. ITEM # SYMBOL P.O.# & DESCRIPTION CPC 1.D.# 5 7 9 10 LTEM C'CODE CATALOG # 2 3 8 11 12 13 14 4482-AY AMMETER, DC, SWITCHBOARD TYPE, 0-93.75MV MOVEMENT, CROMPTON AD. 8 AH 077-0-15KA AMDS-020 0-15KA SCALE AD 4 Û CROMPTON 700 4482-AY AMMETER, DC, SWITCHBOARD TYPE, 125 MV-0-125MV 077-15KA-0-15KA AMDS-021 HOVEMENT, 15KA-0-15KA SCALE 700 AD 38 0 4482-AY AMMETER, DC, SWITCHBOARD TYPE, 83.33-0-83.33MV CROMPTON AH 3 MOVEMENT, 10KA-0-10KA SCALE 077-10KA-0-10KA AMDS-022 9 ٥ 4482-A GEC VAE21 RL RELAY, HIGH RESISTANCE GROUND AND POTENTIAL MONITORING 062 RL-0259 9 RELAY, LOCKOUT, HAND RESET, 4 DECK, 125V DC COIL, ES LOR RL 86, 86S 448Z-D 062 7804D RL-0060 1 8 N.O. & 8 N.C. CONTACTS 9 0 RL 13 27AC 4482-E RELAY, UNDERVOLTAGE, 120V AC COIL, 2 FORM C P & 8 KRPA CONTACTS 062 KRPA11AY120 RL-0260 1 9 14 64CX 4482-E RELAY, UNDERVOLTAGE, 120V AC COIL, 2 FORM C P & 8 KRPA RL KRPA11AY120 RL-0261 260 1 CONTACTS 15 4482·E SOCKET, & PIN OCTAL PEB 18 RL-0009 008 27E122 2 4482-F INDICATING LIGHT, TYPE ET-16, RESISTOR TYPE, GREEN G.E. ET-16 LT 9 16 G 011686708G3G LT-035 056 TRANSPARENT LENS, 125V DC (TRIP) 8 4482-A RELAY, DC, OVERCURRENT, SHUNT OPERATED, 0-100 MV GEC DBA4 RL 17 76 RL-0262 FULL SCALE DEFLECTION, SCALED 0-16KA, RELAY TO BE EQUIPPED WITH SEAL-IN AUXILIARY ELEMENT

> 4 REVISION DATE: 12/27/88 PAGE 2 REVISION #:

CUSTOMER: WATA/SS-9 CONTRACT 121049

JOB: 4482

TITLE:750V DC METAL ENCLOSED SWITCHGEAR.

WRITTEN BY:SIL DATE TYPED:05/26/88
CUSTOMER ORDER #22967PB
REVISION #: 4 REV. DATE:12/27/88

KINGSTON CONTRACTORS

Tue Dec	27 1988	3	CPC BILL OF MATERIAL JOS # 4482			PAGE 3							a	T'Y. PI	ER LOC	ATION					
ITEM #	SYMBOL	P.O.# &	DESCRIPTION	MFR C'CODE	TYPE & CATALOG #	CLASS CPC [.D.#	QTY.		2	3	4	5	6	N E T / CUI	8	NO. 9	10	11	12	13	14
18	CXD	4482-BJ 1	DC ISOLATION TRANSDUCER, CUTPUT 0-10V DC = 0-15KA DC, INPUT FROM 50 MV, 6000A SHUNT, 120V AC CONTROL POWER	096	SCI-COL 6271A	XD XD - 195	8	1	1	0	0	0	0	0	0	0	0	0	0	0	0
19	VXD	4482-BJ 2	DC ISOLATION TRANSDUCER, CUTPUT 0-10V DC INPUT 0-5MA CUTPUT, 120V AC CONTROL POWER	096	SCI-COL 6271PA6-Z	хо хо-196	4	0	6 , 1	0	0	0	0	0	0	a	0	0	0	0	0
20	RES	4482-8J 4	DROPPING RESISTOR FOR DC VOLTAGE INPUT TO WXD, 3.85 MEGADAM , 2 WATT METAL FILM TYPE IN METAL CAN	052	SCI-COL	XD XD-197	4	0	1	0	0	0	0	0	0	0	0	0	0	0	0
21	UXD	4482-8J 3	WATE TRANSDUCER, 0-5 MA VOLTAGE ENPUT, 0-40 VOLT MAX CURRENT ENPUT, OUTPUT 0-1 MA = 0-28 MW	096	801-COL	XD XD-198	4	0	1	0	0	0	0	0	0	0	0	0	0	0	0
22	THM	4482-AB 1	TELEMEGAMATTMETER-BINARY ANALOG TO RELAY CONVERTER INPUT 0-1 MA, CUTPUT 7 DIGIT BINARY FROM 7 M.O. REED RELAY CONTACTS, TEMP. RANGE 0 DEGREES C TO 50 DEGREES C, CONTACT RATING, 15VA, 1A MAX, EXTERNAL SAMPLE INPUT = 24V POWER SUPPLY 105-125V AC, ENCLO. SIZE K	OHI-SEMI 058	CAD CAD-1941	WD WHDM-033	4	0	1	0	0	0	O	0	0	'o	0	O	0	0	1
23	129	4482-9 1	CONTACTOR, 2 POLE, 780 VOLT, 50 AMP, 125V DC COIL 2 N.O. CONTACTS	WEST. 008	MME 2050	AC AC-0221	42	0	0	1	1	1	1	0		0	0	0	0	0	0
24	182	4482-AZ 1	RELAY, RECLOSING, 4-1/2" SQUARE, SWITCHBOARD TYPE 125Y AC AUXILIARY POWERED ELECTRONIC METER RELAY WITH ONE SETPOINT, ONE CUIPUT RELAY, LOW SET POINT UPSCALE ENERGIZED, RANGE 0143.75V DC TO 0-1.0 OHMS	062	LFE	8R 8R-021	42	0	0	1	1	1	1	C	0	G	0	0	0	0	0
25	183	4482-AZ 2	RELAY, LOAD MEASURING, 4-1/2" SQUARE, SWITCHBOARD TYPE, 125V AC AUXILIARY POWERED ELECTRONIC METER RELAY, SCALED 0-800V DC, TWO SET POINTS AND 2 SPOT QUIPUT RELAYS, DOUBLE REVERSE SETPOINT ENERGIZED	062	LFE	BR BR-022	42	0	0	1	1	1	1	0	O	0	0	0	0	0	0

PAGE 3 REVISION #: 4 REVISION DATE:12/27/68

CUSTOMER: LANATA/SS-9

TITLE: 750V DC METAL ENCLOSED SWITCHGEAR

CUSTOMER CROER #22967PB

WRITTEN BY:SIL DATE TYPED:05/26/88

CONTRACT 121049 KINGSTON CONTRACTORS

REVISION #: 4 REV. DATE: 12/27/88

Tue Dec	27 1988	8	CPC BILL OF MATERIAL JOB # 4482			PAGE 4							Q	Γ'Υ. P	ER LOCA	ATION			-		
ITEM #	JOBNYZ	P.O.# & ITEM	DESCRIPTION	MFR C'CODE	TYPE & CATALOG #	CLASS CPC I.D.#	QTY.	1	2	3	4	5	U1 6	11T/CU:	BICLE S	NO. 9	10	11	12	13	14
25		4482-AZ 3	HIGH VOLTAGE MULTIPLIER/LIMITER ASSEMBLY FOR 750V DC OPERATION OF 182 AND 183	062	LFE	BR BR-023	42	0	0	1	1	1	1	0	0	0	0	0	0	0	0
27	201x	4482-U 1	PART NO. D2600/LES/20/CCT.A/FP22/110VDC RELAY LATCHING TYPE, 110V DC COIL SUICIDE CONTACTS IN SERIES W/BOTH COILS TWO "M" (MAKE ON EXERGIZE) AND 1 "B" (BREAK ON EXERGIZE) CONTACTS	C & S 062	02600	RL -0263	42 -	0	0 6.	1	1	1	1	0	0	0	o	0	0	0	0
28	201X	4482-U 2	SOCKET W/FP22 FOULING PIN	C & S	D2600 D2600/FT/FP22	RL RL-0264	42	0	0	1	1	1	1	0	0	0	0	0	0	0	0
29	201C,T	4482•U 3	PART NO. D2600/2/FP24/24VDC AUXILIARY RELAY, 24V DC COIL, 2 N.O. CONTACTS	C & S 062	02600	RL RL - 0265	84	o	0	2	2	5	2	0	0	0	0	0	0	0	0
30	201C,T	4482-U 4	SOCKET WITH FP24 FOULING PIN	c & s	02600 02600/FT/FP24	RL RL • 0266	84	0	0	2	2	2	2	0	0	0	0	0	0	0	0
31	1722	4482-V 1	PART NO. D2600/24/3X/FP6/110VDC AUXILIARY RELAY, 110V DC COIL WITH 3 N.C. AND 2 N.O. CONTACTS AND 1 N.O. EARLY MAKE CONTACT	C & \$ 062	D2600	RL RL-0267	42	0	0	1	1	1	1	0	0	0	0	o	0	0	0
32	172z	4482-Y 2	SOCKET WITH FP6 FOULING PIN	C & S	D2600 D2600/FT/FP6	RL RL-0268	42	. 0	0	1	1	1	1	0	0	0	0	0	0	0	0
33	186	4482•Z 1	TIMER ON DELAY, 120V AC COIL	ATC São	319 319001601C	RL RL-0269	42	a	0	1	1	1	1	O	0	0	0	0	0	0	0
34	186	4482-Z 2	OCTAL SOCKET	ATC	8256400	RL RL-0270	42	0	0	1	1	1	1	0	0	0	0	0	0	0	0

JOB: 4482 PAGE 4 REVISION #: 4 REVISION DATE:12/27/88 CUSTOMER: WMATA/SS-9 CONTRACT 121049 TITLE:750V OC METAL ENCLOSED SWITCHGEAR

WRITTEN BY:SIL DATE TYPED:05/26/88 CUSTOMER ORDER #22967PB

KINGSTON CONTRACTORS

REVISION #: 4 REV. DATE:12/27/88

Tue Dec	: 27 1988	3	CPC BILL OF MATERIAL JOB # 4482			PAGE S						. –	0	T'Y. P	ER LOC	HOLTA					
ITEM #	SYMBOL	P.O.# &	DESCRIPTION	MFR C'CODE	TYPE & CATALOG #	CLASS CPC 1.0.#	QTY.			٠,			u 6	NIT/CU 7	BICLE	NO. 9	10	11	12	13	14
														<u> </u>							
35	186	4482•Z 3	TIMER SOCKET RETAINING CLIP	ATC	03190250600	RL RL-0271	42 .	0	0	1	1	1	1	0	C	0	0	0	0	0	0
36	102	4482•Z 4	CAM TIMER, REPEAT CYCLE, 120V AC MOTOR 15 SEC/REV, 4 REV/MIMUTE, 6 SWITCHES, RING TERMINALS FOR INCOMING CONNECTIONS	ATC 062	324C 06A3ER1A01S	RL RL+0272	42	0	6 , 0	1	1	1	1	0	0	0	0	0	0	0	0
37	LMR	4482-AA 1	LOAD MEASURING RESISTOR, 15 OHM, GRID TYPE, RATED 50 AMPS AT 750 VDC DESIGNED FOR A CONTINUOUSLY REPEATING DUTY CYCLE OF 1 MIN. ON 30 MIN. OFF	GUYAN	15H5QA	BR - 005	42	0	0	1	1	1	1	0	0	0	0	0	0	0	0
38	150	4482-W 1	RELAY, DC OVERCURRENT, HALL EFFECT SENSOR OPERATED 125V DC CONTROL POWER	88C 062	76T 20602240	RL RL-0273	36	0	0	1	0	1	1	0	0	0	0	0	O	0	0
39	DCCT	4482-W 2,4	HALL EFFECT DC SENSOR, 4000 AMP WITH 610178 CABLE	89C	4000-6 609544-K2	CT - 123	32	0	0	1	0	1	0	0	0	0	0	0	0	0	0
40	DC CT	4482-W 3,4	HALL EFFECT DC SENSOR, 5000 AMP WITH 610178 CABLE	BBC	5000-8 608768-T5	CT CT-124	4	0	0	0	0	0	3	0	0	0	0	0	0	0	0
42		4482-s 1	LUG, COMPRESSION, 2 HOLE PAD, COPPER, 1000 MCM	BURNDY 064	YA YA44-2N	LG LG-036	218	0	0	5	5	5	7	0	0	0	0	0	0	0	0
43	TERM.BX	1 4482-P	TERMINAL BLOCK, 12 POINT, WITH COVER AND MARKING STRIP	MARATHON	1500H 1512H	TB TB-041	A.R.	0	0	0	0	0	0	0	0	0	0	0	0	0	0
44		4482-P 2	TERMINAL BLOCK, 8 POINT, WITH COVER AND MARKING STRIP	MARATHON	1500H 1508H	T8 T8-029	A.R.	0	0	0	0	0	0	0	0	0	0	0	0	0	0
45		4482-R 1	TERMINAL BOARD, 6 STUD	G.E. 015	EB-4 2860351G3	TB TB-031	50	1	1	1	1	1	1	0	0	0	0	0	0	0	0

JOS: 4482 PAGE 5 REVISION #: 4 REVISION DATE:12/27/88

CUSTOHER:WHATA/SS-9

JOB: 4482

TITLE:750V DC METAL ENCLOSED

WRITTEN BY:SIL DATE TYPED:05/26/88

CONTRACT 121049 KINGSTON CONTRACTORS

SWITCHGEAR . CUSTOMER GROER #22967PB REVISION #: 4 REV. DATE: 12/27/88

Tue De	c 27 1988	3	CPC BILL OF MATERIAL JOB # 4482	- 		PAGE 6							0	T'Y. P	ER LOC	ATION					
ITEM #	SYMBOL	P.O.# &	DESCRIPTION	MFR	TYPE &	CLASS	QTY.	_		3		s		NIT/CU 7			•••				
		1TEM		C'CODE	CATALOG #	CPC 1.0.#		'	•	3	•	,	6	•	8	9	10	11	12	13	14
46		4482-N 1	PULLOUT FUSE BLOCK, 2 POLE, 250V, 30 AMP	FPE 014	C30-2	FU FU-023	209	4	4	4	4	5	4	0	0	Ó	0	0	0	0	0
47	FUSE	4482•G 3	CONTROL FUSE, CLASS R. 30 AMP, 250 VOLT	GOUL0 013	FT F1-30	FU FU- 138	200	4	4	4	4	4	4	0	0	0	0	0	0	0	0
48	FUSE	4482-G 4	CONTROL FUSE, CLASS R, 15 AMP, 250 VOLT	GOULD 013	FT F1-15	FU FU-139	51	0	0	1	1	2	1	0	0	0	0	0	0	0	0
49	FUSE	4482-G 5	CONTROL FUSE, CLASS R, 10 AMP, 250 VOLT	GOULD 013	FT-10	FU FU- 140	104	2	3	2	2	2	2	0 .	0	٥	0	0	0	0	0
50	HTR	4482-J 1	STRIP HEATER, 120V AC, 125 WATT	CHR'LOX	PT PT-512	AC-0222	50	ı	1	1	1	1	1	0	0	Ö	0	0	0	0	0
51	M.THERM	1 4482-K 1	THERMOSTAT, ADJUSTABLE, 22 AMP MAX RESISTIVE, SPST	DAYTON	DPST ZE206	AC AC-0019	9	. 0	0	0	0	1	0	0	0	0	0	0	0	0	0
52	кам	4482-AZ	AMMETER, 0-15 AMP, 2-1/2" SQUARE (HEATER LOAD)	LFE 058	AH19390000	AP AMAP-075	9	C	0	0	0	1	0	0	0	0	0	0	0	0	٥
53	11	4482-AH 1	ISOLATION TRANSFORMER, 1:1 RATIO, 600V, 10KV BIL, 150 VA	171 058	465 465 • 120	CT CT+125	42	0	0	1	1	1	1	0	0	0	0	0	0	0	0
54		4482•X 1	PULLOUT FUSE BLOCK, 1000 VOLT DC, 63 AMP, 1 POLE	CARBONE 014	\$120 £97041	FU FU•141	4	0	1	0	0	0	0	0	0	0	0	0	0	0	0
55		4482-X 2	PULLOUT FUSE BLOCK, 1000 VOLT DC, 63 AMP, 2 POLE	CARBONE 014	\$1120 L97070	FU FU-142	42	0	0	1	1	1	1	0	0	0	0	0	0	0	0

PAGE 6 REVISION #: 4 REVISION DATE: 12/27/88 CUSTOMER: WATA/SS-9 CONTRACT 121049

JOB: 4482

TITLE:750V DC METAL ENCLOSED SWITCHGEAR.

WRITTEN BY:SIL DATE TYPED:05/26/88 CUSTOMER ORDER #22967PB

KINGSTON CONTRACTORS

REVISION #: 4 REV. DATE: 12/27/88

Tue De	27 1988	3	CPC BILL OF MATERIAL JOB # 4482			PAGE 7							Q	1'Y. P	ER LOC	RO1 TA					
ETEM #	SYMBOL	P.O.# &	DESCRIPTION	MFR	TYPE &	CLASS CPC 1.0.#	QTY.					5	U 6	NIT/CU	BICLE	NO. 9	10	11	12	13	14
		ETEM		C,CODE	CATALOG #	CPC 1.0.#				,	•	,	ь			7	10	"	12		
56	FUSE	4482-G 1	FUSE, 1000V DC, 20 AMP	GOULD 013	101 A100P20	FU-143	4	0	1	O	0	0	0	0	0	0	0	0	0	0	0
57	FUSE	4482-G 2	FUSE, 1000V DC, 50 AMP	GOULD 013	101 A100P50	FU-144	42	0	د' 0	1	1	1	1	0	0	C	0	0	0	0	0
58		4482-AR 1	#14 AVG, CONTROL WIRE, 600V, 90 DEGREE C, TYPE SIS	CO191. 027		WI WI-009	A.R.	0	0	G	0	0	0	0	0	0	0	0	0	0	0
59		4482-AG 1	#6 AMG, CONTROL WIRE, 600V, 90 DEGREE C, TYPE SIS	COMM. 027		WI WI -041	A.R	0	0	0	0	0	0	0	0	0	0	0	0	0	0
60		4482-88 1	#12 ANG, CONTROL WIRE, 1KVDC MIN.	CCHM. 027		wt -036	A.R.	0	0	0	0	0	0	0	0	Ò	0	0	0	0	0
61		4482-AX 1	#8 AMG, CONTROL WIRE, 1XVOC MIN.	COM1. ·		WI WI-037	A.R.	0	0	0	0	0	0	0	0	0	0	0	0	0	0
62		4482-M 1-6	CLIP SLEEVE WIRE MARKERS, VARIOUS LETTERS AND MUMBERS	BRADY	SCN	AC AC-0204	A.R.	0	0	0	0	0	0	0	0	0	0	0	0	0	0
. 63		4482∙L 1	THERMAL SLEEVING, \$/8", 1200 DEGREE F.	COLEFLEX 040	C F240-5/8	AC AC-0223	A.R.	0	0	0	0	Đ	0	0	0	0	0	0	0	0	0
64		4482-Н 1	KNIFE SWITCH, 125V DC, SINGLE THROW, 30 AMP	FILNOR	A-1102	AC AC-0210	50	1	1	1	1	1	1	0	0	0	0	C	0	0	0
65	100	4452-8R 182	TRUCK OPERATED CELL SWITCH FOR GEC - HSNP BREAKER	СРС	3798-0391	BR - 024	50	i	1	1	1	1	1	0	0	0	O	0	0	0	G

REVISION #: 4 REVISION DATE: 12/27/88 PAGE 7

CUSTOHER: UNATA/SS-9
CONTRACT 121049

TITLE:750V DC METAL ENCLOSED SWITCHGEAR -

WRITTEN BY:SIL DATE TYPED:05/26/88 CUSTOMER ORDER #22967PB

KINGSTON CONTRACTORS

CONTRACTORS REVISION

REVISION #: 4 REV. DATE: 12/27/88

Tue De	c 27 198	8	CPC BILL OF MATERIAL JOB # 4482			PAGE 8							Q.	r'Y. Pi	R LOC	HOLTA					
ITEM #	SYMBOL	P.O. # &	DESCRIPTION	MFR	TYPE &	CLASS	QTT.			•			U	IT/CUI	BICLE	NO.					
	*	LTEM		C.CODE	CATALOG #	CPC 1.D.#		1	2	3	4	5	6	7	8	9	10	11	12	13	14
66	CAP	4482-AH 1	SURGE CAPACITORS, 0-750 VOLT	G.E.	181443	LA-021	42	0	0	1	1	1	1	0	0	0	0	0	Ó	0	0
67	30010	4482-B 1	DICOE, 6 AMP, 400 VOLT	WEST.	R34 R3400406-8019	AC AC-0224	84	0	é <u>0</u>	2	2	2	2	0	0	0	0	0	0	0	0
68		4482-AJ 1	STAND-OFF INSULATOR, 1-1/2 INCH HIGH FOR ITEM 66	GLASTIC	2015-3A	8U 8U-134	168	0	0	4	4	4	4	0	6	0 .	0	0	0	0	0
69		4482-AD 1	KEY INTERLOCK	KIRK	FOE	AC AC-300	16	1	1	0	0	0	0	0	0	0	0	0	0	0	0
70		4482-AT	NEMA TYPE ENCLOSURE WITH PANEL (FOR ITEM 22)	BOFFMAN	NEMA I AZGNIGA	EN EN•197	4	0	. 1	0	Ó	0	0	0	0	٥	0	0	0	0	0

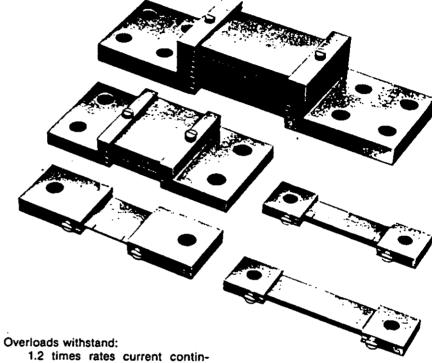
PAGE 8 REVISION #: 4 REVISION DATE: 12/27/88

JOB: 4482

Shunts 880 Series

Designed and manufactured to give maximum reliability in arduous conditions, these heavy duty shunts provide an accurate d.c. millivoit signal suitable for ammeter indicators, overload protection and control devices. Standard outputs are 50mV and 100mV, other voit drop values are available.

- Accuracy class 0.25
- Ratings up to 10,000A.
- Riveted and soldered construction.
- Long term stability.
- In-line busbar mounting.
- Shock and vibration tested.



Construction

Highest quality materials, rugged design and advanced manufacturing techniques are used throughout. The substantial solid brass end blocks have conservatively rated contact surface area. For maximum long term stability and strength, manganin resistance elements are both riveted and hard soldered into slots in the end blocks.

Above 2000A, end blocks are multi-bladed. Model 886 accepts ¼ in. (6.35mm) busbars as standard and other sizes must be specified.

For current ratings of 30A and below, base mounted shunts should be used if the manganin element could be subject to damage due to flexing.

Specification

880 Series complies with BS89, IEC51 and A 1042 where appropriate.

Accuracy class: 0.25
Class 0.2 available on request.

1.2 times rates current continsuously.

5 second ratings: 40A-500A = 10 times

501A-2000A = 5 times 2001A-10,000A = 2 times rated

Temperature coefficient: 0.002% per °C overall.

Ambient temperature:

calibrated for 20°C, the working range is -20°C to +60°C.

Temperature rise:

corectly mounted in freely circulating air, temperature rise will not exceed 90° C.

Maximum load:

for maximum accuracy, load should not exceed 0.1% of the shunt current rating.

Shunt leads:

Supplied separately in pairs to ANSI C30.1. Standard length 5 ft. (1.52m) Resistance 0.065 ohms with hard soldered brass terminals and non-flammable drip proof insulation.

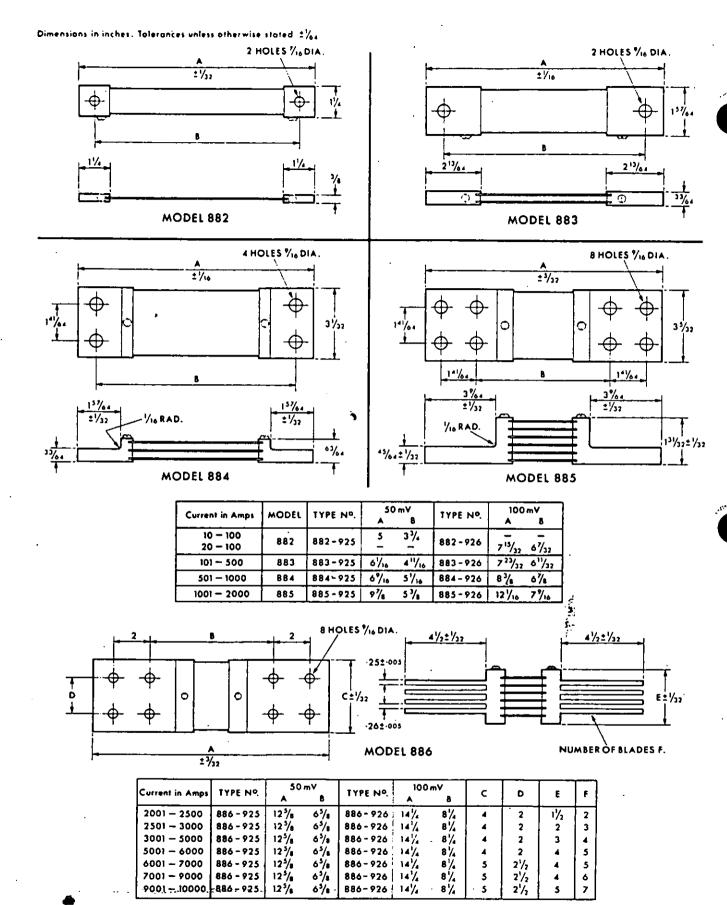
Installation

For maximum heat dissipation, mount shunts in the horizontal plane, with the blade faces vertical. Utilize the full end block contact surface area. Ample ventilation should be provided. Busbars should be adequately rated, clean and level, with a thin coat of silicone grease applied to the contact surface area. Use M10 (5/16 in.) fixing bolts with model 882 and M12 (½ in) for all other shunts. Use flat and tension washers under the nuts and tighten fully.

Insulated mounting blocks are available for models 882, 883 and 884. Dimensions on request.

Safety at Work

Shunts are uninsulated and protection against accidental contact may be necessary.



All potential terminals for shunt leads are 10-32 UNF Slotted Pan head screws with washers, Information contained in this publication is correct at time of publication but the right is reserved to supply products

INSTRUMENTS

MIDWEST:

CROMPTON INSTRUMENTS INC. 2763 HIGGINS ROAD, ELK GROVE VILLAGE, ILLINOIS 60007

TELEPHONE: (312) 593-1107 TELEX: 28-0540
WEST COAST: CROMPTON INSTRUMENTS INC. 1562A PARKWAY LOOP, TUSTIN, CALIF. 92680
TELEPHONE: (714) 731-2333 TELEX: 69-2309
OTHER LOCATIONS IN: CANADA, AUSTRALIA, ENGLAND, SCOTLAND; HOLLAND, AND SINGAPORE

INSTALLATION INSTRUCTIONS

D.C. MOVING COIL AMMETERS AND VOLTMETERS

MOUNTING

Cut and drill panel as indicated in Fig.1. All drilling and wiring on the switchboard should be completed before mounting the instrument, and it is desirable to defer mounting as long as possible to reduce the risk of accidental damage to the front cover of the instrument while work is proceeding on the switchboard.

After mounting, correct any pointer deviation from zero by means of the zero adjuster.

WIRING

Connect the instrument as shown in the appropriate diagram overleaf. Terminal studs should be tightened sufficiently to ensure good contact but should not be over-tightened. The use of wrenches with over-long handles is, for this reason, deprecated.

The efficient magnetic screening of these instruments makes it unlikely that they could be affected by stray fields, but due precautions should be taken in keeping wires carrying heavy currents as far away from the instrument as is possible.

GROUNDING

On a metal panel which is itself grounded the instrument's fixing studs will securely ground its case provided care is taken to obtain a good metallic contact through any paint on the rear surface of the panel. On non-metallic panels, one of the fixing studs should be connected to ground.

AMMETERS

Direct-connected ammeters may be used on all loads up to and including 30 amps. For higher currents use an external shunt with a suitably-scaled 50mV ammeter indicator.

VOLTMETERS .

Voltmeters may be direct-connected up to a maximum of 800 Volts, and must be protected by fuses.

MOVING COIL RECTIFIER INSTRUMENTS

For these A.C. instruments use the connection diagrams shown on page 16.

SHUNTS

A shunt dissipates the heat generated by the passage of current more by conduction and convection than by radiation. It is therefore necessary that the ends of shunts and of the conductors connected to them are of such cross-section and of such contact area as to prevent any undue temperature rise.

Where he shunt is built up of a number of strips of metal, cooling is best effected when the shunt is mounted horizontally with the strips in a vertical plane. If the shunt has to be mounted vertically with one terminal above the other, then the positive terminal should be the lower since, owing to the Peltier effect, the terminal at which the current enters the shunt will normally develop more heat than the other terminal.

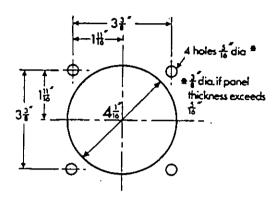


Fig.1. Panel drilling plan. For instrument dimensions see pages 11 and 12.

SHUNT LEADS

These are supplied with the instrument; standard length 5 ft. with resistance of 0.065 ± 0.01 ohm. They must not be cut and any excess length should be coiled and taped upclose to the rear of the instrument. If the purchaser supplies shunt leads their resistance must agree with that quoted for the standard leads. Leads longer than 5 ft. can be supplied to order. If particularly long leads are unavoidable it may be necessary to use shunts and indicators of 100mV ratings; the maximum lead resistance is approximately 0.25 ohm for 50mV ratings and 1 ohm for 100mV ratings.

SHUNT LEAD COMPENSATING RESISTANCE

Alternatively, ammeter indicators can be supplied fitted with adjustable shunt lead compensating resistors to enable the indication to be adjusted to its true value on site. METHOD OF ADJUSTMENT. The indicator is marked with its mV rating and with its instrument plus leads resistance value. This is the total resistance of the indicator and shunt leads (with shunt disconnected) at which a true indication will be obtained. With the shunt disconnected a resistance bridge should be connected across the shunt end of the leads; after setting the bridge to the resistance value marked on the indicator, the rheostat on the indicator should be adjusted until a zero deflection is obtained on the bridge galvanometer. Alternatively, if a resistance bridge is not available, a standard millivoltmeter should be connected across the shunt ends of the leads, with the shunt disconnected. With a low adjustable D.C. voltage source connected across the shunt ends of the leads, the voltage should be adjusted until the indication on the milliammeter agrees with the mV rating marked on the indicator. The rheostat on the indicator should then be adjusted to the point where the indicator reads full scale.

CLEANING

Before wiping or cleaning the outer surface of the front cover, all dust should be carefully brushed off to avoid any scratches on its surface.

Any superficial scratching which the plastic windows may sustain can be removed by careful use of a proprietary acrylic polishing agent. Care should be taken to avoid contacting plastic windows with spirit-based liquids as this would cause severe crazing.

COVER REMOVAL

Extreme precautions are taken in the factory to prevent the ingress of any dust into the interior of the instrument. Similar steps must be taken should it be necessary to remove the front cover of the instrument for any reason, The following procedure should be observed:-

- 1. On no account should the cover be removed in circumstances where ferrous particles however minute could conceivably enter the interior.
- 2. Every precaution should be taken to avoid the entry of dust. The operation should be carried out in reasonably dust-free conditions, and free from draughts or crosscurrents of air.
- 3. When the cover is removed it should immediately be placed, inner surface downwards, on a clean sheet of paper, so that no dust can settle on its inner surface. Care should be taken not to rub or even touch the inner surface so as to avoid damage to the anti-static treatment applied at the factory.
- 4. Should it be necessary to leave the cover off the instrument for any length of time, the instrument should be screened from dust by being placed in a clean dustfree bag or container, preferably transparent. Care

- should be taken in doing this to avoid damaging the exposed pointer, dial, etc.
- 5. The cover must be replaced carefully, to ensure that the pin on the zero adjuster engages properly with its slot in the zero adjuster arm on the top cross-bar of the instrument mechanism.

REP AIRS

These instruments have 'Hi-Q' taut band suspended movements: see pages 5 & 6 for full details. They have no pivots, jewel bearings, spiral control springs, or pneumatic or magnetic damping arrangements to sustain damage or wear in use, and it is extremely unlikely that they will ever need servicing or repair. Should any instrument suffer such gross mechanical or electrical abuse as to affect its operation it should be returned to the manufacturer for attention. The assembly and adjustment of the mechanism can be carried out only on jigs specially designed for the purpose, and on no account should repairs be attempted by any other personnel, however skilled.

CONNECTION DIAGRAMS

REAR VIEW OF INSTRUMENT IS SHOWN

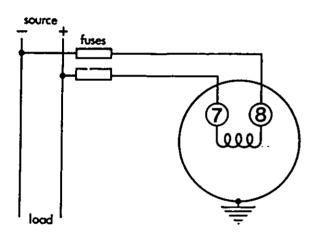


Fig.2. Direct-connected voltmeter

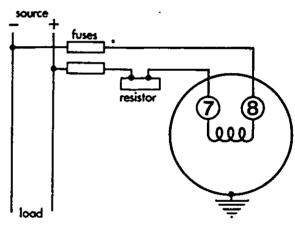


Fig.3. Voltmeter, over 750 volts, with external resistor.

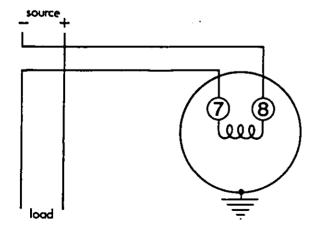


Fig.4, Self-contained ammeter.

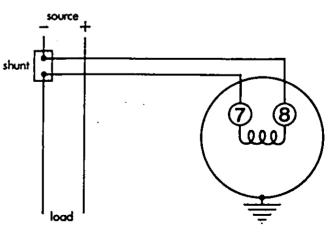


Fig.5. Ammeter indicator with external shunt.

CROMPTON INSTRUMENTS

MIDWEST:

CROMPTON INSTRUMENTS INC. 2763 HIGGINS ROAD, ELK GROVE VILLAGE, ILLINGIS 60007

WEST COAST:

TELEPHONE: (312) 593-1107 TELEX: 28-0540 CROMPTON INSTRUMENTS INC. 1562A PARKWAY LOOP, TUSTIN, CALIF. 92680 TELEPHONE: (714) 731-2333 TELEX: 69-2309

OTHER LOCATIONS IN: CANADA, AUSTRALIA, ENGLAND, SCOTLAND, HOLLAND, AND SINGAPORE

Crompton Instruments

ECHNICAL DATA

D.C. MOVING COIL AMMETERS AND VOLTMETERS

GENERAL

These 4½ and 9in, square flange flush mounting switchboard instruments have a pointer deflection of 250 degrees and a scale length of 6.8 and 14in, respectively. They incorporate the most advanced form of Hi-Q oil-damped taut band suspension (Crompton patent) which completely eliminates pivots, jewel bearings, and spiral control springs. The built-in shock-absorbers, which are a prime feature of the Hi-Q system, give these instruments a phenomenal resistance to external shock and vibration and an unrivalled accuracy maintenance in service. For full details of the Hi-Q damping concept see pages 5 & 6, but attention is particularly called to the figures quoted overleaf for Damping Factor, Overshoot, and Response Time, all of which are substantially better than the requirements of ANSI C39.1 - 1981.

MAGNETIC SYSTEM

The self-shielding magnetic system comprises a yoke, outer pole piece, and inner core, all of soft iron, together with two magnets located in slots in the yoke. The magnets are of the anisotropic pattern; i.e. they are made from a special alloy the main constituents of which are iron, nickel, cobalt, and aluminum; in the casting process, the molten alloy is subjected to a strong magnetic field and, as it solidifies, the magnetic domains in the alloy remain aligned in the same direction.

MOVEMENT

The magnetic components are held rigidly between two heavy gauge aluminum plates. The moving coil is secured by brackets to the insulated moulded spindle "is arranged so that one of its longer sides moves in the gap between the core and outer pole-piece of the magnet system.

he moving element is of unique design. A strip of metal ribbon soldered to an accurately centered locating plate is moulded into both ends of the spindle. To this spindle are attached the pointer, balance arm, two damping pads, and the moving coil. Both the ribbon and the metal locating plate are divided in the center, thus enabling the top and bottom sections of the ribbon to be used to conduct the current into and away from the moving coil.

This form of construction eliminates the mechanical joints used in the common form of taut band movement which has separate ribbons attached to each end of a metal staff, and thus adds considerably to the ruggedness of the movement. The self-shielding magnetic system enables the instrument to be mounted at will on either ferrous or non-ferrous panels.

The dial plate has a platform scale on which the graduations are in the same plane as the tip of the pointer, thus eliminating parallax errors in reading.

TOP CROSS BAR TOP TENSION SPRING __ STOP PLOS TOP BAMPING PAR ZERO ADJUSTER LIN POLETER TOP LICAMENT SALANCE ARM MOAINO MO MOULDED SPINDLE MOVING COM SOTTOM DAMPING PAD (MOYING) . MAGNET PLUG MARKET SYSTEM POLYPROPYLERE MIRRERS 80TT8# CR025EAR BOTTOM DAMPIES PAD BOTTOM TERSION SPRING Fig. 1. Exploded view of movement.



The complete mechanism is mounted on a moulded baseplate into which captive 10-32 terminal studs, $1\%_4$ in, long, are fitted. This assembly is housed in a heavy gauge pressed steel barrel with a square top flange which carries the integral %-28 fixing studs. Rubber washers on the mechanism fixing screws and polypropylene buffers on the periphery of the magnet system provide additional protection against external shock and vibration.

The front cover which carries the zero adjuster is secured to the flange of the barrel by screws in its four corners. It is therefore possible to remove the cover to obtain access to the dial etc. without having to take the instrument off the panel.

Where it is desirable to prevent zero adjustment by unauthorised persons, the cover can be supplied undrilled without a zero-adjuster button. Access to the zero-adjuster arm on the mechanism can then be obtained by removing the front cover from the instrument in situ.

A supplementary pre-set pointer can be fitted to the cover. Adjustable from the fernt, this can be used to mark a selected point on the scale.

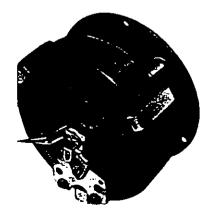


Fig. 2. The top aluminum fixing plate has been removed from this movement to show details of the magnet system.

SELF-CONTAINED RANGES

Microammeters.

200 microamps (min.) 500 microamps.

Milliammeters, Ammeters

Any desiled range from 1 mA up to 30 amps, in decimal multiples of the progression 1, 1.5, 2, 3, 4, 5, 6, 8. Voltmeters

Any desired range from 50 mV up to 800 volts, in decimal multiples of the progression 1, 1.5, 2, 3, 4, 5, 6, 8.

APPROXIMATE TERMINAL RESISTANCES

	Microammeters	٨	Ailliammeters .
Range	Resistance, ohms	Range	Resistance, ohms
		1	400
,	•	5	20
200	1.200	10	5
500	200	20	2.5
		50	2

For ranges over 50 mA, and up to the maximum of 30 amps, the movement coil has an internal shunt.

Ammeter Indicators: for use with external shunt. Standard rating is 50 mV, 10 mA, at full-scale deflection, resistance 5 ohms. 100 mV or other ratings can be supplied to order. Voltmeters: standard resistance for ranges 1 volt and over is 1000 ohms per volt. Other sensitivities to order.

MOVEMENT TECHNICAL DATA

Weight of moving element, grm	8.0
Torque for full-scale deflection, grm/cm	0.2
Ampere-turns for full-scale deflection	0.4 .
Moving coil pole air gap, inches	094
Flux density, lines per sq. cm1	800

PERFORMANCE

When tested in accordance with ANSI C39.1 - 1981.

Accuracy Class	1 Percent
----------------	-----------

Overload Capacity:-

-Ammeters: 1000% momentarily, 100% for 15 minutes, and 50% indefinitely,...

-Voltmeters: 25% indefinitely.

RECTIFIER PATTERN, FOR USE ON A.C.

These instruments can be supplied fitted with full-wave rectifiers and calibrated for use on A.C. These instruments have high sensitivity and low power consumption, and are suitable for use on frequencies up to 10kHz.

Sensitivity: milliammeters, approx. 1 to 1.5V drop at FSD voltmeters, 5 volts and over, 1000 ohms per volt.

Accuracy Class: 2.0

Self-contained Ranges:-

- -Milliammeters: min. 1 mA, max. 200 mA.
- -Ammeters, with internal C.T.: 0.5, 1, 2.5, 5, 10, 20, or 30A
- -Voltmeters: min. 5 volts, max. 800 volts.
- -Voltmeters with internal P.T.: 0.25, 0.5, 1, 1.5, or 2 volts Preferred Scalings: decimal multiples of the progression 1, 1.5, 2, 3, 4, 5, 6, 8.

SHUNT LEADS

D.C. Ammeter Indicators when supplied with external shunts are provided with shunt leads 5 ft. long, having a resistance of 0.065 ± 0.01 ohm. These leads are to be considered as part of the indicator, the two being calibrated together. Longer leads can be supplied to order.

SHUNT LEAD COMPENSATING RESISTOR

Indicators can be supplied fitted with an adjustable shunt lead compensating resistor on the terminal baseplate. By this means, an installation having leads of non-standard resistance can be adjusted on site to give a true indication on the instrument of the current flowing in the circuit.

SPECIAL FEATURE AVAILABILITY





Fig. 3

Fig. 4.

SUPPRESSED ZERO INSTRUMENTS

D.C. instruments can have mechanically-suppressed zeros, the maximum degree of suppression being 20% of full-scale value.

EXPANDED SCALE D.C. VOLTMETER Fig. 3.

By the use of inbuilt zener diodes the lower 80% of the scale range can be compressed, without loss of the zero, point, giving a scale shape as shown in Fig. 3. This f ure can be provided on any D.C. voltmeter from 0-3-7 w upwards but not on rectifier pattern A.C. instruments.

POT-LINE VOLTMETERS Fig. 4. (High-shock, 800 series)

Special voltmeters can be supplied for use in smelter plants to withstand conditions of high ambient temperature and strong magnetic fields. Other features include compressed lower scale and built-in continuous overload protection of ten times full-scale value.

OTHER MODIFICATIONS

The following are available to order:-Center or offset zero. Dials in colors other than white. Colored lines or segments on scale. Additional set of figures on one scale. Additional scale on same (flat) dial. Flat dial with finely-divided scale and knife-edged pointer. Captions other than standard electrical unit designation. Captions in languages other than English. Customer's name or logo on dial. Calibration in terms of non-electrical quantities, including applications where the required correspondence between scale intervals and deflection force is non-linear. Non-reflecting finish on windows. Heavily-damped movement. Sealed panclimatic case. (41/2in. size only, 800 series)

For installation instructions see pages 19 & 20.



Publication R-5443PB



THE GENERAL ELECTRIC COMPANY LIMITED

ST. LEONARDS WORKS . STAFFORD . U.K.

TYPE VAE21 FRAME LEAKAGE RELAY FOR HIGH RESISTANCE EARTH FAULTS RELAY TYPE VAE21
FRAME LEAKAGE RELAY FOR
HIGH RESISTANCE EARTH FAULTS

APPLICATION

Structures or frames, such as those surrounding rectifiers or rectifier supply busbars, can become accidentally 'live' due to faults. Such frames, nominally insulated from earth, can be bonded together and connected to earth by an earth bar. For such schemes, protection against earth faults has often been provided by the main system overcurrent relays, but measurement of current or voltage to earth can ensure faster, more sensitive protection.

A typical scheme for low resistance earth fault protection is described in Publication R-5252.

High resistance faults between frame and earth develop high voltages, which are dangerous to personnel and to equipment. Main system overcurrent relays would be insensitive to such faults, but the type VAE21 relay will detect high resistance faults; it has the following features:

- Suitable for protection of a.c. and d.c. systems
- Fast operation
- Continuously monitors the voltage between the protected structure and earth
- * Continuously monitors the protective circuits
- Limits fault currents
- Initiates alarms
- * Disconnects power sources from the fault

OPERATION

The relay is connected in two separate paths between the protected structure and earth, as shown in the simplified diagram, Figure 1.

Relay element 64X is a continuously energised voltage monitoring device. An a.c. supply is fed via a transformer to a bridge rectifier in the relay. The bridge rectifier output circulates via: normally closed (break) type contacts 64C-2 and 64C-1, the protected structure, relay coils 64C and 64X in series, and earth, back to the rectifier. This d.c. voltage energises relay 64X but is too low to operate relay 64C.

A short circuit between the protected structure and earth, separate from the relay paths, will short-circuit the relay coils. Relay 64X will be de-energised, operate its flag or target, and operate contacts for alarm initiation.

A break in the connections between the protected structure and earth, or an a.c. supply failure, will also de-energise relay 64X, causing contact operation for alarm indication, plus flag operation.

If the protected structure becomes accidentally live due to a fault, the voltage between the structure and earth will increase and operate relay 64C. This will open contacts 64C-1 and 64C-2 and operate other contacts to trip the power supply to the rectifier and to initiate alarms. The operation indicator flag will also operate. Circuit components limit fault currents to a safe value.

After a fault, the flag indicator and the hand reset contacts of the tripping relay must be reset. The isolating contacts in the supply to the incoming transformer must be operated by hand to interrupt the monitoring supply and allow the tripping relay contacts and operation indicator to be reset.

TECHNICAL DATA

VOLTAGE RATINGS

Auxiliary supply, monitoring voltage, a.c. input: 110/125V, 50Hz or 60Hz, or 230/250V, 50Hz or 60Hz.

The relay will withstand up to 1000 volts a.c. r.m.s. or 1000 volts d.c.

SETTINGS

Single, preset voltage at which monitoring relay 64X operates: 20V or 50V or 70V (d.c. or r.m.s. a.c. 50Hz or 60Hz).

RELAY BURDENS

Depends upon applied voltage, contacts etc., but typically is less than 10VA d.c. or a.c.

CONTACTS

Relay 64C is a VAA13 relay, and has up to 4 hand reset contacts: 64C-1 and 64C-2 are break (normally closed) contacts, plus one make and one break contact, and hand reset operation indicator.

Relay 64X is a VAA11 relay and has up to 4 self reset contacts, normally two make and two break type, and a self reset operation indicator.

OUTPUT CONTACT RATINGS

SYSTEM	MAKE AND CARRY CONTINUOUSLY	MAKE AND CARRY FOR 3 SECONDS	BREAK
o.c.	1250VA with maxima 5A and 660V	7500 VA with maxima 30A and 660V	1250VA with maxima 5A and 660V
d.c.	1250W with maxima 5A and 660V	7500W with maxima 30A and 660V	100W (resistive) 50W (inductive) with maxima 5A and 660V

CASES

The relay is supplied in a size 1 double ended drawout case (1D.DE), suitable for flush or projection mounting, finished bright black as standard.

Relays for use in exceptionally severe environments are finished to BS2011:20/50/56 at extra cost. Standard relays are finished to BS2011:20/40/4, and are satisfactory for normal tropical use.

CASE DIMENSIONS

Case Size	Height	Width	Depth *
1D DE	237 _{mm}	173mm	198mm

^{*} Plus 21mm for maximum length of M5 screw terminals. Dimensioned drawings of case outlines, panel cutouts and mounting details are available on request.

INFORMATION REQUIRED WITH ORDER

Case finish and method of mounting.

Auxiliary a.c. voltage and frequency.

Suggested monitoring voltage, d.c.

Protective voltage setting a.c. or d.c.

Maximum voltage that structures could attain, i.e. protected equipment voltage to earth.

Number and type of contacts required on relay elements 64C and 64X.

Maximum value of fault current attainable on protected equipment.

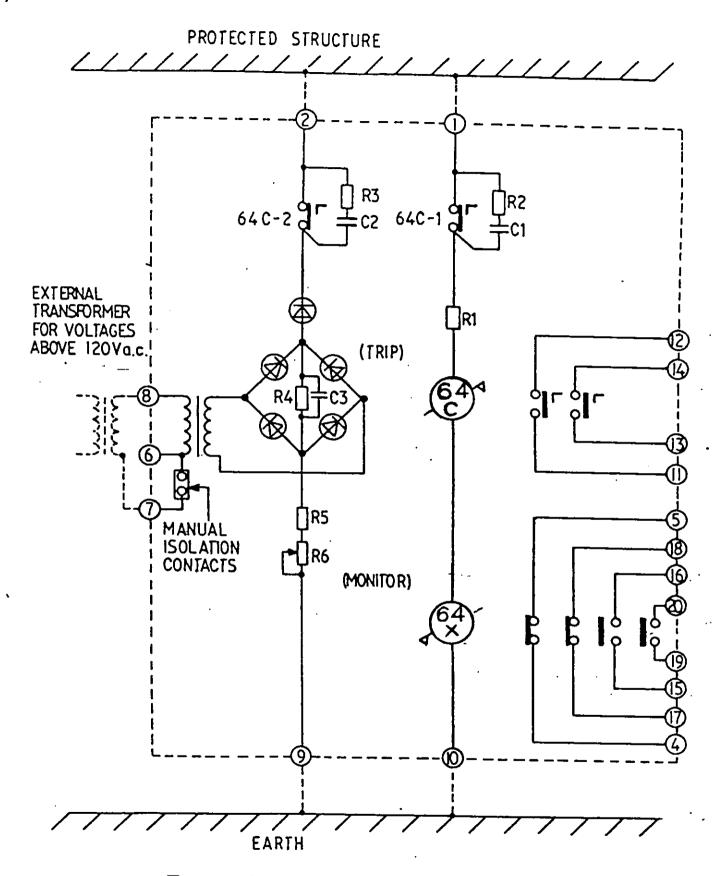
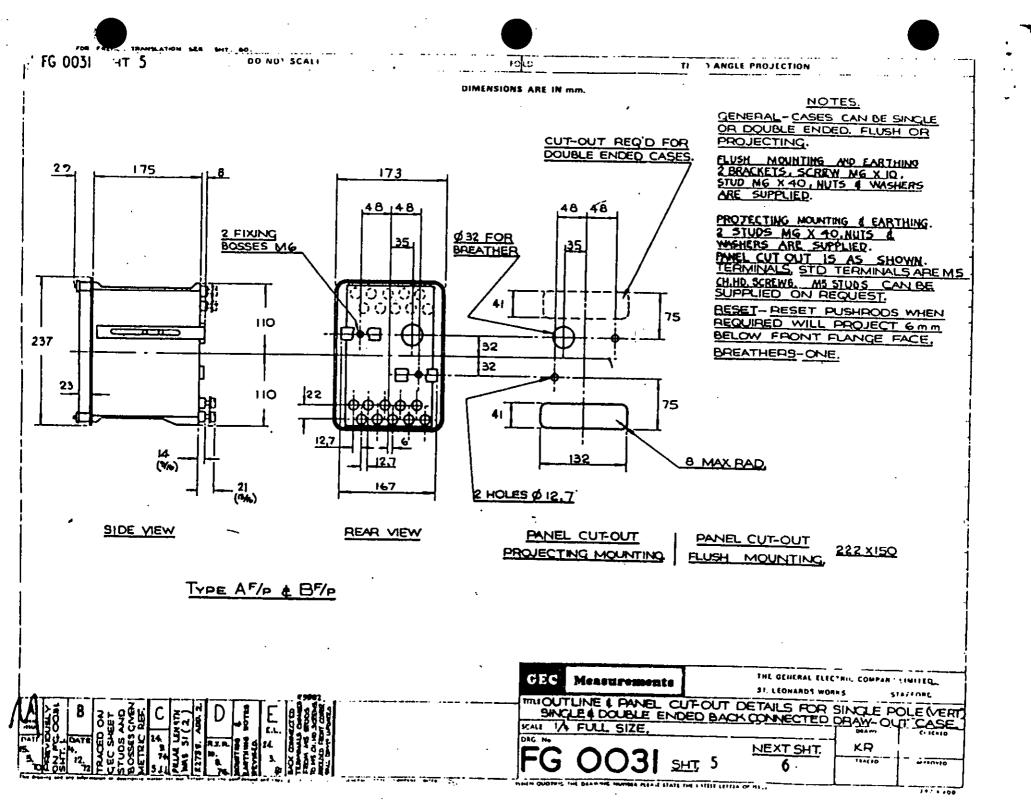


Figure 1 HIGH RESISTANCE EARTH FAULT RELAY

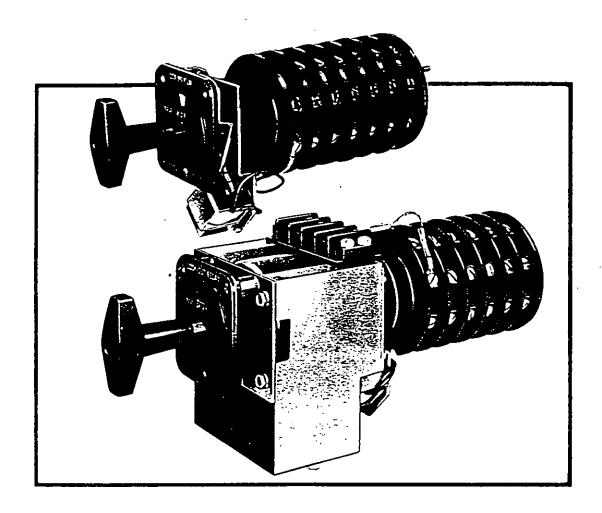


Technical Publication

LOR-1

Effective April 15, 1987

HIGH SPEED MULTI-CONTACT LOCK-OUT RELAYS FOR POWER INDUSTRY APPLICATIONS





HIGH SPEED MULTI-CONTACT LOCK-OUT RELAYS FOR POWER INDUSTRY APPLICATIONS

ELECTROSWITCH Weymouth, Massachusetts

ABSTRACT

The series 24 Lock-out Relays are highspeed (eight milliseconds) control relays used primarily as auxiliary relays in appliused primarily as auxiliary relays in applications requiring many contacts (up to forty). The LOR is an electric-trip and manual-reset device. The LOR/ER is an electric-trip and either manual or electric-reset. The LOR/SR is an electric-trip and self-reset device. All units have mechanical position indicator targets. They are qualified to ESC-STD-1000 which includes aging and seismic vibration requirements to AMSI/IEEE 323-1964 and ANSI/IEEE-344-1975 for class IE uses in nuclear power generating stations. The testing also satisfies ANSI/IEEE C37.90-1978 and AKSI/IEEE C37.98-1978.

INTRODUCTION

Lock-out Relays of various types are often used in the electrical power industry. These auxiliary relays are electric-trip, manual or electric reset control relays for the purpose of tripping and locking out circuit breakers or other devices automatically when a fault or other predetermined condition exists. The lock-out relays are generally used in conjunction with differential relays to protect transformers, buses, and rotating machinery in various electrical systems.

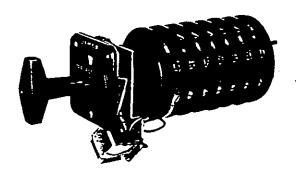


Fig. 1. Series 24 LOR Manual-reset Lock-out Relay

Initial Release - September 15, 1977

Revised - January 3, 1980

Added LOR/SR - February 1, 1983

Revised - March 15, 1985 Revised - April 15, 1987

Lock-out Relays of known types often have ten or more NO and NC contacts. The relays can be programmed to change sequences such as shutting down a faulty pump and then initiating the action to start-up a standby pump or bypassing a faulty circuit by opening and closing breakers.

Known relays of this type are normally latched in the RESET position and trip-out to a TRIP position when commanded. There are then manual-reset, electric-reset, and self-reset versions to get back to the RESET position.

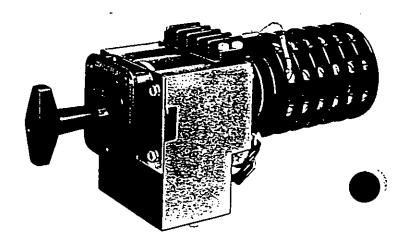


Fig. 2. Series 24 LOR/ER Electric-reset Lock-out Relay and LOR/SR Self-reset Lock-out Relay

High-speed, rugged, multi-contact units are needed. This paper describes a family of Lock-out relays with up to forty contacts that operate as quickly as eight milliseconds and are seismic shockproof.

BASIC CIRCUIT OPERATION

The control of the Lock-out Relays for operation as a relay requires no special wiring. They only require a NO contact (S1) to command the LOR to TRIP and the electricreset LOR/ER needs an additional NO contact (S2) to initiate the command for RESET. The choice of S1 should take in consideration the burden data of trip coil, LOR/T, since SI will "make" this current. This circuit is self-interrupting with the LOR contacts so SI need not be concerned with the "break" of the TRIP circuit. On the electric-reset LOR 52 needs to make only the KI relay circuit so the burden of LOR/R does not effect S2. Any pilot duty device is acceptable for both \$1 and \$2.

The LOR schematic is shown on Fig. 3.

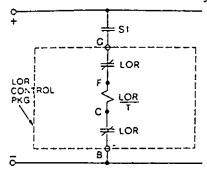


Fig. 3. Manual-reset LOR Control Circuit (shown in RESET position)

The standard station control bus voltage is used. The LOR, as shown, is in the RESET position. The LOR/T coil form represents the linear solenoid that releases a trigger that locks the LOR in the RESET position when the trigger is activated. The mechanical design is described later under THE ELECTRO-MECHANICAL DRIVE.

The LOR contacts shown are normally closed in the reset position. They are within the LOR control package. G and B are tie points to connect the LOR to the control circuit. C and F are internal connection points shown for information.

To command the Lock-out Relay to TRIP, S1 is closed. This completes a circuit across the LOR trigger solenoid, which operates, causing the device to snap to the TRIP position. It locks into this position and remains there indefinitely. When this happens, the LOR contacts open thereby removing the control circuit from the bus.

The unit will stay locked-out in the TRIP position until manually reset. Sl may be any kind of auxiliary contact -- from a breaker, a protective relay, or from another auxiliary device like a relay. The condition of the Lock-out Relay is visible by the handle location and a mechanical target within the nameplate (Black for RESET, Orange for TRIP).

Electric-reset LOR/ER Circuit

The LOR/ER schematic is shown on Fig. 4.

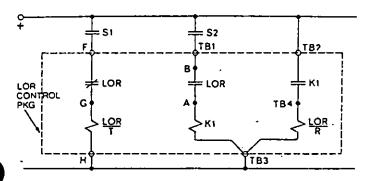


Fig. 4. Electric-reset LOR/ER Control Circuit (shown in the RESET position)

The electric-reset Lock-out Relay operates from the control bus voltage like the manual-reset version. The LOR/ER, as shown, is in the RESET POSITION. The LOR/T coil form is the same linear solenoid that is used in the manual-reset LOR, and controls the trigger that locks the LOR/ER in the RESET position. The LOR/R coil form represents the rotary solenoid that is used to reset the LOR/ER electrically. KI is a relay used to control the rotary solenoid. This enables S2 to be a low level contact. It controls only the KI relay coil. The KI contact operates the high current rotary solenoid. TB1, TB2, TB3 are terminal block contacts, and F and H are LOR tie points -all are for connection to the control bus. G, B, and TB4 are internal tie points shown for information.

The command of the LOR/ER to the TRIP position is the same as with the manual-reset LOR which was previously described. When tripped, the NC LOR contact in the LOR/T circuit opens removing LOR/T solenoid from the circuit. When this happens, the LOR NO contact in the Kl relay circuit closes enabling this circuit to be used.

To command the LOR/ER to reset, S2 is closed. This completes the circuit to the K1 relay and it operates closing contact K1. This completes the circuit to the LOR/R rotary solenoid and it indexes to the RESET position. When this happens, the NO LOR contact opens. This opens the circuit on the K1 relay coil. K1 relay drops out opening contact K1 that opens the rotary solenoid LOR/R circuit. At the same time the NC LOR contact, in the linear solenoid LOR/T circuit, closes, setting up the LOR/ER for the next TRIP command.

S1 and S2 should be momentary contacts and should not stay closed. If both contacts are closed at the same time, a "pumping" action will result with the LOR/ER indexing back and forth between the RESET and TRIP positions.

The handle and target indicators are the same on the standard electric-reset LOR/ER as the manual reset LOR. The handle on the high-speed LOR/ER is not an indicator and remains in the vertical position and the target must be manually reset (see page 9).

Self-reset LOR/SR Circuits

The self-reset Lock-out Relay operates from the control bus voltage like the LOR and LOR/ER. The LOR/SR, as shown in Fig. 5 and 6, is in the RESET position. The LOR/T coil is the same linear solenoid that is used in all LOR's, and controls the trigger that locks the LOR/SR in the RESET position. The LOR/R is the same rotary solenoid used in the LOR/ER and is used to electrically reset the LOR/SR. Kl and K2 are two relays with NO contacts used in the control circuit. B-A is a NO contact and E-F-G is a form C contact -- both in the control circuit. F-G is NC in the reset position while F-E is NO. TB1, TB2, TB3, and TB4 are terminal block connection points for the user. Rl and R2 make up a bridge circuit

on both the INSTANTANEOUS RESET and the TIME DELAY RESET units. In addition the TIME DELAY RESET version has an additional lE-IF normally open (NO) contact to isolate the K2 coil plus the time delay circuit consisting of R1 and C1-C2-C3-C4 which are wired in parallel. D1 protects the capacitors from a possible incorrect polarity hookup.

The INSTANTANEOUS RESET version of the LOR/SR will reset itself within 80 milliseconds after the fault has cleared itself (Sl opens). This circuit is illustrated in Fig. 5.

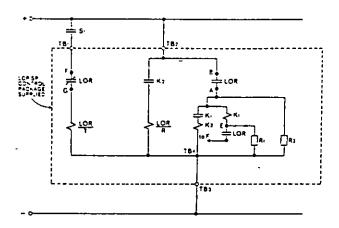


Fig. 5. Instantaneous-reset circuit for the self-reset (shown in RESET position) Lock-out Relay

The LOR/SR trips in the same manner as the manual-reset LOR. With Sl closed (simulating the commanded or fault condition) B-A contact closes and E-F contact closes. In this manner E-F and A-B are both connected to the (+) bus so the Kl coil sees no voltage difference and cannot operate. Therefore, the LOR/SR will not reset and may remain in the TRIP position indefinitely while the RlR2 bridge draws only enough milliamps to maintain the voltage balance of the bridge -- and well below the dropout current of any 0.2 amp. target relays that may be part of the circuit.

When S1 opens (indicating the fault or predetermined condition has cleared), the R1R2 bridge becomes unbalanced since the E-F contact, although closed, is in the S1 contact circuit. K1 operates, closing contact K1 and K2 operates, closing contact K2 and the rotary solenoid LOR/R operates and indexes to the RESET position completing the cycle.

Contact E-F, and A-B then open dropping out relays K1 and K2 (and their contacts). Contact F-G closes setting up LOR/SR for the next command.

The TIME DELAY SELF-RESET (shown in RESET position) version of the LOR/SR, illustrated in Fig. 6, operates in the same manner as the instantaneous reset version except the R3-C1-C2-C3-C4 circuit causes a time delay of from 300 to 600 milliseconds from the time S1 opens until the LOR/SR contacts reclose.

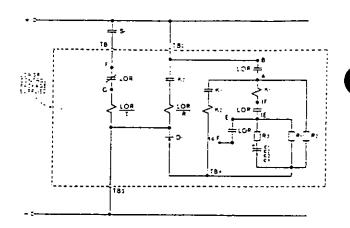


Fig. 6. Time-delay self-reset circuit for the LOR/SR

Operating Voltage

The LOR, LOR/ER, and LOR/SR Lock-out Relays are direct current actuated auxiliary relays. Because they are only actuated for short periods of time and are self-interrupting, they may be subjected to maximum design voltage indefinitely without exceeding 50°C temperature rise in ambient conditions as high as 55°C. This is using class 105 insulation and the applied thermocouple method of temperature determination.

The Lock-out Relays operate reliable over the full voltage ranges described i ANSI/IEEE C37.90-1978, the "Standard for Relays and Relay Systems Associated with Electric Power Apparatus."

These ratings are shown on Table I.

TABLE !
Coil Operating Range

COIL	NOMINAL VOLTAGE	NORMAL VOLTAGE OPERATING RANGE
A.B	24VDC	19.2 to 28VDC
C	48 VDC	38.4 to 56VDC
D,E,G	125VDC	100 to 140VDC
F,H	250VDC	200 to 280VDC

The trip and reset solenoid coils provide reliable operation over a wide latitude of operating conditions. Trip coils A, B, C, D, E, and F have substantial overlapping voltage ranges enabling some "custom-fitting" depending on desired speed versus current burden. Trip coils G and H have controlled threshold voltage levels to insure that the unit will not trip at half-voltage. G and H coils are useful where cummulative stray voltages due to capacitive and other effects might be impressed on the LOR coil causing occasional nuisance trips.

The full voltage ranges are shown on Tables II and III.

The Threshold Voltage shown is the minimum level that can produce a TRIP operation. This is not a reliable operation and this voltage level should not be normally used. The normal operation should be within the limits of the Operating Range.

The Operating Range represents the design limits for reliable operation. Safety factors are included so operation can occur above and below the indicated range as previously explained.

TABLE II
Trip Coil Voltage Data

		•	-
COIL	NOMINAL VOLTAGE	THRESHOLD VOLTAGE	OPERATING RANGE
A	24VDC	6VDC	10 - 40VDC
В	24VDC	9VDC	18 - 50VDC
С	48VDC	12VDC	24 - 70VDC
0	125VDC	16VDC	30 · 140VDC
E	125VDC	23VDC	45 · 140VDC
F	250VDC	33VDC	70 - 280VDC
G	125VDC	70VDC	90 - 140VDC
Н	250VDC	140VDC	180 - 280VDC

TABLE III Reset Coil Voltage Data

COIL	NOMINAL VOLTAGE	OPERATING RANGE
Α	24VDC	19.2 to 28VDC
С	48VDC	38.4 to 57.6VDC
D	125VDC	100 to 150VDC
F	250VDC	200 to 275VDC

Coil Burden Data

The LOR, LOR/ER, and .LOR/SR solenoid coil burden data is outlined in Table IV.

As previously explained, the control bus needs to be able to supply the burden detailed in Table IV but does not need to interrupt it — the units are self-interrupting. The reset coil is hard wired to the control bus so the actuating means (S2 on Fig.4) is not subjected to the burden (only the K1 coil burden at less than 1 ampere. S1 controlling the trip coil does "make" and carry the trip coil current.

TABLE IV
Coil Burden Data

		TRIF	COIL	RESE	T COIL
COIL	COIL CIRCUIT VOLTS	COIL CIRCUIT DC OHMS @25°C	BURDEN (AMPS) AT RATED VOLTAGE	COIL CIRCUIT DC OHMS @25°C	BURDEN LAMPS. AT RATED VOLTAGE
A	24VDC	3.3	7.3	.7	33.8
В	24VDC	7.7	3.1	-	
C	48VDC	13.0	3.7	3.0	15.9
D	125VDC	27.0	4.6	12.4	10.1
E	125VDC	50.0	2.5	1	
F	250VDC	104.0	2.4	80.6	3 1
L G	125VDC	27.0	4.6		
Н	250VDC	104.0	2.4	-	

Trip Coil Current - Voltage Characteristics

The trip coils may be used over a wide range of voltage levels as previously described. To aid in this selection Fig. 7 graphs the voltage/current characteristics of the trip coils. These values are the same for the manual-reset LOR, the electric-reset LOR/ER, and the self-reset LOR/SR Lock-out Relays. Fig. 7 is used with the Response Time graph of Fig. 8. Target selection data is detailed on Table V and VI and Fig. 9 to 12.

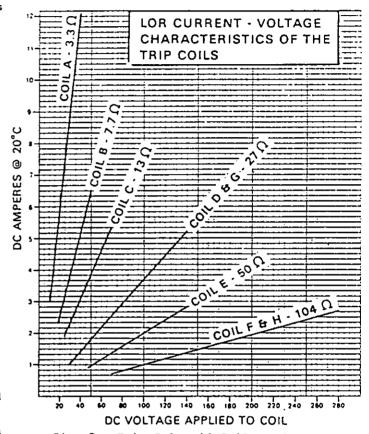


Fig. 7. Trip Solenoid Coil Burden Data

TABLE V

LOR Trip Coil Selection for Positive Target Operation

Operating	LOR Trip Coil	LOR Trip Coils to Use				
DC Volts	-2A Target	2A Target				
24	A.B.C	i				
48	B.C.D.E	<u>_</u>				
100	D,E,F	!				
125	D.E.F.G	D				
140	D.E.F	0				
190 !	F	1 0				
250	F,H	l o				

TABLE VI
Minimum Required DC Voltage for Positive Target Operation with Manual-Reset LOR

LGP no accitional TRIP circuity (Target) COLL - ZA L64 ZA ZA Z5			24 Target resistor (PD) in parallel 25 Ohms (50 Ohms)		24 Target P-C Circuit 40 20 MFD MFD		24 Target Series Resistor (Rs) 7 12.3 16.7 Onms Onms Coms			
5	12	1,2	:2			-			92	50
C	2,	35	٠٠.٤		80	95	:05	95		
£	.,	.,,		75 70	105 125				!	1
G F	90 180									1

Response Time - Trip Solenoid

Fig. 8 shows the high-speed response of the Lock-out Relays. The values given are total response to close NO contacts. The values are for ten deck LOR's and eight deck LOR/ER's and LOR/SR's. There is very little difference in smaller units. The response time of the trip coil of the high-speed electric-reset Lockout-relays is the same as the manual-reset LOR's.

Response Time - Reset Solenoid

The reset time of the electric-reset LOR/ER Lock-out Relays is generally not an important applications consideration so a graph has not been prepared. The response is approximately fifty milliseconds at rated voltage for all coils. The reset times of the self-reset LOR/SR is described on page 3.

Target used with Lock-out Relays

All the Lock-out Relays have a mechanical target as part of the nameplate --Black for RESET and Orange for TRIP. This indicates the condition of the LOR. The target resets when the LOR resets (with the exception of the high-speed trip electricreset LOR/ER and self-reset LOR/SR where the memory target is manually reset).

External targets may also be used in conjunction with the LOR's to show the condition of the devices that are being controlled. The most common .2A targets operate satisfactorily with any LOR. .6A targets are also generally satisfactory. 2A targets need special attention. Selection of LOR trip coils are shown in Table V with minimum required DC voltages for positive target operation shown on Table VI.

2A targets are generally slow acting. The response time of the LOR's is generally too fast for them to respond. From Tables V and VI it is seen that only trip coil D will respond and only at 118VDC or more. In order to use 2A targets at lower voltages suggested circuits have been

TABLE VII
Target Relay Coil Characteristics

Tests based on following		TARGET	
Target coil characteristics	.2A	.6A) 2A
Coil resistance (ohms)	8.15	.71	.195
Pull-in current (amps)	.15	.45	1.75

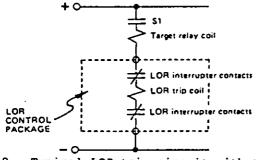


Fig. 9. Typical LOR trip circuit with target relay coil in series with LOR coil

developed. The standard circuit with no additional circuitry is shown on Fig. 9 for comparison. Fig. 10 to 12 are shown as suggested solutions. Table VI shows the minimum voltages to apply with these circuits to get positive 2A target operation.

These circuits were developed using target relays with coil characteristics shown on Table VII.

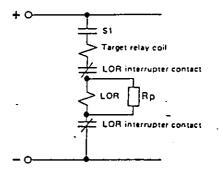


Fig. 10. LOR trip circuit with resistor (Rp) in parallel with LOR trip coil (not supplied with LOR -- see Table VI for recommended values)

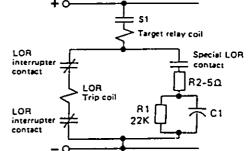


Fig. 11. LOR trip circuit with RC network -momentarily connected with LOR coil
increasing current in 2A target. Cl
discharges through Rl when LOR is
reset. See Table VI for recommended
values of Cl. Order special LOR

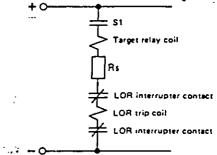


Fig. 12. LOR trip circuit with series resistor (Rs) chosen to reduce trip coil wattage. Value chosen to obtain 5 amperes for 5 milliseconds or longer through target relay coil. See Table VI for recommended values

Transient Protection

The LOR, LOR/ER, and LOR/SR Lock-out Relays are designed and tested to operate reliably in a normal power industry environ ment. This includes being subjected to transients on the control bus up to 3.5KV. Since the LOR is normally isolated from the



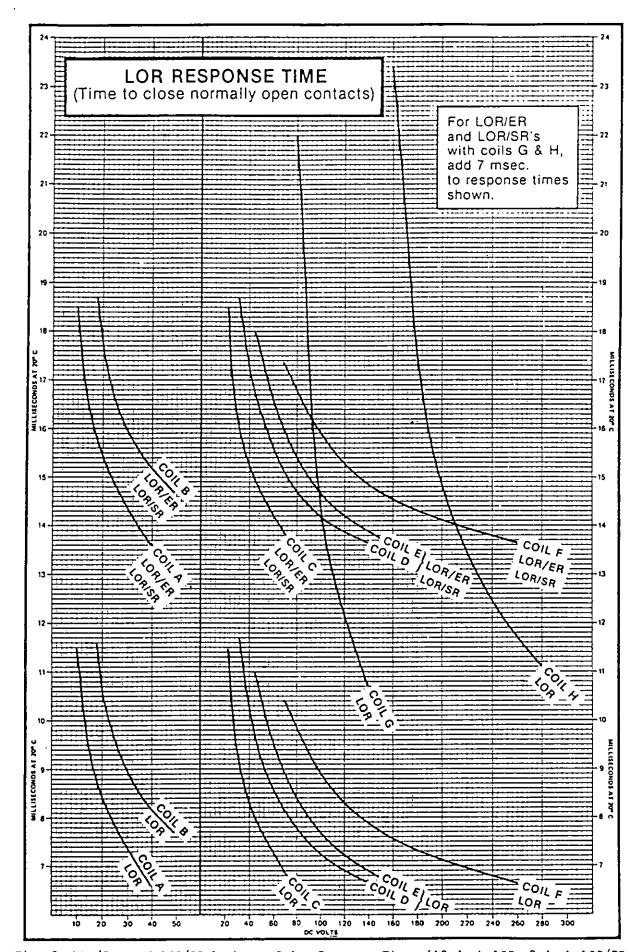


Fig. 8. LOR/ER, and LOR/SR Lock-out Relay Response Times (10 deck LOR. 8 deck LOR/ER. or LOR/SR). For high speed LOR/ER or LOR/SR's, use LOR response times.

bus, it will experience transients only if they occur in the operating mode. This precludes the possibility of a detrimental, accumulating affect over the life of the unit. As such, no transient protection is needed.

Because of the nature of the operation of the solenoid coils, the LOR does generate transients that may be of interest to the user. These transients are less than 2KV and generally in the 1.5KV to 1.8KV range.

BASIC RELAY CONTACTS

The LOR, LOR/ER, and LOR/SR Lock-out Relay contacts operate on the original, reliable principle of knife switches --double sided, double-wiping, spring wiper blades closing on both sides of a terminal. To provide a closed contact, two terminals are bridged or shunted. Fig. 13 shows this contacting arrangement.

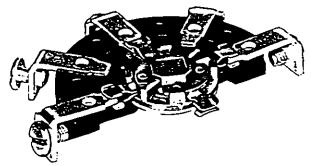


Fig. 13. Double-sided, double wiping knife-type contact configuration

Contact Materials

The wiper blades are made from a phosphor-bronze alloy that combines superior spring qualities with good electrical conductivity. This material and blade design has been proven by extensive laboratory testing as well as more than thirty years of field use and experience. Initially used in rugged naval ship applications, it is also used in industrial applications such as railroad locomotives and earth moving equipment. It has been used for more than thirty years in power industry applications, as well.

The blade assembly is shock-proof and virtually bounce-proof. This makes it ideal for high-speed, quick-make, quick-break devices like the LOR, LOR/ER, and LOR/SR.

The blades are formed, assembled, and riveted nearly closed. The gap is machine adjusted to provide a uniform high pressure. The gap does not change with time and use. Normal use tends to improve the contact surfaces due to the rubbing action. This provides a burnishing as well as cleaning action.

The contact surface conductivity is enhanced by a silver overlay stripe that lasts the life of the unit. This ensures a good contact even in those cases where the LOR, LOR/ER, and LOR/SR is not operated for long periods of time.

The terminals are made of electrically and environmentally compatible copper material with a silver overlay stripe at the contact area plus an overall silver plate to ensure a lastingly good contact surface focustomer wiring purposes. Similarly, therminal screws are made from silver-plated brass.

Number of Decks Available

Table VIII shows the maximum number of decks and contacts available for reliable operation:

TABLE VIII * MAXIMUM DECKS AVAILABLE

LOR TYPE		MAXIMUM CONTACTS
LOR LOR/ER-HI SPEED TRIP LOR/ER-STD SPEED TRIP LOR/SR INSTANT RESET LOR/SR TIME DELAY RESET	10 10 8 8	40 40 32 32 28

Contact Deck Arrangement

The blade and terminal configuration enables the use of multi-contacts in the same deck, and simple stacking procedures enable the fabrication of many independent contacts in one relay. Specifically, two NO contacts and two NC contacts are provided in each deck, and up to ten decks can be stacked, resulting in a relay with up to forty contacts (twenty NO and twenty NC). The deck arrangement is illustrated in Fig. 14.

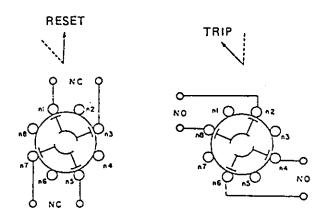


Fig. 14. Basic LOR Deck Layout

The illustration of Fig. 14 is for the first deck. For multideck units the second digit of the terminal number is the same as shown but the first digit changes to denote the deck number. As an example, terminal 82 is in the eighth deck, directly under terminal 12 and used together with terminal 88.

Contact Charts

The previous illustration shows how the LOR's are constructed and is shown as information for the user. Traditional contact charts are normally used, as shown on Fig. 15.



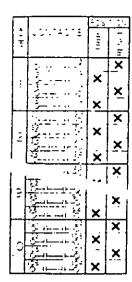


Fig. 15. LOR, LOR/ER, and LOR/SR, Lock-out Relay Contact Chart

Contact Ratings

The LOR, LOR/ER, and LOR/SR Lock-out Relays have been tested to many different circuit conditions. The interrupting ratings are based on 10,000 operations of life, using suddenly applied and removed rated voltage, with no extensive burning of contacts. Inductive ratings are based on tests using standard inductance L/R=0.04 for DC and cosd=0.4 for AC. The Interrupting Rating Column headed "double contacts" means contacts in series. Short time, and continuous atings are based on temperature rise in ontact members and supporting parts not exceeding 50°C above ambient.

Allowable Variation From Rated Voltage

The relay contacts are not sensitive to normal variations in voltage. The interrupting capacity is important as indicated in Table IX. Variations of plus and minus twenty percent in rated voltage need not be considered as long as the interrupting current is not exceeded.

TABLE IX

Contact Ratings for

Series 24 LOR, LOR/ER, and LOR/SR

Lock-out Relays

	INTERRUPTING	RATING (AMPS)	SHORT	
CONTACT	RESISTIVE	INDUCTIVE	TIME	CONTINUOUS
CIRCUIT	SINGLE.	SINGLE	RATING	RATING
VOLTS	CONTACT	CONTACT	(AMPS*)	(AMPS)
125VDC	3	1	60	30
250VDC	2	1/2	60	30
120VAC	20	15	60	30
240VAC	15	5	60	30
480VAC	10	5	60	30
600VAC	6	5	60	30

^{*}Short time current is for one minute

THE ELECTROMECHANICAL DRIVE

The switching portion of the Lock-out Relay is the field proven series 24 Instrument and Control Switch. In this application it is a two position device --TRIP and RESET. There is a powerful coil spring mechanism to drive it from the RESET position to the TRIP position. The device is held in the RESET position by a trigger locking mechanism. This is actuated by a small linear solenoid for electric tripping. The LOR is manually reset by rotating the handle against the coil springs. The LOR/ER is either manually reset or electrically reset utilizing a separate rotary solenoid mechanism. The LOR/SR is self-resetting when the tripping condition has been removed. These mechanisms are described below.

The TRIP Mechanism (Patent No. 3649793)

Industry requirements for Lock-out Relays include:

- . high-speed
- . seismic shock-proof
- . multiple contacts

To get the multi-contact feature and maintain positive and rugged action, heavy spring action is required. This requires a locking mechanism to hold a spring wind-up of forty inch pounds of torque. To get high-speed release a solenoid is needed. Ordinarily a large solenoid is required to do this. Large solenoids are inherently slow so a small linear solenoid is used to release the latch. By nature small solenoids do not develop much torque so a mechanical advantage is needed.

The trigger mechanism was invented to provide the mechanical advantage. One pound of force from the linear solenoid releases the latch that locks the device against forty inch pounds of torque. The trigger uses the principle of coincident radii of two rollers -- one cannot roll without the other. The two rollers are shown in Fig. 16.

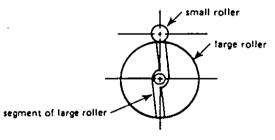


Fig. 16. Relationship of two rollers with coincident radii

The relationship of roller sizes is to get the mechanical advantage needed. Since only a small part of the larger roller is needed, a segment was cut out to reduce size and inertia.

Fig. 17 shows the small roller, large roller segment, and their relationships with the linear solenoid and the relay operating shaft.

As shown the trip mechanism is in the RESET position. This was done by rotating the handle [and relay shaft (1)] clockwise against the relay shaft stop pin (2). When the roller arm (3) [and the small roller (4)] clear the large roller segment (5), the retaining spring (6) positions the large segment (5) against the stop pin (7).

The handle and shaft (1) is now released, allowing the roller arm (3) to spring return counterclockwise until the small roller (4) comes to rest on the large roller segment (5). When the two rollers contact, the mechanical force generated acts along coincident radii (common centerline). Neither roller can rotate; the LOR is locked and reset.

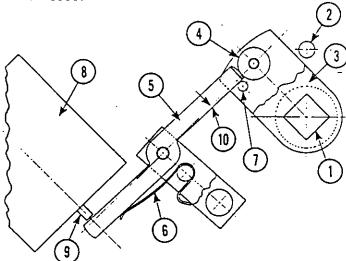


Fig. 17. LOR Trip mechanism

To initiate a TRIP action the linear solenoid (8) is actuated. The solenoid push rod (9) provides a one pound release force to the large roller segment (5) moving it by the release distance (10). When this happens, the roller arm (3) is free to rotate counterclockwise to the TRIP position where an internal stop mechanism stops the rotation.

The RESET Mechanism

The manual reset LOR is reset by manually turning the relay handle clockwise to the RESET position where it locks in. The electric-reset LOR/ER is either manually reset the same way or electrically reset using the solenoid circuit previously described. The LOR/SR self-resets with a solenoid circuit similar to the LOR/ER.

The HIGH-SPEED-TRIP Electric-reset Mechanism

The high-speed TRIP electric-reset or self-reset Lock-out Relay has two features used to accomplish a reliable tripping action in less than eight milliseconds:

 The rotary solenoid is disengaged from the relay shaft after it is used to electrically reset the device. This reduces the drag on the relay shaft enabling the high-speed TRIP. The handle always resets in the vertical position, therefore, it is not used as a position indicator. It is used only to RESET the LOR/ER or LOR/SR manually. The TARGET is the position indicator.

The mechanical target indexes to TRIP (orange) when the LOR/ER or LOR/SR trips but does not reset to black when the LOR/ER or LOR/SR is electrically reset. The target is reset manually with a lever on the face of the nameplate. This enables a station operator to observe and record the fact that the LOR/ER or LOR/SR did TRIP -- a much less expensive method than using recorders.

VERIFICATION TESTING

The series 24 LOR, LOR/ER, and LOR/SR Lock-out Relays have been tested to many different service conditions to insure that they will operate satisfactorily as general devices — not special use. For power industry applications the testing is performed in accordance with the following standards:

- ANSI/IEEE-323-1984

 Qualifying Class IE Equipment for Nuclear Power Generating Stations
- ANSI/IEEE-344-1975 Recommended
 Practices for Seismic Qualification of Class IE Equipment for
 Nuclear Power Generating Stations
- NSI/IEEE C37.90-1978

 Relays and Relay Systems Associated with Electric Power Apparatus
- ANSI/IEEE C37.98-1978
 Seismic Testing of Relays

The testing is performed in accordance with ESC-STD-1000-General Specifications for Rotary Switches and Auxiliary Relays for Utility Applications including IE Equipment Requirements for Nuclear Power Generating Stations. The tests include ratings evaluation tests, aging tests to simulate forty years operating life, and seismic tests.

Aging Tests

Aging tests are run in accordance with ANSI/IEEE 323-1984 and ESC-STD-1000 and consist of the following (run in sequence):

- 1. Visual and mechanical examination
- 2. Circuit configuration
- Dielectric Withstanding Voltage-2200VRMS
 Insulation resistance 100 megohms
- Insulation resistance 100 megohms minimum at 500VDC
- Contact resistance 10 milliohms maximum at rated current
- 6. Radiation aging 10 megarads (10^7)
- 7. Elevated temperature 120 hours at 80°C
- 8. Elevated humidity 96 hours at 95% RH 9. Temperature rise (contacts) 50°C
- maximum

 0. Aging 10.000 cycles at 20A-120VAC
- 10. Aging 10.000 cycles at 20A-120VAC
 and 3A-125VDC (both resistive)
- 11. Seismic vibration ZPA=5g
- 12. After test measurements (in order) items 3, 4, 5, 9, 2, 1



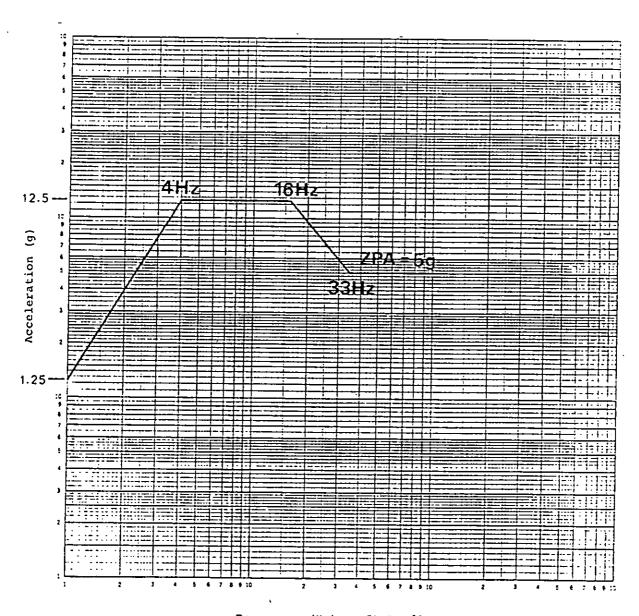
Details on the background of these tests plus the methods and procedures are outlined in ESC-STD-1000.

Seismic Tests

The series 24 LOR, LOR/ER, and LOR/SR Lock-out Relays are subjected to fragility testing in a seismic environment after aging to an accelerated life estimated to be forty years. This sequence is outlined under Aging Tests. The seismic tests are in accordance with ANSI/IEEE 344-1975 and ANSI/IEEE C37.98-1978. The tests are performed in

accordance with ESC-STD-1000. Broadband repeatable multifrequency input motions are used. The Fragility Response Spectrum (FRS) envelopes the Standard Response Spectrum (SRS) shown in Fig. 18 using a biaxial input motion.

The "g" rating of the Lock-out Relays are defined as the ZPA (zero period acceleration). The "g" rating, then, is 5g. The series 24 LOR and LOR/ER were tested in the normal RESET position, the TRIP position, and during transition from RESET to TRIP. The LOR/SR was tested in the RESET position.



Frequency (Hz) at 5% Damping

Fig. 18. Multi-frequency Broadband Standard Response Spectrum SRS)

HOW TO ORDER LOCK-OUT RELAYS

- 1. Select desired trip-coil from data on pages 4 and 6.
- 2. Select reset coil voltage from chart below.
- 3. Choose appropriate catalog number below.
- 4. Units are supplied with engraved nameplate (code 17C-2L22) unless otherwise specified.
- 5. For other than standard relays shown below (or for your own documentation purposes) complete DESIGN GUIDE (shown on pages 12, 13, 14).

MANUAL-RESET LOR

			Catal	og Numbers	for Trip-	Coils		
Decks	Coil A	Coil B	Coil C	Coil D	Coil E	Coil F	Coil G	Coil H
1	7801 A	78013	7801 C	7801 D	7801 E	7801 F	7801 G	7801H
2 -	78024	78023	7802C	7802D	7802E	7802F	7802G	7802H
3	7803A	78038	7803C	78030	7803E	7803F	7803G	7803H
4	7804A	78043	7804C	78040	7804E	7804F	7804G	7804H
5	7805A	78053	7805C	78050	7805E	7805F	7805G	7805H -
6	7806 <u>A</u>	78068	7806C	7806D	7806E	7806F	7806G	7806H
7	7807A	7807B	7807C	7807D	7807E	7807F	7807G	7807H
8	7808A	78083	7808C	7808D	7808E	7808F	7808G	7808H
9	7809A	78098	7809C	78090	. 7809E	7809F	7809G	7809H
10	781 0A	78108	781 OC	781 OD	781 OE	781 OF	781 OG	781 OH

STANDARD TRIP ELECTRIC-RESET LOR/ER

	Reset-Coil	Catalog Numbers for Trip Coils							
Decks	Yoltage	Coil A	Coil B	Coil C	Coil D	Coil E	Coil F	Coil G	Coil H
3	24 VDC	7823AA	7823BA	7823CA	7823DA	7823EA	7823FA		
5	24YDC	7825AA	7825BA	7825CA	7825DA	7825EA	7825FA		
8	24 VDC	7828AA	7828BA	7828CA	7828DA	7828EA	7828FA		
3	48VDC	7823AC	7823BC	7823CC	7823DC	7823EC	7823FC		
5	48VDC	7825AC	7825BC	7825CC	7825DC	7825EC	7825FC		
8	48YDC	7828AC	7828BC	7828CC	7828DC	7828EC	7828FC		
3	125YDC	7823AD	7823BD	7823CD	7823DD	7823ED	7823FD	7823GD	
5	125YDC	7825AD	78258D	7825CD	7825DD	7825ED	7825FD	7825GD	
8	125VDC	7828AD	7828BD	7828CD	7828DD	7828ED	7828FD	7828GD	
3	250YDC	7823AF	7823BF	7823CF	78230F	7823EF	7823FF		7823HF
5	250YDC	7825AF	78258F	7825CF	7825DF	7825EF	7825FF		7825HF
8	250VDC	7828AF	7828BF	7828CF	7828DF	7828EF	7828FF		7828HF

* HIGH-SPEED TRIP, ELECTRIC-RESET LOR/ER

	Reset-Coil	Catalog Nu	mbers for	Trip-Coils
Decks	Voltage-	- Coil-D	Coil E -	Coil F
3	125VDC	7833DD	7833ED	7833FD
5	125VDC	7835DD	7835ED	7835FD
8	125VDC	7838DD	7838ED	7838FD
10	125VDC	7840DD	7840ED	7840FD
3	250YDC	7833DF	7833EF	7833FF
5	250YDC	7835DF	7835EF	7835FF
8	250VDC	7838DF	7838EF	7838FF
10	250VDC	7840DF	7840EF	7840FF

STANDARD TRIP, INSTANT-RESET, SELF-RESET LOR/SR

	Reset-Coil	Catalog	Numbers	for Trip-	Coils
Decks	Yol tage	Coil D	Coil E	Coil F	Coil G
3	125YDC	7843DD	7843ED	7843FD	7843GD
5	125YDC	7845DD	7845ED	7845FD	7845GD
<u>8</u>	125VDC	7848DD	7848ED	7848FD	7848GD

HIGH-SPEED TRIP, INSTANT RESET, SELF-RESET LOR/SR

Decks	Reset-Coil Yoltage	Catalog Nu Coil D	mbers for Coil E	Trip-Coils Coil F
3	125 YDC	7863DD	7863ED	7863FD
5	125VDC	7865DD	7865ED	7865FD
8	125YDC	7868DD	7868ED	7868FD

STANDARD TRIP, TIME-DELAY RESET, SELF-RESET LOR/SR

	Reset-Coil	Catalog	Numbers	for Trip	-Coils
<u>De</u> cks	Voltage	Coil D	Coil E	Coil F	Coil G
3	125VDC	7853DD	7853ED	7853FD	7853GD
5	125VDC	7855DD	7855ED	7855FD	7855GD
7	125VDC	7857DD	7857ED	7857FD	7857GD

HIGH-SPEED TRIP, TIME-DELAY RESET, SELF-RESET LOR/SR

Decks	Reset-Coil Yoltage	Catalog Nu Coil D	mbers for Coil E	Trip-Coils Coil F
3	125 VDC	787300	7873ED	7873FD
5	125YDC	7875DD	7875ED	7875FD
1 7 1	125YDC	7877DD	7877ED	7877FD



	ELEC	TROSV	NITCH	SERIES 24 LOCK-OU		CATALOG NO		
)	UNIT OF ELEC Weymouth M Telephone 6	IRO SWITCH (lassachusetts (<i>CORP</i> 02188	MANUAL RESET	HIGH SPEED ELECTRIC RESET	ENGRAVING CODE:	17C-2L22	REV
	CONTACT	DIAGRAM	1	NAMEPLATE ENGRAVING		P COIL	Depth behind panel	
		POS	NOITI	LOCK-OUT RELAY		A - 24VDC	Panel thickness	
DECK	CONTACT	ra r	ESET	RESET] [3 - 24VDC	RESET CO	
\vdash	11 0-11-0		X	1 11		C 48VDC	NOMINAL VOL	TAGE
	12 041-1-0	+	 ^ 	•		0 - 125VDC	A - 24	4VDC
1	15 01-1-0		X]			
	14 0411116		 			- 125VDC	C - 48	IVDC
	онно			<u> </u>	F	- 250VDC	<u></u>	
	онню		1	CONTACT DECK		- 125VDC	[25VDC
	онно	,		LAYOUT -				:0\/D0
	очню	•		ä-ä	<u></u>	1 – 250VDC		50VDC
	어디ト			., 2~7b.;	OTHER		-	
	어디语			dry o.				
	оннь	, -		, o - o				
	어디어		$\sqcup \sqcup$	n = deck number				
	어H뇽	<u> </u>	<u> </u>					<u>.</u> .
	어디어		$\sqcup \sqcup$	CON	ITROL CIRC	UIT SCHEMATI	CS	
	어디어				shown in Ri	ESET position		
	어디어			MANUAL RESET LOR	[ELECTRIC	RESET LOR/ER	
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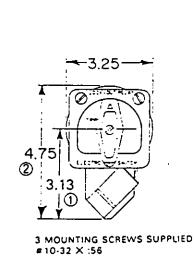
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UNIT OF ELE	CTROSWITCH CTROSWITCH CORP Massachusetts 02188 617:335/5200	SERIES 24 LOR/SR INSTANT SELF-RESET LOCK-OUT RELAY CATALOG NO. ENGRAVING 17C-2L22
	DIAGRAM	NAMEPLATE ENGRAVING TRIP COIL NOMINAL VOLTAGE Panel Thickness B - 24VDC RESET RESET RESET COIL
11 OHH 12 OHH 15 OHH 14 OHH OHH OHH OHH	0 13 X 0 18 X 0 17 X 0 16 X	C - 48VDC NOMINAL VOLTAGE D - 125VDC D - 125VDC E - 125VDC F - 250VDC CONTACT DECK G - 125VDC LAYOUT H - 250VDC
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MADE BY:	DATE:	COMPANY: DWG. NO. SHEET OF
APPROVED:	DATE:	SHEET OF

SERIES 24 LOR LOCK-OUT RELAY

CATALOG NUMBERS

7801 to 7810 SERIES



DEPTH BEHIND PANEL

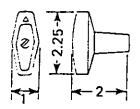
3.25
DIA.

19 MAX. PANEL

*8-32 × .25 BD. HO.

1 4.00 2 5.62 for TRIP COILS G & H

HANDLE DIMENSIONS



CONTACT RATINGS

30A - 600V continuous 20A - 120VAC

15A - 240VAC

6A - 600VAC

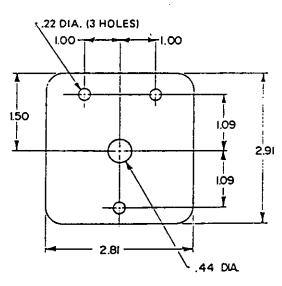
3A - 125VDC

NOTES:

Complete technical data is outlined in Technical Publication LOR-1.

Contacting and wiring diagrams are shown on specific relay drawings.

NAMEPLATE DIMENSIONS AND PANEL DRILLING



DEPTH BEHIND PANEL					
NUMBER OF DECKS	DEPTH INCHES				
1	3.63				
2	4.38				
3	4.75				
4	5,50				
5	6.25				
6	7.50				
7	8.13				
8	8.50				
9	9.25				
10	9.63				

MADE Q M	DATE: 12-4-79
APPR. KHL	DATE: 12-4-79

MASTER DRAWING

Ī	DWG. NO:	LOF	}		_	
ſ	SHEET	1	OF	1		

REw

SERIES 24 LOR/ER, LOR/SR ELECTRIC-RESET & SELF-RESET LOCK-OUT RELAYS

CATALOG NUMBERS

7821 to 7878 SERIES



3 MOUNTING SCREWS SUPPLIED # 10-32 X .56

DEPTH BEHIND PANEL

2.38

2.50

3.25

DIA.

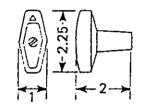
TERMINAL SCREWS SUPPLIED

#8-32 X .25 BD. HO.

1 4.06 2 6.12 for TRIP COILS G & H 3 Memory target for high-speed trip units

① 3.93 ② 5.99 for LOR/SR

HANDLE DIMENSIONS



CONTACT RATINGS

30A - 600V continuous

20A - 120VAC

15A - 240VAC 6A - 600VAC

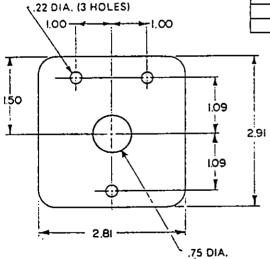
3A - 125VDC

NOTES:

Complete technical data is outlined in Technical Publication LOR-1.

Contacting and wiring diagrams are shown on specific relay drawings.

NAMEPLATE DIMENSIONS AND PANEL DRILLING



ł	DEPTH BEHIND	PANEL (INCHES	3)
NUMBER OF DECKS	HIGH SPEED TRIP LOR/ER	LOR/ER AND INSTANT LOR/SR	TIME DELAY RESET LOR/SR
3	8.00	8.00	8.63
5	9.75	9.75	10.38
7		_	11.63
8	11.63	11.63	_
10	12 00	_	

MADE am	DATE: 12-4-79
APPR. KHL	DATE: 12-4-79

MASTER DRAWING

DWG:	LOR	/ER	&	LOR/SR
SHEET	1	OF	1	

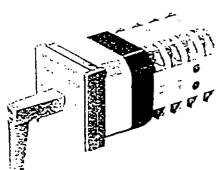
⊚

ECH # 13342 1/17/83

3

REVISIONS:

Technical Publication MIN-1



SERIES 20

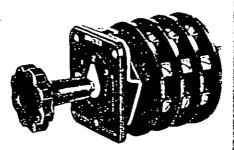
MINIATURE INSTRUMENT & CONTROL SWITCH

204-600140 T to 12 decks 2 to 24 contacts

STANDARD INSTRUMENT &

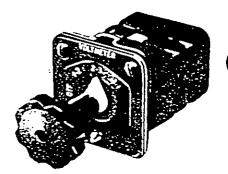
1 to 10 decks 2 to 20 contacts

Technical Publication 24-1



SERIES 24

CONTROL SWITCH 20A-120VAC | 6A-600VAC- Series 20 & 40 DIGEST



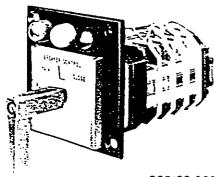
SERVES 40

CAM-ACTUATED INSTRUMENT & CONTROL SWITCH

324-600VAC

1 to 12 decks 2 to 24 contacts

Technical Publication MIN-1



SERIES 20P

LIGHTED INSTRUMENT & **CONTROL SWITCH**

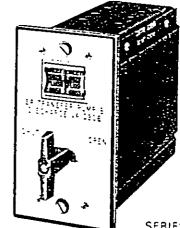
20A-600VAC

1 to 12 decks 2 to 24 contacts

POWER INDUSTRY PRODUCT

ANSI/IEEE 322-1984 (Environ Ansi/IEEE Sui 344-1975 (See Ansi/IEEE C37-90-1978 (Gen

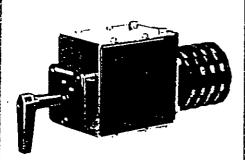
Technical Publication MOD-1



SERIES 20

PLUG-IN MODULE INSTRUMENT & CONTROL SWITCH

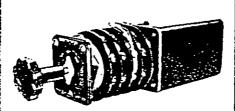
Technical Publication LSR-1



SERIES 24 LSR

LATCHING SWITCH RELAY

2 to 20 contacts 30 msec transfer time Technical Publication SSR-1

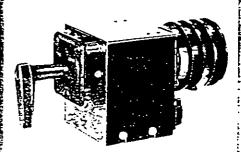


SERIES 24 SSR

ELECTRICALLY OPERATED SELECTOR SWITCH RELAY

Multi-contact auxiliary relay 2 to 8 positions

The same of the same of the same of the same of Technical Publication CSR-1



SERIES 24 CSR

CONTROL SWITCH RELAY

Replaces manual instrument & control switches 2 to 20 contacts 20A-120VAC



180 King Avenue, Weymouth, Massachusetts 02188

Telephone: 617/335/5200 • TWX: 710/388/0377



KRPA series

GENERAL PURPOSE 5 and 10 AMP MULTICONTACT AC OR DC RELAY

UL File E22575 CSA File LR15734

GENERAL INFORMATION

The KRPA is a general purpose relay enclosed in a clear polycarbonate dust cover. This UL recognized, CSA certified relay is available with either sliver contacts, rated 5 amps, or slivercadmium oxide contacts, rated 10 amps. Contact arrangements from 1 Form A (SPST-NO) to 3 Form C (3PDT) are offered.

Ruggedly constructed for long operating life, KRPA relays are ideal for many varied applications. Octal-type plug termination allows rapid installation.

For voltage or current monitoring applications, KRPA-L and KRPA-N models each have an indicator lamp which lights when power is applied to the relay coil. KRPA-L has silver contacts, and KRPA-N has silver-cadmium oxide contacts. Only KRPA-L and -N models with 120-277V AC or 110V DC coils are UL recognized and CSA certifled. Indicator lamp is not available with 25-90V coils.

ENGINEERING DATA

GENERAL

insulation: molded high dielectric material Initial insulation resistance: 1000 megohms

initial breakdown voltage: 500V rms between open contacts.

1500V rms between all other elements Temperature range: AC coils: -45°C to +55°C DC coils: -45°C to +70°C

Typical time values for DC relays (bounce time not included): Pick-up time @ Nom. voltage, + 25°C: 15 milliseconds Drop-out time @ Nom. voltage, +25°C: 10 milliseconds

Termination: 8- or 11-pin octal-type plug

Enclosure: Transparent, high-impact polycarbonate dust cover.

Approximate weight: 3 oz. (85 g)

CONTACTS

Arrangements: From 1 Form A (SPST-NO) to 3 Form C (3PDT) See Ordering Information table.

Material: Silver or silver-cadmium oxide. Consult factory for other materials.

Rating: UL Contact Ratings:

Silver contacts (codes Y & L)-all contact arrangements: 5 amps @ 120V AC; 3 amps @ 240V AC; 1/10 HP @ 120V AC; 1/6 HP @ 240V AC.

Silver-cadmium oxide contacts (codes G & N)-1 & 2 pole models: 10 amps @ 250V AC; 1/6 HP @ 120V AC; 1/3 HP @ 250V AC.

3 pole models: 10 amps @ 120V AC; 6 amps @ 250V AC; 1/6 HP @ 120V AC; 1/3 HP @ 250V AC.

Expected life: Electrical: 100,000 operations, minimum, at rated load.

Mechanical: 10 million operations, minimum.

COILS

Voltages: to 277V AC, 50/60 Hz. and to 125V DC Power @ +25°C: AC: 2 volt-amperes nominal

DC: 1.2 watts nominal

125 mW per movable arm, minimum

3 watts maximum

DC coils requiring as little as 125 mW per movable arm are available. Consult

factory.

Pick-up @ +25°C: AC: 85% or less of nominal voltage

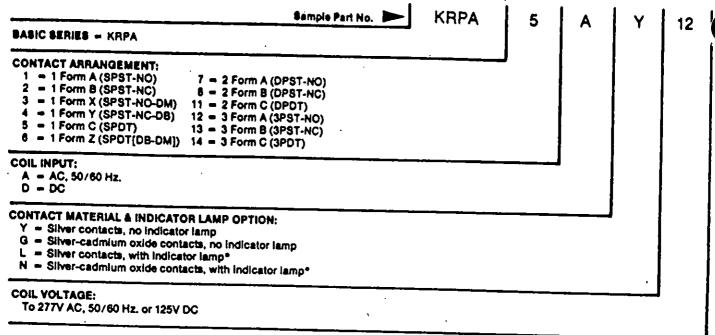
DC: 75% or less of nominal voltage

Duty: continuous

COIL DATA

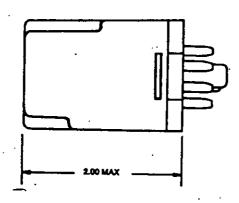
	DC COILS		AC COILS (50/60 Hz.)				
Nominal Voltage	Resistance in Ohms ± 10% @ +25°C	Nominal Current in Milliampe	Nominal Voltage	Resistance in Ohms 2 15% @ +25°C	Nominal Current in Millamps		
6 12 24 48 110	32 120 472 1,800 10,000	188 100 51 26.6 11.5	6 12 24 120 240	6 24 85 2,250 9,110	335 168 84 17.5 8.75		
220	Use 110V relay with 5W resistor in	10,000 ohm series			0.70		

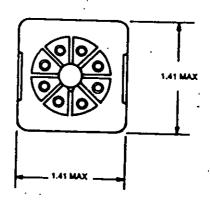
ORDERING INFORMATION



Indicator lamp is not available on models with 25-90V coils. Only 120-240V AC and 110V DC models are UL recognized and CSA certified.

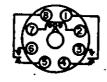
OUTLINE DRAWINGS





WIRING DIAGRAMS







KRPA 5

KRPA 11

KRPA 14

SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE. 13C207 3-82 PRINTED IN U.S.A. \$3

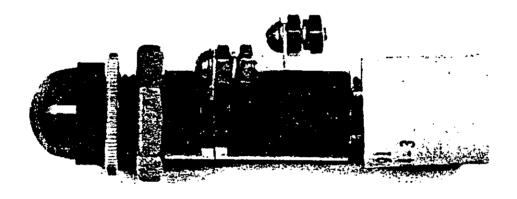


Princeton, Indiana 47671 812/386-1000 TWX: 810-350-2343 TELEX: 278451

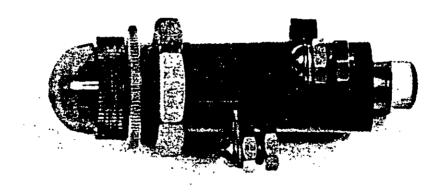


GEH-3500 B Supercedes GEH-3500 A

INDICATING LAMPS TYPE ET-16 and ET-17



ET-16 INDICATING LAMP



ET-17 INDICATING LAMP



GEH-3500

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ORDERING TABLE 7		
HOW TO ORDER		

INTRODUCTION

The ET-16 (incandescent) and ET-17 (neon) indicating lamps consist of a common receptacle, plug in type resistors and lamps, escutcheon and color cap. Available for mounting on switchboard panels up to and including 1/4 inch thickness.

APPLICATION

These lamps can be used whenever a panel mounted signal or indicating lamp is desired.

The ET-16 is available for either one brilliance, or dim bright operation. The ET-17 can be used when extra long life is a factor and brilliance is not. It also can be used when low current is desired.

FEATURES

- 1. The simple "push-twist" type plug has been adopted for both the bulb and the resistor. This was accomplished by incorporating a bayonet base on both components.
- 2. A common receptacle for both the ET-16 and ET-17 coupled with the plug-in resistor and bulb makes it easy to change on the panel without disassembling.
- 3. The resistor is in series with the bulb, and the ohmic value for the different circuit voltages is designed at 80% of the rated bulb voltage to give it longer life. Changing voltages is easily accomplished by changing the series resistor. (See listed tables for the proper resistor).
- 4. A short circuit plug is available when a series resistor is not required or if an external resistor is to be used.
- Standard GE extra-long-life bulbs are specified for all lamps. The ET-16 uses GE Cat. No. 1819 for the 24 DC lamp and GE Cat. No. 1835 for the balance of the ratings. ET-17 uses GE Cat. No. B1A.
- Terminals are readily available. They are designed for either AMP "FASTON" type connectors, solder, or screws.
- 7. Nine basic color caps designed for maximum visibility are available for ET-16: Translucent-red, green, yellow, white. Transparent-amber, red, green, blue, and clear.

ET-17: Because of the special properties of neon, only amber, transparent red, and clear lenses are suitable.

The color caps have a knurled OUTSIDE DIAMETER FOR EASY REMOVAL.

- 8. The ET-16 is also available for dim bright applications.
- 9. When special voltages or resistance is required other than those listed, a special lamp may be ordered with the proper design, or designated series resistor.
- A two inch insulating washer is supplied with each indicating light. It should be mounted on the inside of the panel as illustrated in Figs. 2,3,and 4. The function of this washer is to provide additional insulation between the terminal and ground (panel) if a surge were to be induced on one of the potential leads.

If a bulb other than those listed above is required, the lamp will be furnished less the bulb.

Listed table; give some of the specials made available.

These instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the General Electric Company.

To the extent required the products described herein meet applicable ANSI, IEEE and NEMA standards; but no such assurance is given with respect to local codes and ordinances because they vary greatly.

RATINGS

Resistors ET-16 12.5 Watts ET-17 1 Watt

BULB	DESIGN VOLTAGE	DESIGN AMPS	CANDLE POWER	AVERAGE LIFE (HOURS)
1819 1 £35 B1A	28 55 105-125	.04A .05A .3 MA	Approx34 Approx. 1.1	2500 5000 15,000

CONNECTIONS

See Figure 1A and 1b for typical tell-take and dim-bright connections.

RECOMMENDED PANEL ASSEMBLY

Thread the pal nut against the shoulder of the receptable. Install the two inch insulating washer on the front of the receptacle against the pal nut. Insert the receptacle thru the panel and thread escutcheon nut against panel. Install color cap; hand tighten (do not force). Turn escutcheon nut back up against color cap, then back off 1/2 to 3/4 turn (recommend 3/4 turn) to give at least 1/64 inch clearance but not more than 1/32 inch clearance between color cap and escutcheon nut (for up to 3/16 inch panel). For 1/4 inch panel, color cap will be flush with escutcheon nut. Tighten the pal nut against panel to 10-12 inch-pounds torque.

TABLE 1
ET-16 - INDICATING LAMP

CIRCU RATED	IT VOLT MIN.	AGE MAX.	CAT. NO. (IN- CLUDES LAMP, COLOR CAP, & RESISTOR	RESI 0165A PART NO.	OHMIC	BULB GE CAT. NO	RECEP- TACLE	COLOR CAP	CAR- TON	OUT- LINE
24 D-c 48 D-c 125 D-c 250 D-c 120 A-c 240 A-c	110 220 95	28 56 140 280 130 260	0116B6708G1 0116B6708G2 0116B6708G3 0116B6708G4 0116B6708G5 0116B6708G6	1 2 3 4 5	10 200 2000 5100 1900 4800) 1819	01168670961	SEE ORDER- ING TABLE 1	0165A9257P1	0165A7859

TABLE 2
ET-16 - FOR DIM-BRIGHT APPLICATION

RATED	JIT VOLT MIN.	AGE MAX.	CAT. NO* (IN- CLUDES LAMP, COLOR CAP, AND RESISTOR)		ISTOR A9217 RESIST OHMS TOTAL		BULB GE CAT. NO.	RE- CEP- TACLE	COLOR CAP †	CAR- TON	OUT- LINE
48 D-c 125 D-c 250 D-c 120 A-c 240 A-c	110 220 95	56 140 280 130 260	0127B8108G1 0127B8108G2 0127B8108G3 0127B8108G4 0127B8108G5	1 2 3 4 5	6000 2450	50 1700 4400 1600 4200	1835	0116B6709 63	SEE ORDER- ING TABLE 1	0165A9257	0165A9216

TABLE 3
ET-17-INDICATING LAMP

VOLTAGE RANGE A-c/D-c	CAT. NO.* (INCLUDES LAMP, COLOR GAP, AND RESISTOR)	RESIS 0165A PART NO.		BULB GE CAT. NO.	RE CEP- TACLE	COLOR CAP	CARTON	OUTLINE
110-139 140-219 220-299 300-374 375-449 450-600	0116B6734G1 0116B6734G2 0116B6734G3 0116B6734G4 0116B6734G5 0116B6734G6	1 2 3 4 5 6	200-K 560 K 750 K 1 MEG 1.2 MEG 1.6 MEG	BIA	011686709G1	SEE ORDER- ING TABLE 2	0165A9257P3	0165A7955

⁺ Specify color cap from Table 6 or 7.

TABLE 4

ET-16 SPECIAL 12788177

INDICATING LAMP COMPLETE

		1 REQ	D. OF	GR. RE	OR PT		BULB			
GROUP NUMBER*	VOLTS	RECEPTACLE	DRG.	NO.	PART NO.	OHMIC VALUE	G.E. CAT. NO.	COLOR CAP	CARTON	OUTLINE
1	70				7	750 Ω	1835			
2	17				8	50 Ω	756	**		
3	140				9	2500 Ω	NONE			
4	220				10	4300 ♀	1835	ш		
5	32	6-1			2	200 Ω	1819	TABLE	_	
6	125	ပ်			11	3300	1835	₹	P-1	
7	277	60	4		12	_ 5900 ຄື	1835			6
8	140	57(28/		9	2500 Ω	1835		25	8
9	130	011686709	0165A7844		13	2300 Ω	1835	ORDERING	0165A9257	0165A7859
		111	16					2	65	65
<u> </u>		0	0						5	밁
	ļ							SEE		
<u> </u>	 							S		
L	L	<u> </u>	L					!		

^{**756} Bulb Furnished 3y Customer

TABLE 5
ET-17 SPECIAL 128B1654

INDICATING LAMP COMPLETE

	INDICA	1110		COMPLETE					
2		1	REQ'	D. OF GR.	OR PT.	NO LISTED	BEL	<u>0W</u>	I
	VOLTS			RESISTOR	<u> </u>	BULB		ĺ	l
GROUP		RECEPTACLE	DRG. NO.	PART NO.	OHMIC VALUE	G.E. CAT. NO.	COLOR CAP	CARTON	OUTLINE
1	210-250 AC/DC 67-120	011686709GR-1		1 8	56K 80K	NE51H** NE51 OR	TABLE		
2	AC	6206	7956			B1A	ORDERING	7.5	55
		1168	0165A7956				SE SE	0165A9257	0165A7955
		0	D				SEE	0165	0165

** NE51H BULB Furnished By Customer

TABLE 6
COLOR CAP

CAT. NO.	COLOR CAP				
	COLOR	CAT. NO.			
0116B6708G 0116B6708G*C 0116B6708G*R 0116B6708G*G 0116B6708G*Y 0116B6708G*W 9116B6708G*A 0116B6708G*D 0116B6708G*E	NONE CLEAR RED Ø GREEN Ø YELLOW Ø WHITE Ø BLUE T AMBER T GREEN T RED T	NONE 208A3768P1 208A3768P2 208A3768P3 208A3768P4 208A3768P5 208A3768P6 208A3768P7 208A3768P8 208A3768P9			

ORDERING TABLE 7

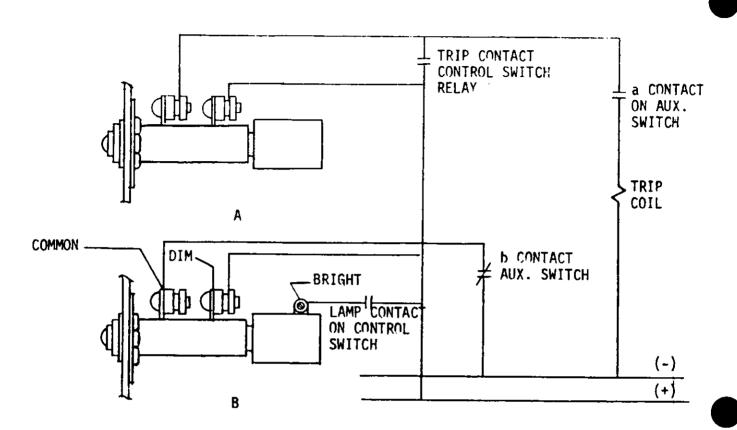
COLOR CAP

CAT. NO.	COLOR CAP	
	COLOR	CAT. NO.
0116B6734G* 0116B6734G*C 0116B6734G*E 0116B6734G*A	NONE CLEAR RED# AMBER	NONE 208A3768P1 208A3766P9 208A3768P7

*=Group No. per Voltage Selected
For Other Voltages Refer to Company
Group No. with No. Suffix=Color Cap Omitted
#Transparent
Transparent

HOW TO ORDER

Order by complete Cat. No. and specify color cap.



- FIG A SHOWS A TELL-TALE CIRCUIT FOR A CIRCUIT BREAKER CLOSE INDICATION. WHEN THE BREAKER IS CLOSED, THE LIGHTED (RED) LAMP SHOWS NOT ONLY THE BREAKER POSITION, BUT ALSO THAT THE TRIP CIRCUIT IS COMPLETE.
- FIG B FOR CIRCUIT BREAKER OPEN INDICATION, THE DIM-BRIGHT CONNECTION IS OFTEN DESIRABLE, ESPECIALLY WHEN A LARGE NUMBER OF LAMPS ARE LOCATED ON ONE PANEL. A LAMP UNIT WITH TAPPED RESISTOR IS REQUIRED, TOGETHER WITH A CONTROL SWITCH HAVING A LAMP CONTACT WHICH REMAINS CLOSED IN THE NORMAL POSITION, EXCEPT AFTER THE SWITCH HAS BEEN TURNED TO THE TRIP POSITION. A WHITE COLOR CAP ON THE LAMP IS CUSTOMARY. WHEN THE BREAKER IS TRIPPED WITH THE CONTROL SWITCH, THE SWITCH CONTACT IS OPENED, AND THE LAMP GLOWS WITH LOW BRILLIANCY. IF THE BREAKER IS TRIPPED AUTOMATICALLY, THE CONTROL SWITCH CONTACT SHORT-CIRCUITS PART OF THE LAMP RESISTOR SO THE LAMP GLOWS BRIGHTLY, AND THE NON-MANUAL OPERATION CAN BE EASILY LOCATED ON THE PANEL.

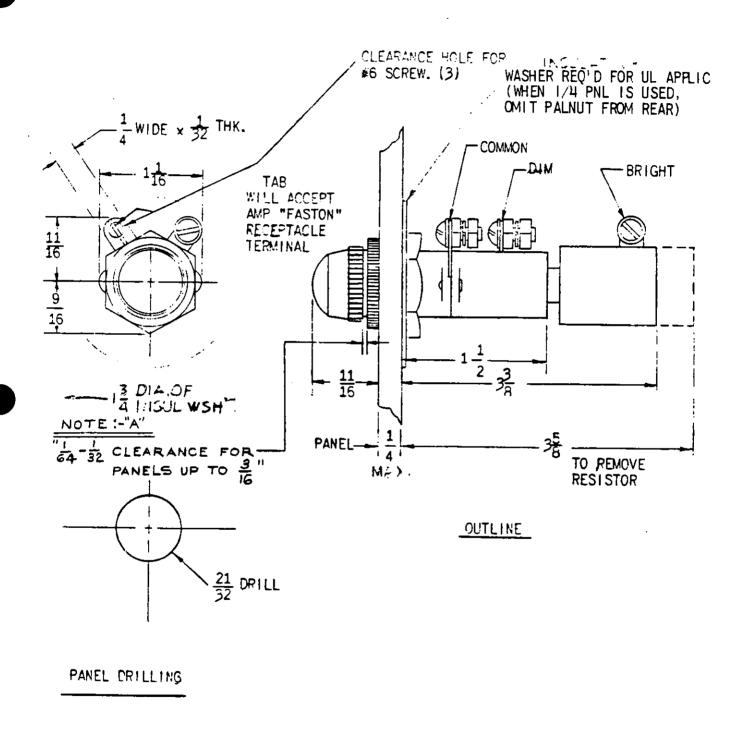


FIG.2 (0165A9216-3) Outline And Panel Drilling For Type ET-16 Indicating Lamp With Tap Resistor For Dim Bright Operations

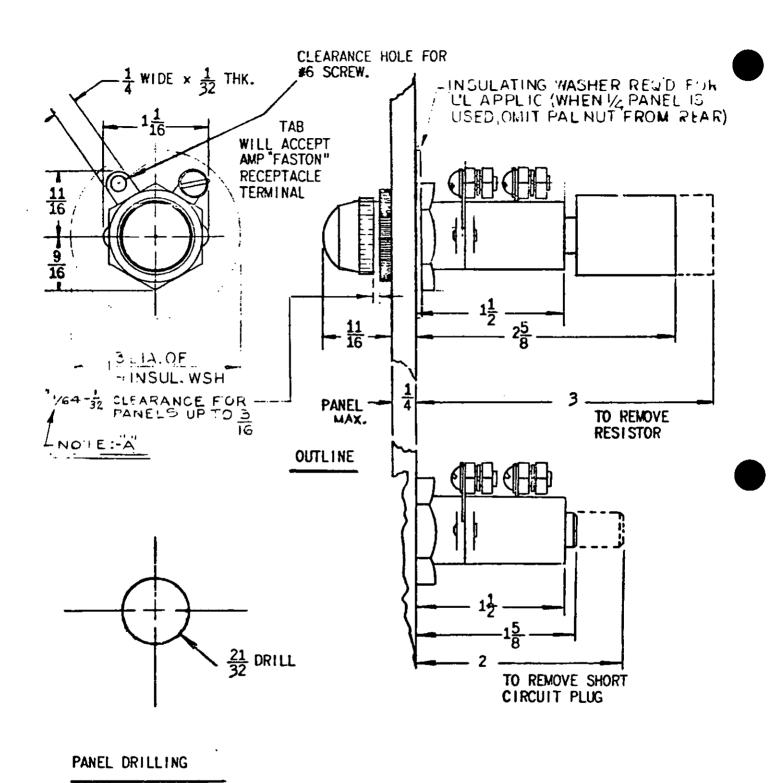
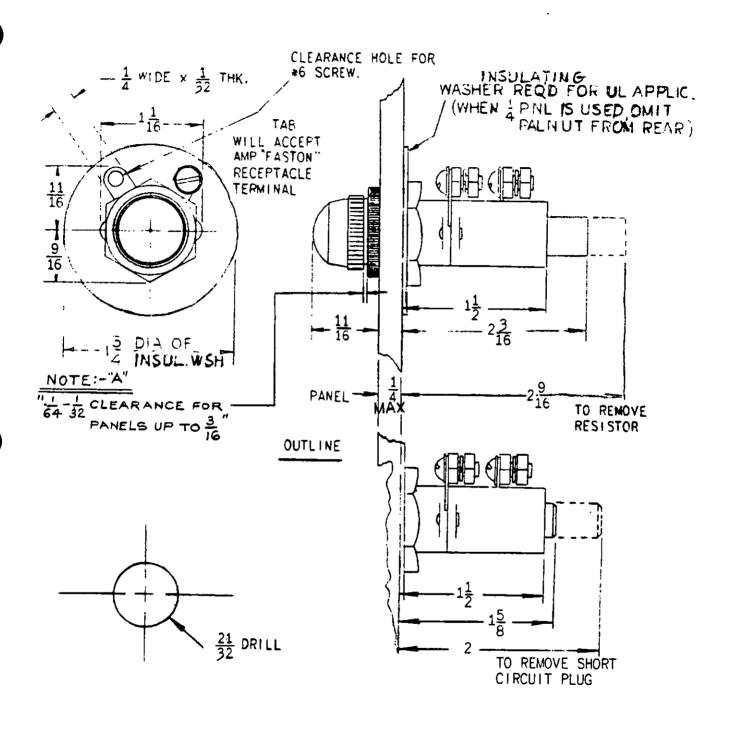


FIG.3 (0165A7859-6) Outline And Panel Drilling For Type ET-16 Indicating Lamp



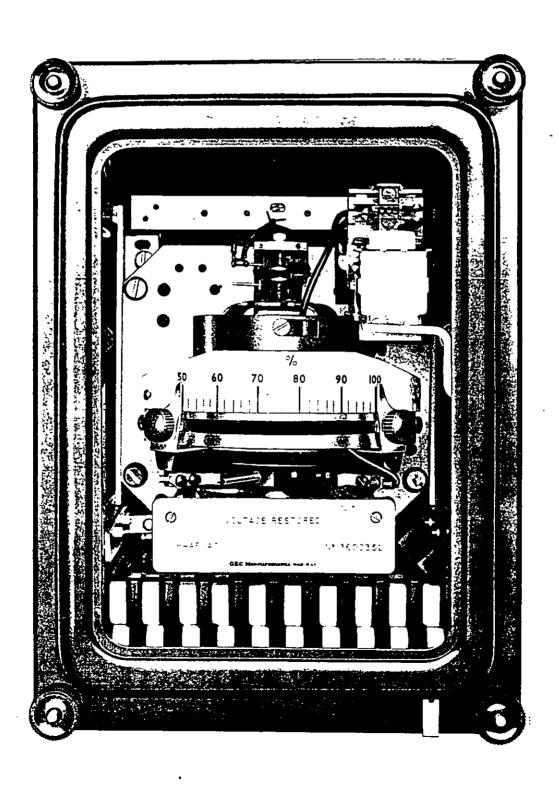
PANEL DRILLING

FIG.4 (0165A7955-6) Outline And Panel Drilling For Neon Indicating Lamp
Type ET-17

GENERAL ELECTRIC COMPANY POWER SYSTEMS MANAGEMENT BUSINESS DEPT. MALVERN, PA 19355

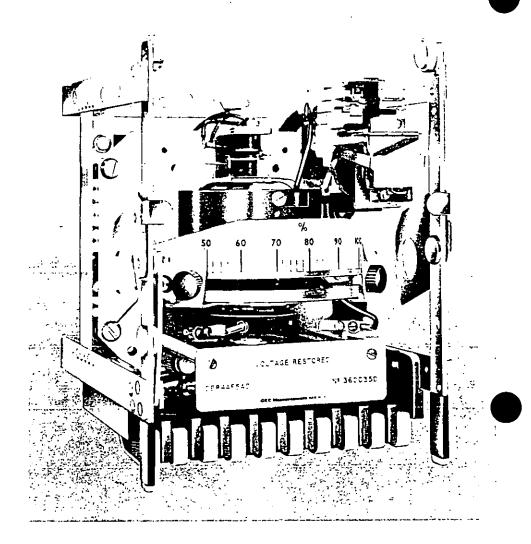


Sensitive Moving Coil Relays
Types
DBA4 and DBB4



DBA4 and DBB4

- * High sensitivity and torque
- * High damping
- * Drop-off/pick-up ratio 97%
- * Low burden
- Bi-directional operation (type DBB4)
- Approved by British Electricity Supply Authorities



APPLICATION

The small energy consumption of the relay movement permits many applications that would not be feasible with simple electro-magnetic relays; the inherent directional property and inverse time-lag are other valuable features.

The versatility of these relays is indicated by these typical applications:

Overcurrent and/or reverse current protection of d.c. systems. Usually by means of an auxiliary heavy current shunt.

Overvoltage and/or undervoltage protection of d.c. systems.

A.c. current or voltage measurement by means of internal rectifier with, for high currents or voltages, auxiliary measuring transformers.

By means of auxiliary C.T.'s and rectifiers and other components, the relays can be applied to a wide range of protection or control schemes for a.c. systems.

CONSTRUCTION

The basic design of the relay follows the conventional d'Arsonval principle, in that it consists of a moving coil rotating in a radial magnetic field. But it must not be confused with instrument movements fitted with contacts which in general are unsuitable for any but the simplest duty of closing a low-rated alarm circuit.

Moving coil damping

Generally the coil is wound on an aluminium former which provides efficient damping due to the eddy currents induced in it when it moves in the magnetic field. When extra heavy damping is required, a copper former is used and still more dampin, can be obtained if an internal shunt is used across the coil.

Sensitivity

Alternative control springs providing standard or approximately double or half standard torque can be fitted.

Moving contact

The moving contact shown in Figures 1 and 2 is designed especially to provide the resilience necessary to ensure satisfactory contact making ' with low available forces. A relay of this type gives a deflection proportional to the applied current and with a current of setting value contact make will be achieved but the entire operating torque will be absorbed by the control spring leaving no margin of force for contact pressure. It follows that for currents only slightly above setting value, contact making is relatively poor and a highly resilient contact is necessary. At the same time it must be protected from mechanical damage arising from the high accelerating force generated when the relay is subject to the large current related to heavy fault conditions. This has been successfully achieved by coil stops and by making the contact from flexible silver alloy wire, pressed and soldered into a screwed brass mount. A duralamin tube, pressed into the same mount, surrounds the silver ontact wire over the majority of its √ength. The duralamin tube does not carry current.

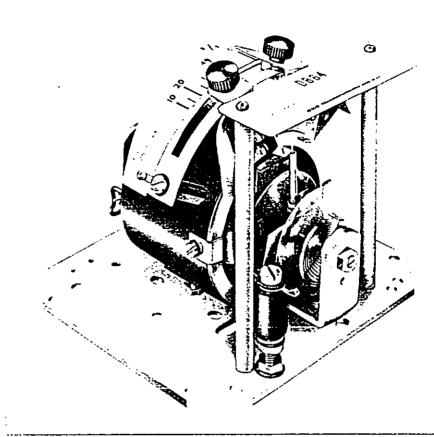
The screwed brass mount is fitted to an insulator carried on the movement shaft and connection to the moving contact is made by a silver ligament which is screened on each side by mica insulators.

Pivots and bearings

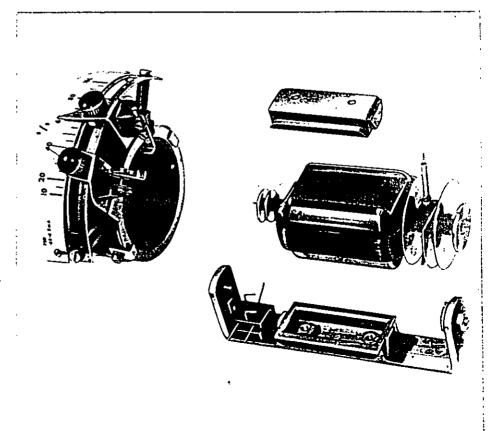
The movement is supported on precision ground 'V' shaped hardened steel pivots, mounted in spring-loaded jewelled bearings, to prevent damage arising from shock or vibration. Vertical mounting of the movement also reduces pivot friction to a minimum.

Movement stirrup

The die-cast stirrup embodies accurate locations for the movement bearings and permanent magnet, ensuring concentricity of the movement. A die-cast clamping piece, similar in shape to the centre section of the stirrup, locates on the magnet centre pole, the complete assembly, amprising stirrup, magnet and lamping piece is then secured in the mild steel tube by two grub screws.



- < TYPE DEBA CUT OF CASE



Magnet assembly

The permanent magnet, consisting of a rectangular block of a high-energy type of magnet steel, is positioned within the moving coil and has mild steel pole pieces so shaped that the whole forms a cylindrical cross-section, providing a uniform magnetic field over the effective angular travel of the coil. To achieve maximum field strength the magnet is magnetised in situ at a stage after assembly of the movement.

A mild steel tube surrounds the magnetic circuit, reducing external flux leakage to a minimum.

The result is a magnetic circuit in which all flux emanating radially from the magnet is usefully employed.

Adjustable quadrants

Two adjustable quadrants are located on a shoulder on the end of the mild steel magnet tube. The quadrants combine the functions of contact carriers and coil stops, the position of the coil stops being such that they permit a constant contact wipe irrespective of the contact setting. Depending upon the application, contacts are fitted to either one or both of the quadrants. When only one contact is fitted, the other quadrant may be used as an adjustable back-stop for the coil, restricting the movement of the coil from the

'contact closed' position by any desired amount. Each of the adjustable quadrants have pointers which register over a common scale. Pointers may be locked in any desired position by a knurled clamping screw.

OPERATION

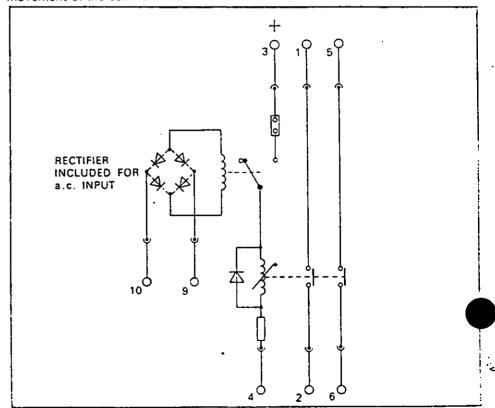
Circuit description

A typical arrangement of the type DBA4 relay is shown in Figure 3. The measuring element contact may be connected directly to terminals, or used to operate an auxiliary follower element type VAA, mounted internally. For measurement of a.c. inputs, a bridge rectifier is included in the circuit.

The circuit arrangement for the type DBB4 relay shown in Figure 4 is basically similar but commonly provides additional contacts for operation in either direction.

Seal-in feature

When required, the left hand adjustable contact can also be used to provide a 'seal-in' feature as shown in Figure 5. This arrangement can be used to produce an adjustable dropoff, pick-up setting ratio and also improve mechanical stability. One contact of the auxiliary element is used to seal-in the element as soon as the measuring element has operated.



rihe auxiliary element will then remain energised until the measured quantity has reduced to the point where the left hand contact closes, short circuiting the auxiliary element coil. The auxiliary element then resets, opening the sealing circuit.

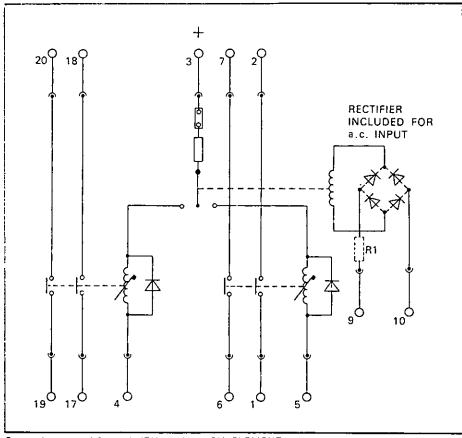
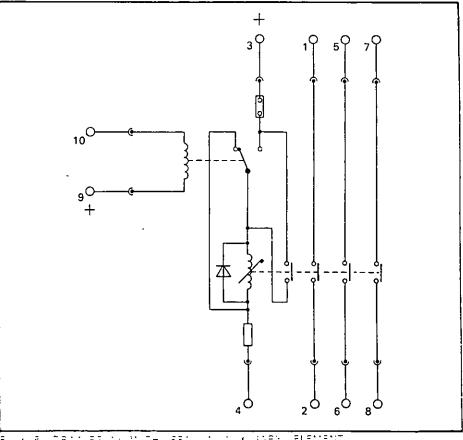


Figure 4 DBB4 RELAY WITH AUXILIARY ELEMENTS



Luky 8 | DBA4 PBUAK WITH I SBAU IN AUKUPARK

Operating time characteristics

The inherent inverse time characteristic is illustrated in curves Figure 6 and Figure 7, which show the effect on operating times of different contact settings and multiples of current settings.

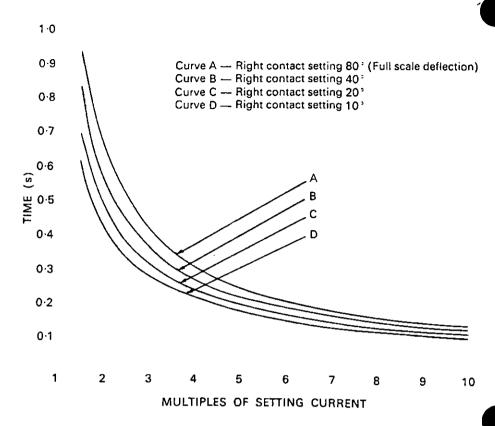
Figure 6 depicts conditions as operating from a normal free zero to varying settings of the right contact, whilst Figure 7 shows conditions as operating from varying settings of the left contact (that is, with a set up zero) to a constant maximum setting of the right contact. An infinite variety of curves is possible between these limits. It should be noted that the curves are typical only for a relay fitted with a standard torque spring and a standard aluminium coil former, no undertaking is given in manufacture to reproduce any particular curve.

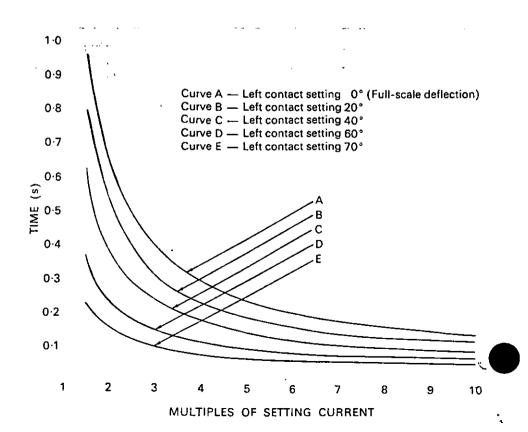
A considerable range of operating times is obtainable by suitable settings of the relay contacts to modify the angle of movement, and/or by choosing a nominal operating current exceeding the relay setting.

The relay may be used to fulfil short-term timing functions, provided the operating coil is supplied from a constant source and the appropriate settings are used, see Figure 6 and Figure 7.

By suitable combinations of short travel and the appropriate degree of over-setting, operating times as quoted in BS.142: 1966 for instantaneous relays may be obtained.

NOTE: The asymptotic regions of the curves have been purposely omitted since it is considered that timings in these regions are too indeterminate to be of much value.





Operating characteristics

	Shunt- operated (75 milli- volt) (standard torque)	Voltage operated (standard torque)	High sensitivity voltage operated (half torque)	Thermo- couple operated (half torque)
Coil resistance (ohms)	0.2	65	245	9.5
Nominal full-scale current (mA)	60	2.5	0.5	2.4
Milliamps per degree deflection	0-75	0.031	0.00625	0.03
*Nominal full-scale millivolts	12	_		22.8
*Millivolts per degree deflection	0.15	_		0.285
Nominal full-scale burden (microwatts)	Coil only 720	410	61	55
†Microwatts for 1° deflection	Coil only 0·11	0.064	0.01	0.009
Maximum continuous current (amp)	1.5 (i.e. 25 × maximum setting)	0·175 (i.e. 70× maximum setting)	0·092 (i.e. 184× maximum setting)	0.45 (i.e. 180× maximum setting)

^{*} Uncompensated for temperature coefficient of resistance.

Measuring element contact ratings

Make and carry momentarily	Carry continuously	Break
500VA, a.c. or d.c. subject to a maxima of 600V and 3 A	1 A a.c. or d.c.	100VA, a.c. subject to a maxima of 250V and 1 A 30 Watts d.c. (non-inductive) subject to a maxima of 250V and 1 A

When intended for primary tripping, relays are supplied with an auxiliary unit fitted with higher capacity contacts.

[†] Multiply by the square of deflection in degrees.

Auxiliary elements

A type VAA auxiliary attracted armature unit may be mounted with the relay in a size 1D drawout case, or up to three attracted armature units can be housed with the relay in a size 1½D drawout case.

Two pairs of contacts with any combination of normally open or normally closed are generally fitted, but this may be extended to suit

customers' requirements. Changeover contact arrangements are also available.

Standard contacts are of a silver/copper alloy, shaped and positioned to ensure a very reliable, low-resistance contact. Special silver/cadmium alloy tips with anti-welding properties suitable for carrying heavy current for short periods can also be supplied. Details of ratings will be supplied on request.

Contact ratings

Type of Contact	Current	Make and carry continuously	Make and carry for 3 seconds	Break	
Standard	a.c.	1250 VA with maxima of 5A and 660V	7500 VA with maxima of 30A and 660V	1250 VA with maxima of 5A and 660V	
Standard	d.c.	1250 W with maxima of 5A and 660V	7500 W with maxima of 30A and 660V	100 W (resistive) 50 W (inductive) with maxima of 5A and 660V	. (

Operation indicator

A hand re-set operation indicator is fitted as standard on the auxiliary unit. Burden of auxiliary unit – type VAA (at 125V d.c.) coil 2·1W series resistor 5·4W

Insulation

The relay will withstand 5kV, 50Hz, for 1 minute between each pair of the following groups:

- (a) Measuring element circuit.
- (b) Auxiliary element coil and contact circuits.
- (c) Relay case (earth).

The relay will also withstand 2kV, 50Hz, for 1 minute between any pair of the following groups:

- (a) Auxiliary unit coil circuit.
- (b) Output contact circuits.
- (c) Relay case.

PARTICULARS REQUIRED WITH ORDERS

Please state:

- 1 Type of relay (DBA4 or DBB4).
- Application.
- 3 Supply system details.
- 4 If voltage or current operated.
- 5 If shunt operated, give shunt data and particulars of leads if other than standard 4ft (1.2 metres).
- Scale marking and setting range.
- 7 If auxiliary element is required
 - (a) Number and arrangement of contacts;
 - (b) Trip circuit voltage and contact rating required.
- 8 Is an operation indicator required? If so state if shunt or series operated.
- 9 Type of mounting: flush or projecting.
- 10 Panel thickness.
- 11 Any other relevant information.

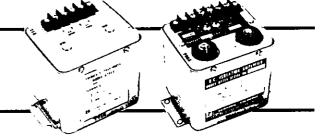
Our policy is one of continuous product development and the right is reserved to supply equipment which may vary slightly from that described

GEC Measurements The General Electric Company Limited of England

St. Leonards Works Stafford ST17 4LX England

Telephone: 0785 3251 Telex: 36240 Cables: Measurements Stafford Telex

EXCELTRONIC ™



FREQUENCY TRANSDUCERS Models 6281B, 6283B, 6284B

DESCRIPTION

Scientific Columbus Frequency Transducers develop a DC output signal which is proportional to input frequency.

These transducers have an expanded scale output. A variety of calibrations may be ordered or the user may calibrate the transducer at the installation site to meet specific requirements.

These transducers feature the exceptional Scientific

Columbus constant current output. This means, for a given input, no adjustment is necessary to compensate for various output signal loop characteristics.

Series components and devices such as indicators, recorders, resistors for alarms and analog-to-digital pickoff points can be added to the output signal circuit without recalibrating these transducers. Filtering is also included, which simplifies matching these units to fast response de-

SPECIFICATIONS

Input Voltage Overload Frequency Range Output Accuracy

Ambient Temperature Effect on Accuracy Adjustments Burden Ripple

Temperature Range Response

6284B 6283B 6281B 120 V 120 V 120 V 150 V 150 V 150 V 375-425 Hz 55-65 Hz 45-55 Hz 0-1 ma into 0-10K ohms 0-1 ma into 0-10K ohms 0-1 ma into 0-10K ohms 0.02% of

± 0.02% of ± 0.02% of Center frequency at 25°C Center frequency at 25° C ± 0.0025% / C Max. ± 0.0025% PC Max. Zero, Span Zero, Span

4VA 1% maximum output peak 20°C to + 60°C 20°C to + 60°C

4VA 4VA 1% maximum output peak 1% maximum output peak

20°C to + 60°C 0.4 sec. to 99% of final value 0.4 sec. to 99% of final value 0.4 sec. to 99% of final value

Center frequency at 25° C

± 0.0025% C Max.

Zero, Span

Connections see page 49, Connection 49E Packaging see page 47 Style II Case

SHUNT/ISOLATION/ AMPLIFIER Model 6271A

DESCRIPTION

The Model 6271A Shunt Amplifier is a linear amplifier designed to amplify DC shunt millivolt signals or D.C. voltages from 50 MV to 1000 V D.C., and provides complete isolation of the input signal. A magnetic amplifier is used in the input circuit to isolate the input from all other circuits and grounds. The input is tested at 4000 volts D.C. for one minute to insure that no breakdown will occur when connected to shunts operating at high voltage levels above ground. The output circuit is a hybrid amplifier operating in the transconductance mode to provide a constant current output. Load resistance variations from 0-10K have less than 0.1% effect on the output current. This makes the amplifier an ideal device for telemetering, scaling, recording applications or matching to tone transmitters or A to D converters. The output is also filtered, thus making expensive filtering unnecessary.

A 20 turn zero and gain adjustment is provided and is accessible through the top cover. Large gain changes can be accomplished by changing the auxiliary gain resistor across terminals 3 and 4.

SPECIFICATIONS

Power Requirements Signal Input (nominal) Signal Input Range Options Input Impedance Output D.C. Load Impedance Accuracy Temperature Range Temperature Coefficient

Size Packaging

Connections see page 49 Connection 49D

Response Time

120V 60 Hz ± 10% 10VA (Max.) 0 to ± 100 Millivolts 50 MV to 1000 V D.C. 5000 ohms/Volt 0 to ± 1 ma Any Load between 0-10K

± 0.5% RO@ 25°C 10°C to + ± 0.04% °C 3" x 4%" x 4⁷/₁₆" High Style II Metal Case

Dimensions see page 47 Style II Case

D.C. AMPLIFIER Model 6181A

SPECIFICATIONS

Amplifier Type DC Instrument Amplifier/6181A

and Model Current 10 µ a to 5 ma DC Input Limits Voltage 10 mv to 8 Volts Max Current 10 ma DC Output Limits

Voltage 8 Volts **Effective Input** Less than 10 ohms for current input, more Impedance than 10 megohms for voltage input

± 0.5% maximum output* Gain Stability ± 0.5% of maximum output DC Linearity

Zero Stability 20 μ v/° C maximum (5 μ v/° C typical) referred to input

0.1 second or better to reach 99% of final

value - 10°C to + 50°C

Ambient Temperature Range

Duty Cycle Continuous* Weight

Approximately 2-1/2 lbs. 100-130 V, 50-400 Hz, single phase, 5 VA Power Requirements

See Unit Instruction Manual for 4 modes of operation



Within specified ambient temperature range.

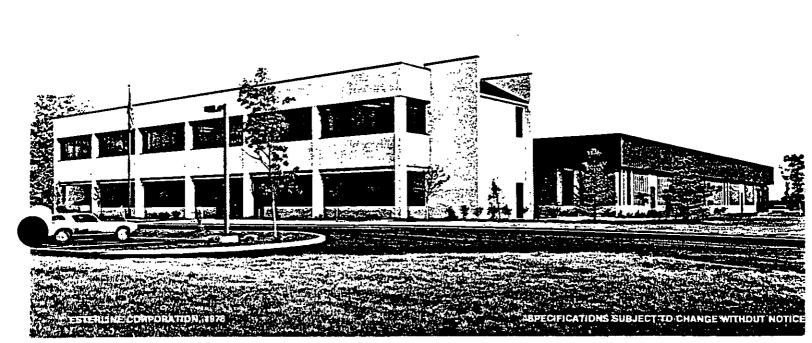


Power Instrumentation Specialists to ELECTRIC UTILITIES INDUSTRY and SYSTEM MANUFACTURERS

Presents

THE DIGILOGICS
THE EXCELTRONICS®
THE JEMS®
THE MICROJOULES
AND RELATED DEVICES

These high accuracy transducers, solid state meters, signal conditioners, test equipment, laboratory and field standards, along with custom designed instrumentation systems are recognized as outstanding contributions to the electrical energy measurement field.



Modifications and Options for Transducers

Modification Description	Applicable Models	Suffix To Model No.	Modified Rating or Description
OUTPUTS Calibration			
External Power	Watt, VAR, Watt/VAR	A2	Auxiliary Power required.
internal Power	Watt, VAR, Watt/VAR	A4, in place of A2	Auxiliary Power not required.
50-200% Cal. Adj. (current)	XL Watt, XL VAR	- 20	0.5-2.0 mA full scale at rated input.
50-200% Cal. Adj. (voltage)	XL Watt, XL VAR	- 21	5-10 Vdc full scale at rated input.
High Accuracy	Volt, Current	A4 (delete A2)	± 0.1% RO accuracy
Certification of Compliance	All models	Use word description	
Traceability to NBS	Watt, VAR, Current, Volt	Use word description	
Sepia Drawings	Connections/Outlines	Use word description	
Scaling Resistors	All models	"Special Calibration"	0.025% wire-wound precision scaling resistors
Seismic Rated	Watt, VAR, Current, Voltage	- S	Test Data Available
INPUTS 69 Volts (0-90 V)	Watt, VAR	- 0	250 watts (VARs) per element
240 Volts (0-300 Volts)	Watt, VAR	- 1	1000 watts per element
480 Volts (0-600 V)	Watt, VAR	- 2	2000 watts per element
1 Amp	Watt. VAR	- 3	100 watts (VARs) per element
2.5 Amp	Watt, VAR	- 4	250 watts (VARs) per element
7.5 Amp	Watt, VAR	– 11	750 watts (VARs) per element
10 Amp	Watt, VAR	- 5 ·	1000 watts (VARs) per element
15 Amp	Watt, VAR	- 7	1500 watts (VARs) per element
25 Amp	Watt, VAR	- 8	2500 watts (VARs) per element
10 Amp	Current	– 1	0-10 A input
25 Amp	Current	- 2	0-25 A input
240 Volt	Voltage	- 1	0-300 V input
480 Volt	Voltage	- 2	0-600 V input
25 Hz	Watt, Current, Voltage	- 25	A State of the search of the s
50 Hz	All models	- 12	
400 Hz	Most models	- 6	

SURGE WITHSTAND CAPABILITY (SWC)

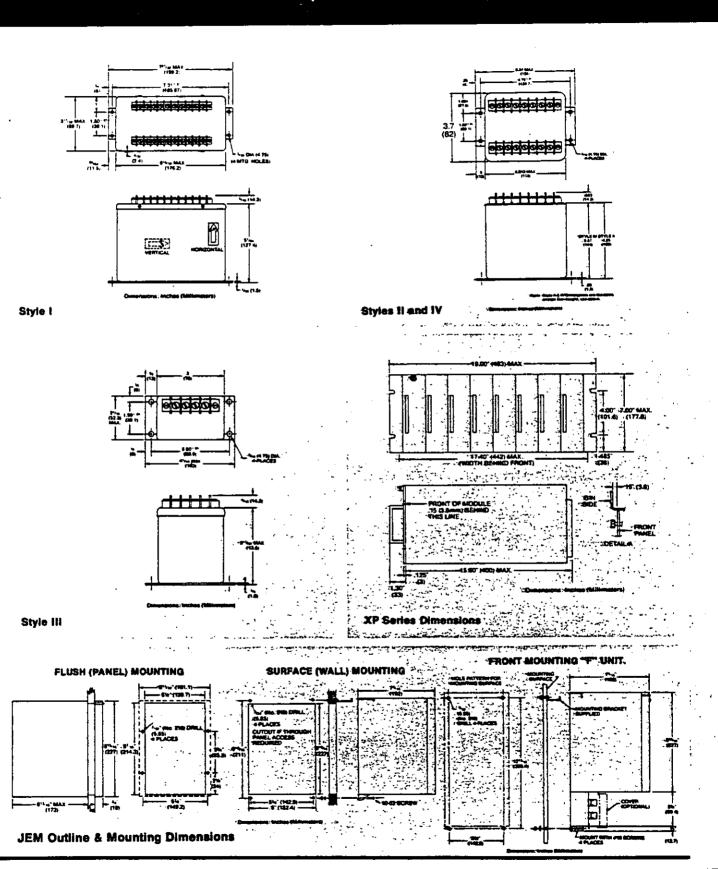
ANSI C37.90a/IEEE 472

Applies to all Scientific Columbus Transducers

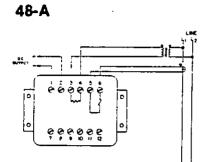
Scientific Columbus Transducers are capable of meeting the IEEE Standard Surge Withstand Capability Test: The SWC test wave is an ocillatory wave, frequency range 1.0 MHz to 1.5 MHz, voltage range of 2.5KV to 3.0 KV crest value of the first half cycle peak, envelope decaying to 50% of the crest value of the first peak in not less than 6 microseconds from the start of the wave. The source impedance of the surge generator used to produce the test wave shall be 150—2. The test wave to applied to a test specimen at a repetitive rate of not less than 50 tests per second for a period of not less than 2.0 seconds.

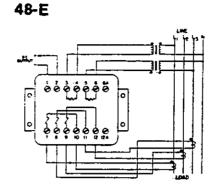


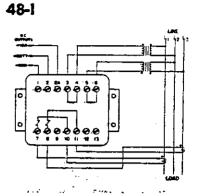
Outline Dimensions Style I, II, III, IV, XP Series and JEM

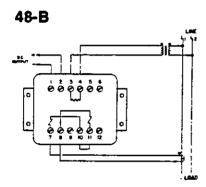


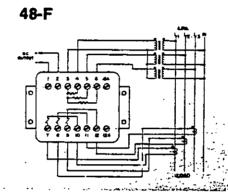
"See important notice below

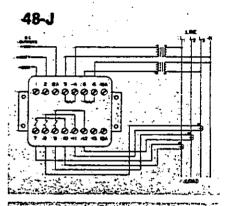


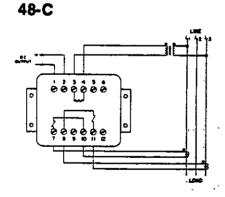


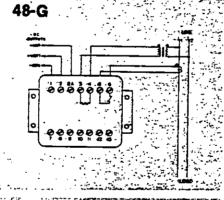


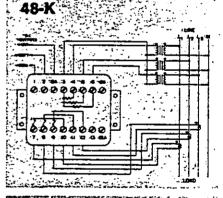


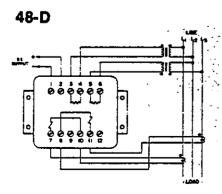


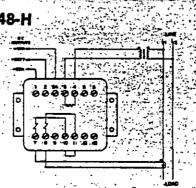












Amplifier Power, when required, is supplied to terminals as follows:

Terminals Terminals

9 & 12 6A & 12A

Conn: 48-A 48-D (2½ ele)

48-B 48-E

48-C 48-F

48-D (2 ele) 48-J

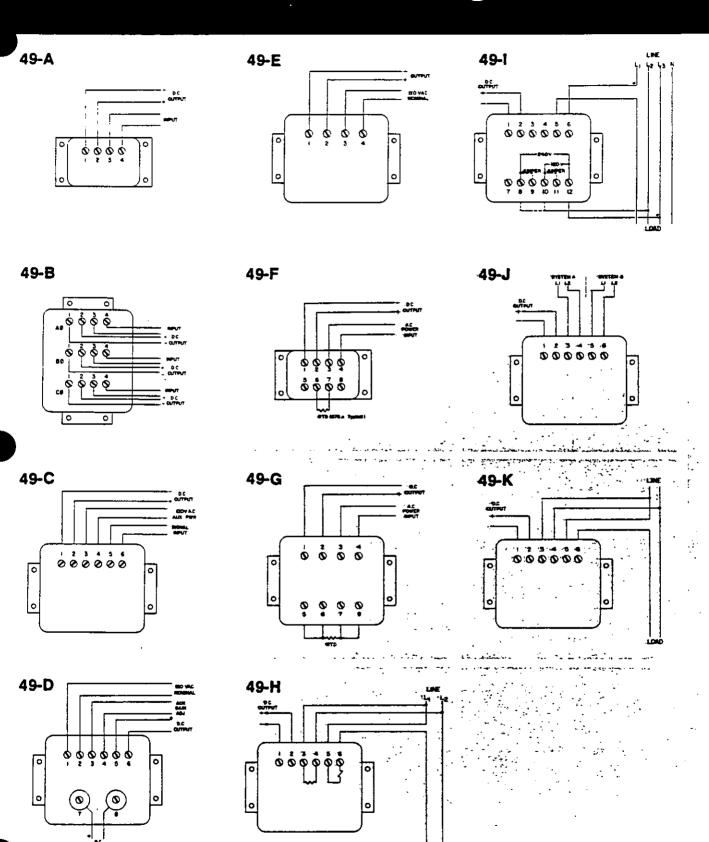
48-G 48-K

48-H

48-I

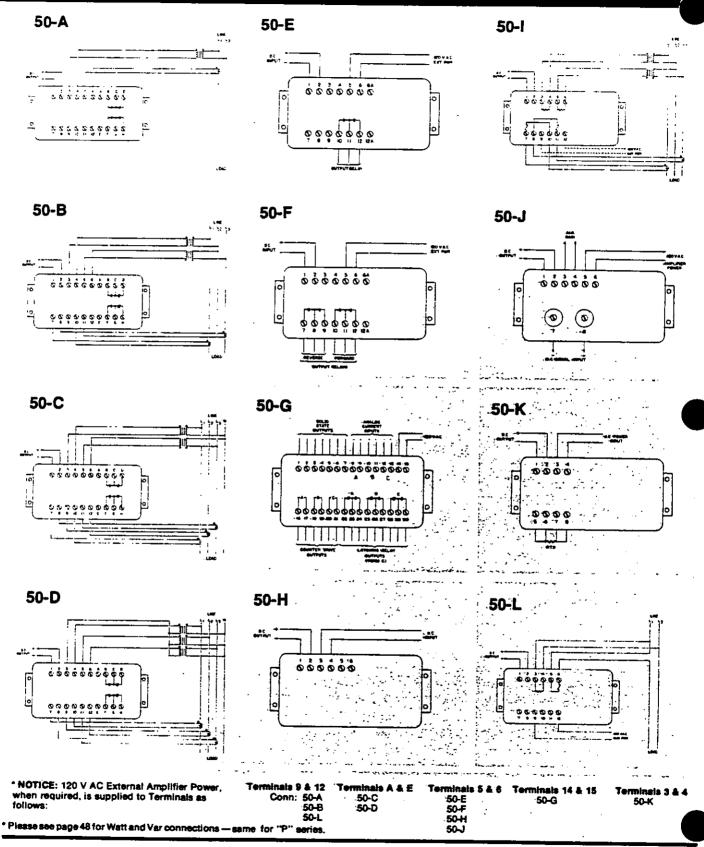
NOTICE: 120 V. AC External

Contract to the second





■ See important note below





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INSTRUCTION MANUAL FOR EXCELTRONIC WATT AND VAR TRANSDUCERS

WARRANTY AND REPAIRS

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EXCELTRONIC WATT AND VAR TRANSDUCERS

DESCRIPTION

The Scientific Columbus EXCELTRONIC Watt and Var Transducers are state-of-the-art, high-reliability electronic devices that provide a dc current output signal which is very accurately proportional to input watts or vars. The excellent accuracy, long-term stability, and very low error influences are made possible at economical prices by use of patented and patent-pending techniques. Many features of the outstanding DIGILOGIC Transducer series have been utilized along with new developments to make an unprecedented performance/value combination.

The EXCELTRONIC series is available in 1, 1-1/2, 2, 2-1/2, and 3-element configurations. All models are packaged in the same small case which measures only 5-5/16" by 3-11/16" by 4-13/16". They are physically interchangable with the Halltiplier series transducers and have the same identical electrical connections, making it easy to upgrade existing installations where improved performance is desired. Nominal input ratings are 120 V and 5 A per element. Standard calibration is 1 mA output for 500 watts (or vars) per element.

SPECIFICATIONS

FOR

EXCELTRONIC WATT TRANSDUCER XL-A2/A4 SERIES

General Specifications

Function High accuracy watt transducer

Phases 1 or 3

Elements 1, 1-1/2, 2, 2-1/2, 3

Calibrating Input 500 watts/element

Rated Output (RO) 1 mA dc into 0-10 kilohms at calibrating watts

(polarity reverses for reverse power flow)

Potential Input 120 volts nominal

Operating Range 0-150 volts (85-135 volts for A4 Series)

Overload, continuous 175 volts

Burden, at 120 V 0.05 VA maximum per element (1.75 VA for

A4 Series)

Current Input 5 amperes nominal

Linear Operating Range 0-10 amperes
Overload, continuous 15 amperes
Overload, 10 sec./hr. 50 amperes

Overload, 1 sec./hr. 400 amperes

Burden, at 5 A 0.1 VA maximum per element (0.2 VA on l

2

element units)

Frequency Range ± 10 Hz of calibration (60 Hz standard)

Power Factor Range No restriction

Temperature

Normal Operating Range $25^{\circ}C \pm 5^{\circ}C$ Extended Operating Range $-20^{\circ}C$ to $+70^{\circ}C$

Additional Influence on

Accuracy (extended range) ± 0.005% of reading/OC

Storage Range -40°C to +82°C

Humidity 0% to 95%

Accuracy

± (0.2% Reading + 0.01% RO), including all stated variables except extended temperature range, 0% to 200% of calibrating watts.

Output

Stability Load

Compliance

Low Impedance Terminal

Impedance

Response Time, to within 99% of final value after

step change Ripple, peak

Calibration Adjustment

Range

Zero Adjustment

Auxiliary Power

Burden at 120 V

Protection Isolation

Dielectric

Surge

Packaging and Connections

Weight: 1 element 2 element

3 element

Options*

±1 mA at calibrating watts

±0.1% RO/year 0-10 kilohms 11 volts minimum

2

100 megohms minimum

400 ms, maximum 0.5% RO, maximum

±2% RO minimum None required

 $85-135 \text{ Vac}, 60 \text{ Hz} \pm 10 \text{ Hz}$

1.5 VA maximum

Complete: Input/Output/Power/Case

1800 V rms for 1 minute or 2200 V for 1 second

Withstands IEEE SWC test

See drawings on following pages

2 pounds, 2 ounces (0.96 kg)

2 pounds, 10 ounces (1.19 kg)

3 pounds, 2 ounces (1.42 kg)

Calibration Frequency (40-400)

Nominal Voltage Variations (60-480) Nominal Ampère Variations (1-20)

Voltage Outputs (0-10 V)

(Output impedance = 1000 ohms/V)

* Variations from standard calibration will possibly require some specifications to be relaxed or changed to be applicable to the option requested.

SPECIFICATIONS

FOR

EXCELTRONIC VAR TRANSDUCER XLV-A2/A4 SERIES

General Specifications

Function

High accuracy var transducer

Phases

l or 3

Elements

1, 1-1/2, 2, 2-1/2, 3

Calibrating Input

500 vars/element

Rated Output (RO)

1 mA dc into 0-10 kilohms calibrating vars

lag input (polarity reverses for lead)

Potential Input

120 volts nominal

Operating Range

0-150 volts (85-135 volts for A4 Series)

Overload, continuous

175 Vac

Burden at 120 V

0.05 VA maximum per element (1.75 VA for

A4 Series)

Current Input

5 amperes

Linear Operating Range

0-l0 amperes

Overload, continuous

l5 amperes

Overload, 10 sec./hr.

50 amperes

Overload, 1 sec./hr.

400 amperes

Burden at 5 A

0.1 VA maximum per element (0.2 VA for 1

element units)

Frequency Input

60 Hz (standard)

Power Factor Range

No restriction

Temperature

Normal Operating Range

 $25^{\circ}C \pm 5^{\circ}C$

Extended Operating Range

-20°C to +60°C

Additional Influence on

Accuracy (extended range) $\pm 0.005\%$ of Reading/OC, typical

Storage Range

 -40° C to $+82^{\circ}$ C

Humidity

0% to 95%

Accuracy

 \pm (0.2% Reading + 0.02% RO), including all stated variables except extended temperature range, 0% to 200% of calibrating vars.

Output

Stability Load

Compliance

Low Impedance Terminal

Impedance

Response Time, to within 1% of RO of nominal out-

put after step change

Ripple, peak

Calibration Adjustment

Zero Adjustment

±1 mA dc at calibrating vars

±0.2% RO/year typical

0-10 kilohms

ll volts minimum

2

100 megohms minimum

400 ms, maximum 0.5% RO, maximum ±2% RO minimum

None required

Auxiliary Power Burden at 120 V

 $85-135 \text{ Vac}, 60 \text{ Hz} \pm 10 \text{ Hz}$

1.5 VA maximum

Protection

Isolation

Dielectric

Surge

Complete: Input/Output/Power/Case

1800 V rms for 1 minute or 2200 for 1 second

Withstands IEEE SWC test

Packaging and Connections

See drawings on following pages

Weight: l element 2 element

3 element

2 pounds, 2 ounces (0.96 kg) 2 pounds, 10 ounces (1.19 kg) 3 pounds, 2 ounces (1.42 kg)

Options*

Calibration Frequency (40-400) Nominal Voltage Variations (60-480) Nominal Current Variations (1-20)

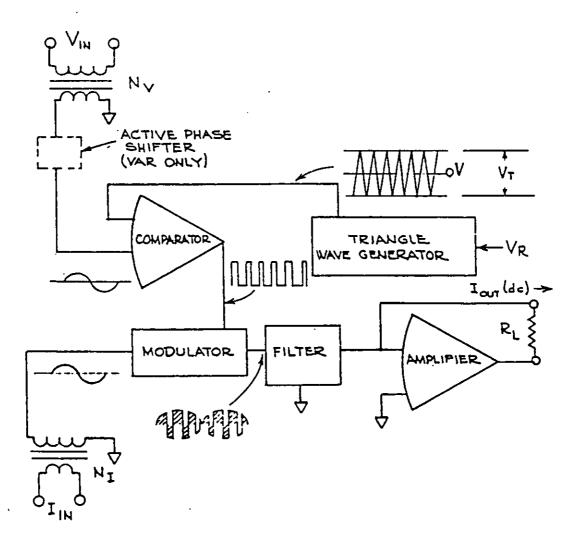
Voltage Outputs (0-10 V)

(Output impedance = 1000 ohms/V)

Variations from standard calibration will possibly require some specifications to be relaxed or changed to be applicable to the option requested.

THEORY OF OPERATION

The Exceltronic transducers use the time-division multiplier principle which depends on combined pulse-width and pulse-amplitude modulation of a rectangular pulse train. Referring to the block diagram, it is seen that the input v oltage, V_{in} , is ratioed downward by the potential transformer and converted into a variable pulse-width wave train by the comparator and triangle wave generator. In var transducers an active phase shifter introduces exactly 90 degrees phase shift just ahead of the comparator. The input current, I_{in} , is ratioed downward by the current transformer and is pulse-width modulated in the modulator by the comparator output signal. This pulse-width, pulse-height signal, whose average value is a dc current proportional to watts or vars, is filtered and fed to the external load by the unity gain output amplifier.



Simplified Block Diagram, Single Element Transducer

The input current signal is never converted to a voltage internally, hence offset voltages and other voltage errors and drifts have little influence on the accuracy and stability of the transducer and the need for a "zero" adjustment is eliminated. The output impedance is extremely high, making the output current practically unaffected by load resistance changes within the voltage compliance limitations of the amplifier.

Only the transformer ratios and the highly stable triangle wave voltage enter directly into the transfer function, resulting in excellent long-term stability and low temperature influence. The transformer ratios, of course, do not change and the triangle wave is controlled by a very stable reference zener diode.

The transfer equation for watt transducers is:

$$I_{out} = \frac{K I_{in} V_{in}}{V_T N_V N_I} \cos \theta$$

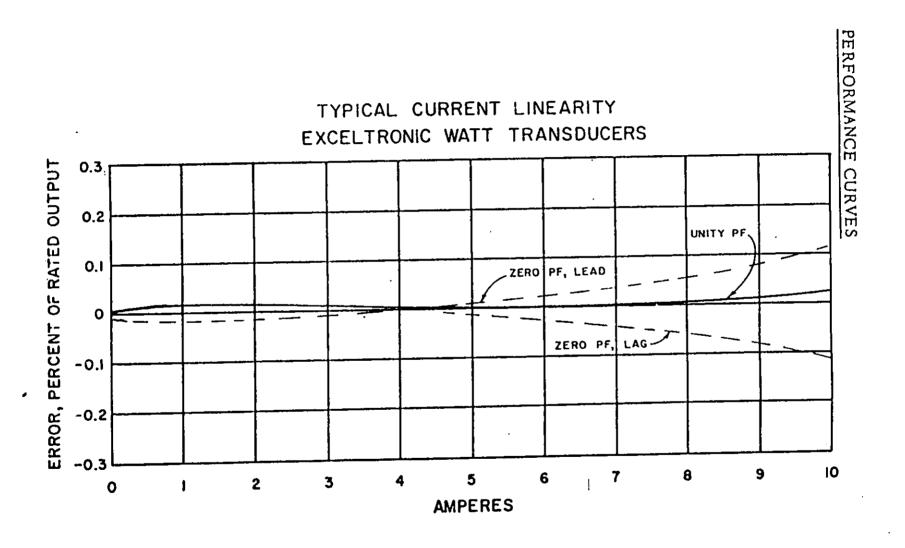
and for var transducers:

$$I_{out} = \frac{K I_{in} V_{in}}{V_T N_V N_I} \sin \theta$$

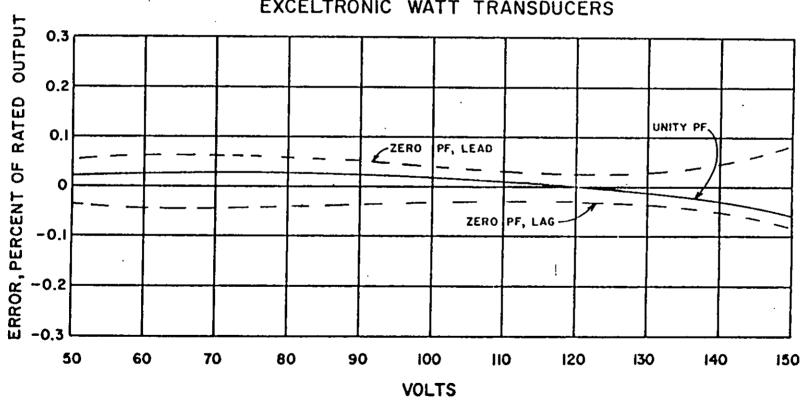
K is a proportionality constant and θ is the phase angle between V_{in} and $I_{in}.\ V_T$ is the triangle wave amplitude. N_V and N_I are the potential and current transformer ratios.

The input transformers are designed to give excellent linearities over wide operating ranges and are rated for 1,800 volts rms dielectric test. Burdens are very low; less than 0.1 VA and 0.2 VA for potential and current, respectively, at nominal input levels.

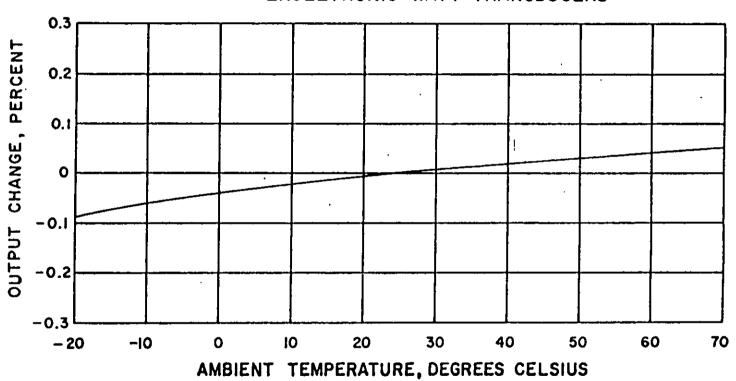
The power supply is well regulated and its burden is less than 1.5 VA at 120 volts. Line voltage variations from 85 to 150 volts have practically no influence on the transducer performance.



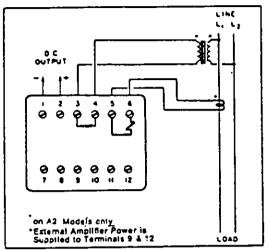
TYPICAL VOLTAGE LINEARITY EXCELTRONIC WATT TRANSDUCERS



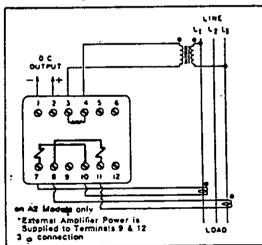
TYPICAL TEMPERATURE INFLUENCE EXCELTRONIC WATT TRANSDUCERS



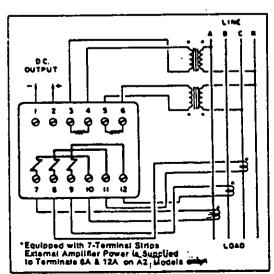
CONNECTION DIAGRAMS



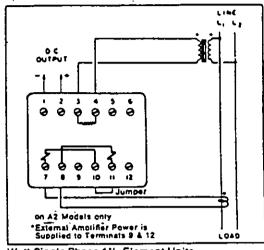
Watt or Var Single Phase One Element Units



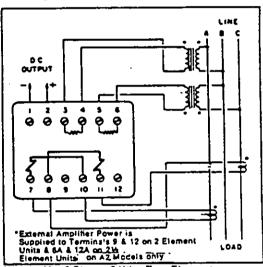
Watt Three Phase 11/2 Element Units



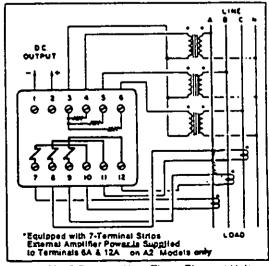
Watt or Var 3 Phase, 4 Wire 2½ Element Units



Watt Single Phase 11/2 Element Units

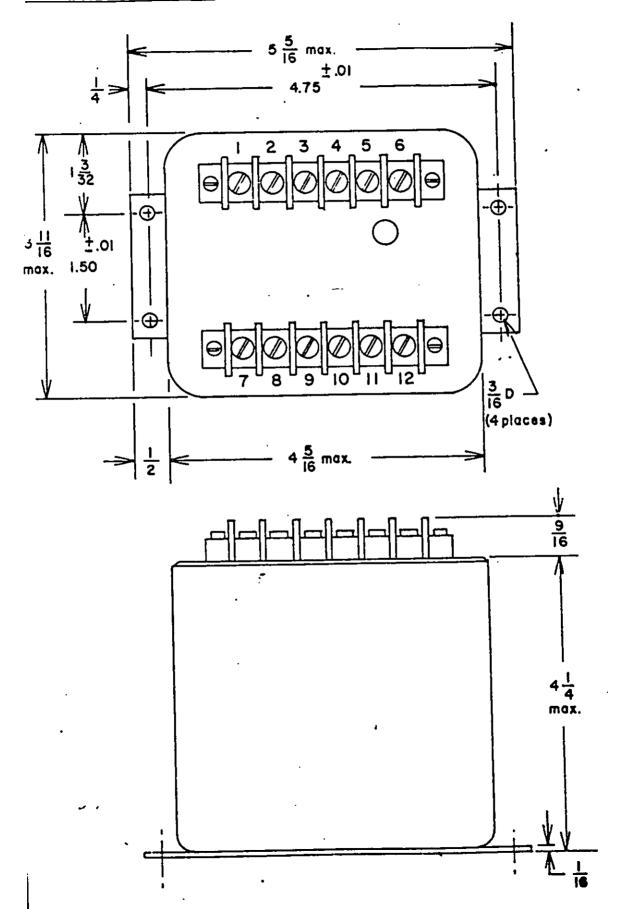


Watt or Var 3 Phase, 3 Wire Two Element or 2½ Element Units



Watt or Var 3 Phase, 4 Wire Three Element Units

* External amplifier voltage is not required on the A4 Series transducers.





EXCELTRONIC POWER TRANSDUCER

P SERIES

AN6 1-5 MA AN7 4-20 MA

AN8 10-50 MA

DESCRIPTION

SCIENTIFIC COLUMBUS HAS OVER 60 HIGH OUTPUT CONSTANT CURR. ENT TRANSDUCERS AVAILABLE FOR YOUR SELECTION, THESE TRANS-DUCERS MEASURE VOLTAGE, CURRENT, WATTS, VARS, FREQUENCY AND POWER FACTOR, WITH THE POPULAR OUTPUTS COMPATABLE WITH CONTROL EQUIPMENT.

ALL THE TRANSDUCERS CAN BE FIELD CONVERTED TO HAVE 1-5. 4-20, OR 10-50 MA OUTPUTS PROPORTIONAL TO INPUT. WHEN ORDERING ADOITHE SUFFIX ANGANZANG TO THE MODEL NUMBERS DESCRIBED IN THIS BULLETIN, THE UNITS WILL BE DELIVERED PRE-CALIBRATED FOR THE DESIRED OUTPUT, AND IS THE 1-5 MA CALIB

RATION; ANT IS THE 4-20 CALIBRATION; AND AND IS THE 10-50 CAL-IBRATION

CAUBRATION FOR THE WATT AND VAR MODELS MUST BE DESIG-NATED AS - U FOR UNIDIRECTIOAL WHERE ZERO WPUT RESULTS IN THE MINIMUM OUTPUT (1 MA OR 4 MA OR 10 MA RESPECTIVELY) OR -B FOR BI-DIRECTIONAL WHERE ZERO INPUT IS MID- RANGE OUTPUT I3 MA OR 12 MA OR 10 MA. RESPECTIVELY), THE MID-RANGE OUTPUT IS EASILY OBTAINED BY A JUMPER CHANGE AND A SLIGHT RECAUBRATION

SPECIFICATIONS COMMON TO WATT AND YAR MODELS

NOMINAL VOLTAG	SE INPUT	120 V	FREQUENCY RANGE	E (WATTS)	50-60 HZ
VOLTAGE RANGE	i	0-135V	FREQUENCY RANGE	FREQUENCY RANGE (VARS)	
PERMISSIBLE VO	LTAGE CVERLCAD	150 V	POWER FACTOR RA	NGE	ANY
VOLTAGE BURGE	N (PER ELEMENT)	0.05 VA AT 120V	TEMPERATURE RAN	IGE	0-50 °C
NOMENAL CURRE	NT INPUT	SA	TEMPERATURE EFF	ECT ON ACCURACY	± 0.0075 % / °C
PERMISSABLE CL	JRRENT OVERLOAD	10 A CONTINUOUS	ACCURACYAINEARI	TY @ 25°C	± 0.25 %
		250 A FOR 1 SEC	AC COMPONENT (P	TO P)	2.3 % MAX
CURAENT BURDE	IN (PER ELEMENT)	0.10 VA AT 5A	RESPONSE TIME		1 SECONO MAX
EXTERNAL POWE	IR RECUIRED	100- 13 0 V	ZERO ADJUST		± 5 % OF ZERO POINT
		50 HZ-500 HZ 8 VA	CALIBRATION ADJUS	STMENT	± 20 %
DELECTRIC TEST	1500	V RMS	ANS OUT PUT		1-5 MA INTO 0 TO 3000 Ω
			ANT OUT PUT		4-20 MA INTO 0 TO 750 D
CONNECTIONS		SEE REVERSE SIDE OF THIS SHEET	ANS OUT PUT		10-50 MÅ INTO 0 TO 300 Q
ADOMONAL SP	ECIFICATIONS FOR	WATT MODELS	ADOTTOHAL SP	ECIFICATIONS FOR	
MODEL NO."	CIRCUIT	FULL SCALE CAUSPATION WATTS	MODEL HO."	CROUT	FUIL SCALE CALIBRATION VARS
XL5C5P	10 2WIRE	500 WATTS	XLVSCSF	1 0 2WRS	SOC WARD
XLIKS	10 1WRE	1000 WATTS	XLV31K5P	3 0 4 WIRE	1000 VARS
XL31K52 V2 P	30 AWRE	1500 WATTS	XLV31K52 1/2 P	3 0 3 WRE	1500 VARS
X_342K5P	30 4WRE	1500 WATTS	XLV 342K5P	3 0 4 WIRE	1500 VARS

SPECIFICATIONS COMMON TO VOLT, CURRENT, POWER FACTOR, FREQUENCY, AND ISOLATION TRANSDUCERS

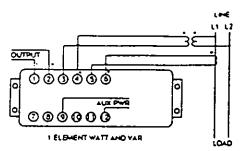
ADD SUFFIX ANK, ANT, ANE, TO MODEL NUMBER

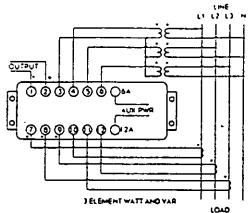
NOMINAL VOLTAGE INPUT	120 V	TEMPERATURE RANGE	0 · 50 °C
PERMISSABLE VOLTAGE OVERLOAD	150 V	TEMPERATURE AFFECT ON ACCURACY	11%
VOLTAGE BURDENS	3 VA MAX	ACCURACY / UNEARITY @ 25 °C	± 0.5 %
CURRENT CIRCUITS NOMINAL INPUTS	5.4	AC COMPONENT (P-P)	105% MAX.
PERMISSABLE CURRENT OVERLOAD	10 A CONT	RESPONSE TIME	1 SEC MAX
	250 FOR 1 SEC	ZERO ADJUST	15% OF ZERO POINT
CURRENT CIRCUIT BURDENS	3 VA	CALIBRATION ADJUST	± 20 %
EXTERNAL POWER REQUIRED	100 - 130 V	ANE OUTPUT	1-5 MA WTO 0 - 3000 D
	50 TO 500 HZ 8 VA	ANT OUT PUT	4-20 MA INTO 0 - 750 D
DIELECTRIC TESTS	1500 Y RMS	ANS OUT PUT	10 - 50 MA INTO 0 - 300 ft
(ISOLATION UNIT) INPUT TERMINALS	4000 V D C	1	

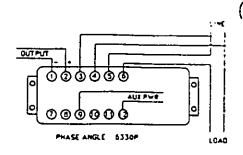
SPECIACATION	IS:VOLTS, CURRENT, FREQUE	ENCY POWER FACTOR	ISOLATION AMPLIFIER
<u> </u>	THE COLCOL	HOOR HO	TYPE

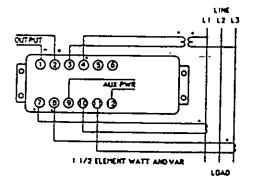
[.] ADD SUFFIX ANS, ANT, ANS, TO MODEL NUMBER

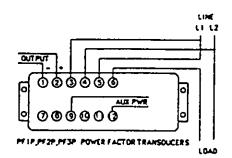


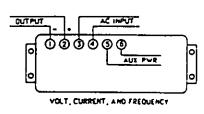


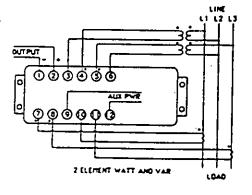


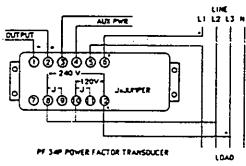


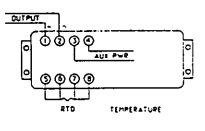


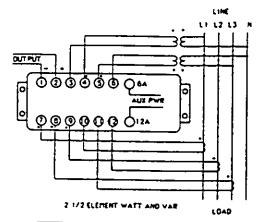


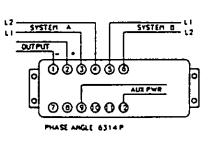


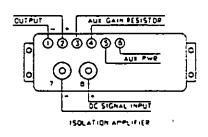














ANALOG TO BINARY CODED RELAY OUTPUT CAD-1941

Description:

The Model CAD1941 Converter was designed to provide a binary coded relay contact closure for a zero to 1 mA dc input signal. The relay outputs represent the 7 bit binary logic of the input signal.

The output relays are commoned at terminal 16 and individually brought out at terminals 9 through 15, with terminal 9 "LSB" and terminal 15, the "MSB".

Each relay contact is protected with an RC network of .22 ufd and a 249 ohm resistor.

The external sample input voltage is required to be activated before reading the coded outputs. When the input pulse of 24V dc is applied to this input, an internal signal is fed to the ADC converter which updates all output relays. The output relays will remain in the new state until another input sample pulse is initiated.

The maximum sample rate is 50 milliseconds. The external sample pulse width should be less than 25 milliseconds to accomplish this rate.

Specifications:

Model CAD1941

Input: Signal Max

0 to 1 mA dc 0 to 1.2 mA dc

*Load

10K ohm

**External Sample Voltage

24V ± 5V

Sample pulse width

< 900 MSEC for 1 Sec rate

Output:

Signal

7 bit binary

Relay

7 normally open

Contact Rating

15VA Max., 1A, 50Vdc

Accuracy

± 1.0% RO

Temperature Range

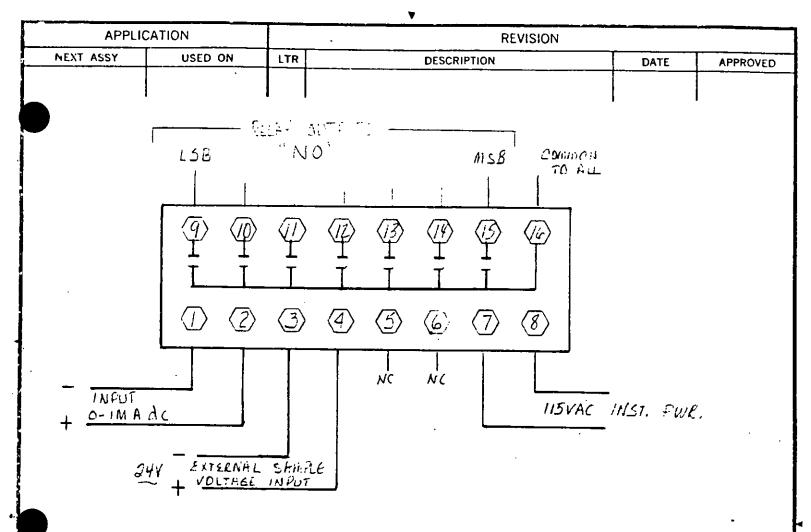
0 to 50°C

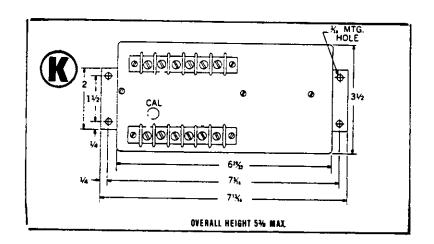
Instrument Fower Required

115VAC ± 10% 60 Hz

* Note: (1) This input resistor can be changed, via terminal 1 & 2, for direct reading in engineering units. Resistor is internally mounted.

**Note: (2) This input is isolated via photo-coupler.





UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES TOLERANCES ARE:	D CONTRACT NO.		OHIO SEMITRONICS INC					
FRACTIONS DECIMALS ANGLES ± .XX ± ±	APPROVALS	DATE	1	1205 Ches	sapea	ke Ave (Col. OH. 43	3212
± .xxx ± ± .xxx ±	DRAWN		Ţ					
MATERIAL	CHECKED D. Miller	11-30-83	1	CONNECT	ridws	F DIM	. WOIZNZI	DIAGRAMS
	20111722147	30.00	1		CAI	3-1941		
TINISH		1	SIZE	CODE IDEN	T NO.	DRAWING	NO.	
111136			Α					
DO NOT SCALE DRAWING	1	•	SCALE			<u> </u>	SHEET	OF
BISHOP GRAPHICS, INC.	<u> </u>		<u> </u>					

Instructions For Type MME Contactor 10, 25, 50, 100 or 150 Amperes, DC 600 Volts, Maximum



THE CONTACTOR

Each type MME contactor is a front-connected industrial contactor rated for DC applications up to 600 volts. They are available in several configurations.

This industrial type control is designed to be installed, operated, and maintained by adequately trained people. These instructions do not cover all details, variations, or combinations of the equipment, its storage, delivery, installation, check-out, safe-operation, or maintenance. Care must be exercised to comply with local, state, and national regulations, as well as safety practices, for this class of equipment.

Each structure has a 150 ampere DC continuous rating, but to match the contactor to the load for maximum contact life, the contactor is supplied with either a 10, 25, 50, 100, or 150 ampere blowout coil from the factory. In addition the 10, 25, and 50 ampere versions have different main contact springs and operating coils than the 100 and 150 ampere units. See Table I for identification information.

Each operating coil is designed for continuous duty at full voltage and does not require the insertion of a series resistor after pick-up. The design is such that the contactor will pick-up and seal at 80% of rated voltage when the coil is hot, i.e., at operating temperature. The coil will also stand 110% of rated voltage without burnout. Note that the normal operating temperature of an industrial contactor coil is higher than boiling water, so do not be alarmed by this temperature.

The Type MME 11 has one normally-open and one normally-closed main contact and two operating coils. The normally-closed contact at the bottom will not completely seal until the lower coil is energized. The control circuit must be designed to continuously energize either the top coil or the bottom coil. Both coils must not be deenergized at the same time because the lower main contact does not have adequate contact pressure unless the lower coil is energized.

The MME contactor line is also intended as a replacement for earlier rear-connected contactors Type M and MM. This requires the use of one rear-connection kit 2184A10G08 for each MME contactor. Instructions for the conversion are included in the kit.

TABLE I-CURRENT RATINGS					
FRONT CON	NECTED TYPE MME CO	NTACTORS			
Contactor Type Identification (Less Coil)	Pole and Contact Arrangement NO = Normally Open NC = Normally Closed				
MME 01-10	1 NC	10			
MME 10-10	1 NO	10			
MME 20-10	2 NO	10			
MME 11-10	1 NO/1 NC	10			
MME 01-25 MME 10-25 MME 20-25 MME 11-25	* 1 NC 1 NO 2 NO 1 NO/1 NC	25 25 25 25 25			
MME 01-50	1 NC	50			
MME 10-50	1 NO	50			
MME 20-50	2 NO	50			
MME 11-50	1 NO/1 NC	50			
MME 01-100	1 NC	100			
MME 10-100	1 NO	100			
MME 20-100	2 NO	100			
MME 11-100	1 NO/1 NC	100			
MME 01-150	1 NC	150			
MME 10-150	1 NO	150			
MME 20-150	2 NO	150			
MME 11-150	1 NO/1 NC	150			

AUXILIARY CONTACTS

Each MME contactor can accommodate two Type L46 auxiliary contacts. Type MME 11 double-throw contactors (1 NO/1 NC) can mount two L46's per throw. When ordering auxiliary contacts specify Type L46, the mode (Normally-Open or Normally-Closed), and the type designation of the MME contactor on which the auxiliary contact is to be mounted. See Table II for auxiliary contact ratings.

							
TABLE II -	TABLE II - AUXILIARY CONTACTS						
L46 CONTACT RATINGS							
DC Volts	Make	Break					
10-20	10A	10A					
20-600	200 VA	200 VA					

INSTALLATION

The MME contactor is intended to be mounted on a vertical flat metal panel. The two mounting holes have a ¾ inch diameter. Use .312" dia. steel mounting bolts with a flat washer against the plastic base and a lock washer under the head. When the contactor is mounted in position, there must not be any grounded, any energized, or any combustible part inside of the minimum arcing clearance (dotted-line shown on Figures 2, 3, 4 or 5) which is the exhaust pattern of the arcbox.

Like most DC contactors, the frame of the Type MME is at line potential when the contactor is energized. Gases and flashes of light from the arcbox can also be hazardous. Make the installation accessible only to authorized and trained personnel.

Before mounting the contactor on the panel, make sure all curcuits on the panel are de-energized. Check Table I to see that the voltage and current ratings of the contactor agree with the application. Next. check the label on the operating coil to see that its rated voltage agrees with the coil supply voltage to the panel. Finally, insure that the auxiliary contacts have the correct electrical function (normally-open or normally-closed) and the correct physical arrangement to agree with the wiring diagram.

After the contactor is mounted to the panel, temporarily withdraw each arcbox by disengaging the flat spring latch on the right side of the arcbox, and pulling the arcbox forward, away from the panel, toward you. The arcbox will be restrained by its polarizing shunt and need not be completely removed. It can be allowed to dangle for the time being.

With the arcbox clear, connect the line cable to the line terminal(s), using a lug for the cable and steel hardware in the clearance hole in the terminal. Refer to Figures 2, 3, 4 or 5 for the location of the .343" dia. or .281" dia. terminal holes on the contactor. Do not use hardware any longer than necessary. Make certain there is ½ inch clearance between the hardware and the mounting panel.

Next connect the load cable to the load terminal at the bottom or center of the contactor, using similar hardware and maintaining at least ½ inch clearance.

With the panel still de-energized, operate the contactor by pushing on the top of the moving armature toward the panel with a screwdriver. The moving system should move freely on its bearing with no mechanical interference or rubbing.

REINSTALL THE ARCBOX BY SLIDING IT BETWEEN THE BLOWOUT IRONS UNTIL IT ENGAGES THE SPRING LATCH AND IS LOCKED. Check the moving armature again by pushing with a screwdriver to make certain the moving system can move freely, both in closing and opening movements.

Make the connections to the coil terminals and the auxiliary contact terminals.

The contactor is now ready for service. Precautions during the first power operation should be in accordance with safety practices appropriate to the application, and should be under the control of authorized and qualified personnel.

MAINTENANCE

This industrial type control is designed to be installed, operated, and maintained by adequately trained people. These instructions do not cover all details, variations, or combinations of the equipment, its storage, delivery, installation, check-out, safe-operation, or maintenance. Care must be exercised to comply with local, state, and national regulations, as well as safety practices, for this class of equipment.

Make certain that the contactor and panel are completely de-energized before attempting any maintenance or repair.

It is recommended that the contactor be examined at regular intervals so that preventive maintenance



can be done. The frequency of examination will depend on how many interruptions per hour or per day the contactor must withstand. Ten to twenty operations per hour would suggest weekly examinations; ten to twenty operations per day would indicate examination every three or four months. In the beginning, examination should be relatively frequent until some history has been developed.

ARCBOX INSPECTION

Withdraw the arcbox after unlatching and turn it over so that the inside can be observed. Some erosion, producing a whitish color is normal, as are some streaks of smoke. However, if the erosion produces cavities that might become holes through the arcbox wall, or if the inside is glazed with metal globules or glass-like melted areas, the arcbox should be replaced.

To completely remove the arcbox, it is also necessary to remove the screw securing the end of the polarizing shunt to the frame.

CAUTION: NEVER OPERATE CONTACTORS WITHOUT ARCBOXES LATCHED IN PLACE AND POLARIZING SHUNTS FASTENED TO THE MAIN FRAME.

CONTACTS

It is normal for contacts to show some burning and mechanical abrading. Every time the contactor operates, some material is lost from the contacts. When the contactor has operated so many times (and lost so much material) that the moving and stationary contact faces barely touch each other, then the contacts must be replaced.

The allowance for contact face wear is called "overtravel". When the Type MME contactor is new the overtravel is at full value. When the overtravel has decreased to the minimum acceptable shown in Figure 1 the contacts must be replaced.

After a particularly difficult interruption, a contact may develop beads of metal. Such beads can be removed with a file and if the overtravel is still within limits, the contactor can be returned to service. There is no need to try to file out every blackened pit in a contact.

However, if either contact face is eroded so that the silver alloy is gone and only copper remains, that contact must be replaced even if the overtravel is within limits.

Contact springs generally do not need attention unless they get burned by a bad interruption, or unless they simply wear out mechanically. Do not try to adjust a spring. If it needs attention, replace it. Order replacement contacts and contact springs in kit form, one kit per pole. See Table III.

ARMATURE

The armature uses a knife edge bearing which should outlast the rest of the contactor. It is intended to operate without fubrication so that it does not collect abrasive dust. The only maintenance required is to make certain that the moving armature does in fact move freely without interference or binding.

OPERATING COIL

If the operating coil is to be changed or replaced first de-energize the panel and disconnect the coil terminals. Then unlatch the arcbox and withdraw. Next loosen the two bolts holding the arcbox and the moving system, which will then hang from the contactor suspended by the main current shunt. It is then obvious that the pole face screw and pole face can be removed to remove the coil. Keep track of the parts removed and replace them in the reverse sequence with the replacement coil. Make certain when the replacement is complete, that the moving system moves freely and the arcbox is fully installed.

REPLACEMENT DEVICES

Order replacement devices and coils by type designation shown on the name-plate, which is coded as shown in Table I. Specify the coil operating voltage. The contactor type number does not include auxiliary contacts (electrical interlocks), which must be specified separately, by contact arrangement.

Example:

One-Type MME 10-50 with 250 volt DC coil and one normally-open auxiliary and one normally-closed auxiliary.

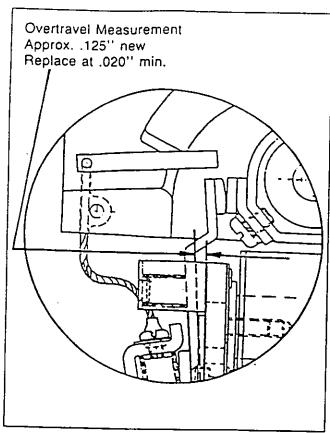


Fig.	1	Measuring	Contact	Overtravel
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Pole Arrangement	Renewal Part	Renewal Part No.
All	Contact and contact spring kit (1 pole)	2184A10G14
2 NO	Contact Support Kit	2184A20G17
2 NO	Shunt Replacement Kit	2184A20G16
1 NO/1 NC	Shunt Replacement Kit	2184A11G07
1 NO	Shunt Replacement Kit	2184A10G21
1 NC	Shunt Replacement Kit	2184A10G21
2 NO	Armature Kit	2184A20G15
1 NO/1 NC	Armature Kit	2184A11G06
1 NO	Armature Kit	2184A10G19
1 NC	Armature Kit	2184A10G19
Ali	Coil Mounting Kit	2184A10G20

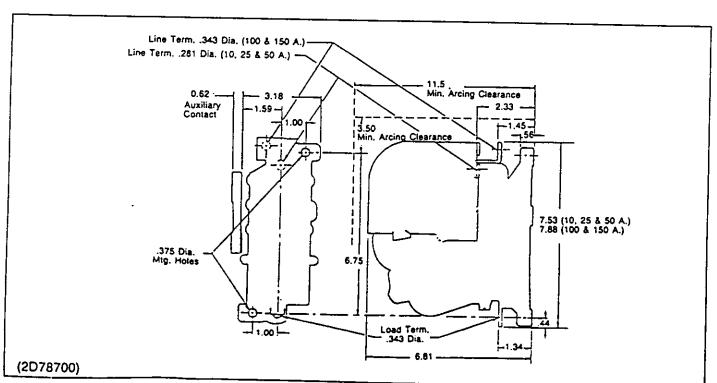


Fig. 2 Dimension Drawings (Dim. in inches) of 1 NO Pole MME Contactor

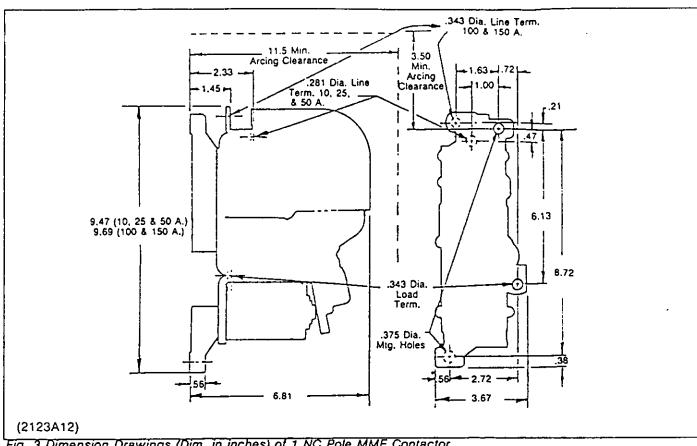


Fig. 3 Dimension Drawings (Dim. in inches) of 1 NC Pole MME Contactor

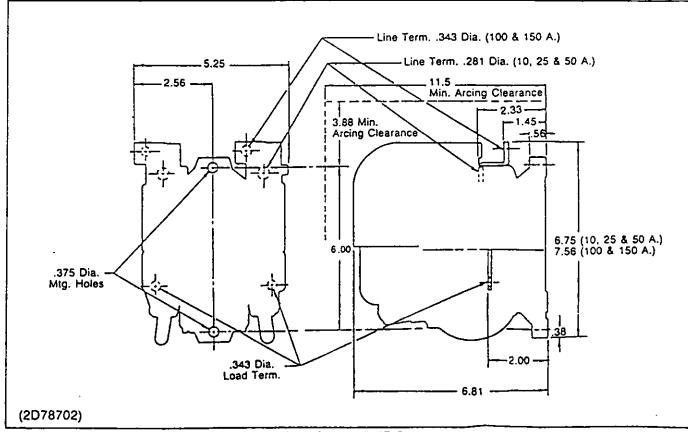


Fig. 4 Dimension Drawings (Dim. in inches) of 2 NO Pole MME Contactor

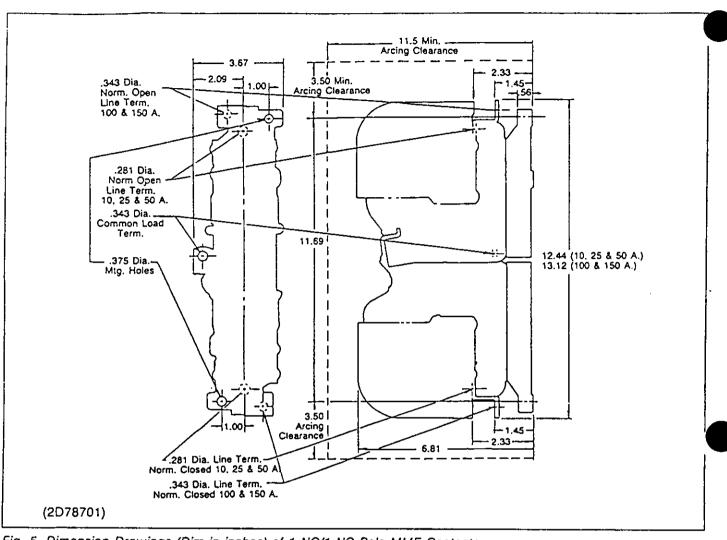


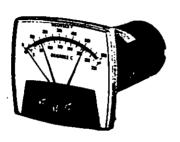
Fig. 5. Dimension Drawings (Dim in inches) of 1 NO/1 NC Pole MME Contactor

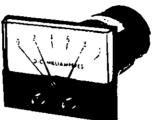
Process Control Division 55 Green Street

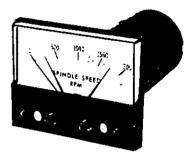
Clinton, Massachusetts 01510 CORPORATION (617) 835-1000

INSTRUCTION MANUAL .

195 & 196 SERIES METER RELAY CONTROLLERS 955-242 2284







195 SERIES Dual Setpoint

196 SERIES Dual Setpoint

196 SERIES Dual Setpoint with Manual Reset

Fig. 1 195 and 196 SERIES Meter Relays

INTRODUCTION

These instructions cover the installation of 195 Series Meter Relays in three sizes and 196 Series Meter Relays in two sizes.

195 and 196 Series Meter Relays consist of two separate units, an indicator setpoint unit and a control unit. The indicator setpoint unit is basically an electric indicating panel instrument, to which has been added control point indication and initiation. The indicator setpoint unit has control point adjustment knob(s), control point indication pointer(s), light sensor(s), lamp and light shield. The control unit consists of a DPDT load relay for each setpoint and supplies power to the lamp and light sensor(s) in the indicator setpoint unit.

OPERATION

Operation is based on the characteristics of a light-sensitive solid-state sensor, which is effectively CLOSED with light incident upon it and is effectively OPEN when shielded from the light. One of these sensors is attached to each setpointer and is connected to a transistorized switch circuit in series with a load relay coil. The light shield, carried by the indicating mechanism, controls admission of light to the sensor, causing the load relay(s) to be energized or de-energized strictly in accordance with POSITION of the indicating pointer with respect to the setpointer(s).

For ON/OFF control action (automatic reset), as shipped from the factory, the sequence of operations is as follows: The setpoint(s) (low = blue, red = high) are positioned at desired points on the scale by use of knobs located on the indicator front. With power connected to the control unit, operation of the load relay(s) is in accordance with POSITION of the indicating pointer as shown in Table I.

TABLE I
MODE OF OPERATION OF RELAY(S)

	HIGH (RE	D) SETPOINT	LOW (BL	UE) SETPOINT
INST. POINTER RELATIVE TO SETPOINTS	LIGHT- SENSOR	LOAD RELAY	LIGHT- SENSOR	LOAD RELAY
Downscale (LEFT) from Setpoint(s)	Light	Energized	Dark	De-energized
Between Setpoint(s)	Light	Energized	Light	Energized
Upscale (RIGHT) from Setpoint(s)	Dark	De-energized	Light	Energized

In addition to DC and AC (rectifier) measurement models, meter relays can be supplied as pyrometers. These pyrometers have bimetallic cold-junction compensation.

MANUAL RESET

Front Panel - The 4½-inch size 196 Series Meter Relay can be supplied with built-in manual reset push buttons on the face of the instrument. The unit shown in Fig. 1 has a double setpoint; however, a single setpoint (high or low) can be supplied also. The manual reset provides an alarm light adjacent to the push button which lights when the setpoint is tripped. The alarm light is extinguished and load relay is energized when the manual reset push button on the front panel is pressed and the indicating pointer is in a position to admit light on the sensor to provide the control action indicated in Table I.



External (User Supplied) - All sizes of 195 and 196 Series Meter Relays can be provided with manual reset action by the connection of user-supplied, momentary contact switch(es) to the appropriate terminals and by the removal of jumper(s) as indicated in Fig. 2. Thus, when the relay is tripped, the load relay cannot be re-energized again until (a) the indicating pointer is in a position to admit light to the sensor per Table I and (b) the external (normally open) momentary push-button switch is pressed.

IMPORTANCE OF PERIODIC OPERATIONAL CHECKS

Operational reliability can be increased by periodic testing of the meter relay as described below.

- 1. The setpoint tripping function should be tested periodically. Each setpoint on a two-set unit should be tested separately since each setpoint has its own circuitry. The simple test consists of manually rotating each setpoint beyond the instrument pointer to determine if the output relay contact opens or closes, as it should.
- 2. Determine that the mechanism pointer drops freely to 0 and returns to its original scale position without any hesitation or signs of sticking by removing and returning the input signal to the instrument.

The frequency of such a periodic operational check should be determined by the user, based on his application and the potential impact of a meter relay malfunction. An instrument which fails to meet the above checks should be removed for service by qualified instrument service personnel.

The adjustment potentiometers on the small transistor switch circuit board inside the indicator setpoint unit are sealed at the factory and should not be adjusted.

CAUTION

Improper adjustment of the potentiometers could result in setpoint trip failure (relay continuously energized) regardless of pointer position.

SPECIFICATIONS

SETPOINT COINCIDENCE ERROR: ±2% F.S.

REPEATABILITY: 0.3%, F.S.

CURRENT INPUT SIGNALS: For measured currents above 20 mA AC, an auxiliary transformer must be used, except for models with an internal 5 amp current transformer. Digits 5 and 6 in the part number designate internal or external transformer. LS indicates internal current transformer. HF indicates external transformer required.

VOLTAGE INFLUENCE: 0.75% max. change with 10 volt change (from 117VAC reference)

INDICATING POINTER TRAVEL: The indicating pointer will indicate accurately above or below either setpoint.



- LOAD RELAY: a. Three-pole double-throw for each setpoint. Only two poles/setpoint available for external connections. (See external connections, Fig. 2.) Only one pole/setpoint available on self-contained manual reset models.
 - b. Contact Rating: 5 amps AC non-inductive at 120V; 5 amps DC non-inductive at 28V.

CAUTION

The output relay contacts are silver and silver cadmium oxide for reliable operation in non-inductive circuits up to 5 amps at 120VAC or 28VDC. Normal energy levels of voltage and current aid in breaking down non-conducting contact surface films. Therefore, use of the meter relay contacts is not recommended at low energy levels such as millivolt signal circuits or logic circuits. Contact performance will vary depending on meter relay environment.

MOUNTING POSITION:

Indicator Setpoint Unit:

Standard: Scale vertical

Optional: Any with special calibration

Control Unit: No position influence

AC POWER SUPPLY FOR CONTROL UNIT: (See note below.)

Minimum

Nominal

Maximum

107V, 50/60Hz 117V, 50/60Hz,

117V, 50/60Hz, 7.0 VA Max. 127V, 50/60Hz

for either single or double setpoint unit

NOTE: If the load being controlled causes a voltage drop of more than 2 volts in the AC voltage supply for the meter relay, the meter relay supply should be taken from a different source to prevent "hunting" of the control system.

CONTROL POINT BAND: Less than 1% F.S.

FREQUENCY INFLUENCE: 0.3% max. change, 60Hz to 45Hz or 60Hz to 65Hz CONTROL ACTION: Automatic on/off action (Automatic Alarm Reset). If

alarm or limit control action (Manual Alarm Reset). If alarm or limit control action (Manual Alarm Reset) is desired, the user can provide it be removing jumper wires and adding momentary-contact or push-button switches as shown in Fig. 2. If built-in manual reset option is supplied and automatic reset in desired, connect jumpers across Terminals 1, 2 and 3 per Fig. 2.

LAMP: Expected life five years. Output relay becomes de-energized on lamp failure and setpoint trip does not operate. This failure is normally self indicating.

DIELECTRIC TEST: Live parts to face and panel--2,600 volts RMS.

INSTALLATION

MOUNTING

NOTE: All drilling of the panel should be completed before the unit is mounted. (See Figures 6, 7, 8, 9, 10, 11 and 12)

- 4 -



195 and 196 Series Meter Relays are sturdily constructed and will withstand reasonable amounts of vibration and handling. If panel vibration is enough to cause false pointer indication, or if severe mechanical shock is expected in operation or shipping, mount the control unit separately to reduct the effect of the length and weight of the combined assembly.

CAUTION

Control Unit identity number must be as noted on the setpoint unit rating plate.

The indicator setpoint unit contains its own shielding and can be mounted on magnetic or nonmagnetic panels without special calibration.

The 3½- and 4½-inch sizes may be mounted as a unit (see Figures 6, 7, 9, 10, 11 and 12) or the control unit may be mounted separately from the indicator setpoint unit. (See Fig. 8 for separate mounting of the control unit.) The 2½-inch size (195 Series only) requires separate mounting of the control unit with a bracket and a connection cable, which are furnished with this size. (See Fig. 8.)

ACCESSORIES FOR OPTIONAL REMOTE CONTROL UNIT

Accessory kits for installing the control unit remotely are available:

NOTE: Kits described below cannot be used on meter relays with self-contained manual resets.

Kit, Cat. No. 1125-426 - This kit contains plug, socket, wiring connection diagram, bracket and hardware for the meter relay. The user must supply and construct the cable of the desired length by soldering the insulated cable leads to plug and socket. The wire gage of the cable must be selected to provide each conductor with a resistance of 0.1 ohm or less. The following table can be used as a guide for this 0.1 ohmper-lead determination.

AWG SIZE	MAX. CABLE LENGTH
18	19 feet
20	12 feet
22	7 feet
24	4.5 feet
26	3.0 feet

Kit, Cat. No. 1125-425 - This kit contains a six-foot cable with plug and socket connectors soldered to cable, plus bracket and hardware. (This kit is furnished as standard equipment with 24-inch meter relays.)

CONNECTIONS

All wiring must comply with local codes, regulations and ordinances. No internal fusing is provided in the meter relay.

DO NOT MAKE CONNECTIONS WHILE POWER IS APPLIED TO EITHER THE POWER SUPPLY TERMINALS, THE CONTROL RELAY TERMINALS OR THE MEASUREMENT TERMINALS.



INDICATOR SETPOINT UNIT

Connections to the circuit being measured are made at terminal studs on the back of the case of the indicator setpoint unit. (See Fig.4.) The left-hand stud (rear view) is always positive. The contact surface of nuts, washers and cable terminals must be thoroughly clean to insure good contact.

Connections between the indicator setpoint unit and the control unit are made through a built-in connector and socket when the control unit is mounted "piggy-back" on the indicator setpoint unit (3½- and 4½-inch size) or by a prewired cable assembly for the 2½-inch size or when the control unit is mounted remotely with other sizes.

AUXILIARY CURRENT TRANSFORMER

All $2\frac{1}{2}$ -inch meter relays and some other models with 20 mA AC rating require an auxiliary current transformer.



These models must not be connected without the auxiliary current transformer.

The transformer (Part No. 2062-150) is rated for 20 mA output with 5 amp input with a burden of 2.5VA. See Figures 13 and 16 for connections and dimensions. Models requiring this transformer are identified by HF in digits 5 and 6 of the part no. (example V3-12HF-CD00).

Other models have an internal 5 ampere transformer. These models do not require the auxiliary current transformer (example - Fart No. V3-12LS-CD00).

CONTROL UNIT

Terminals for the 117 VAC, 60Hz power supply for the double-pole, double-throw relays (one per setpoint) and for the alarm or limit control action are on the back of the control unit. Each terminal is supplied with a No. 6-32 pan head machine screw. (See Figures 2 and 3 for terminal layout.)

The relay terminals are entirely passive and are completely isolated from either the measured circuit or the power supply circuit. (See Table I and Fig. 2 for relay operation.)

ADJUSTMENTS

The following zero adjustments may be necessary in some cases due to a shift in zero position because of shock in transportation. Also, pyrometers must be adjusted for total thermocouple resistance.

The meter relay should be in its operating position when any such adjustment is made ("nominal" voltage is power supply voltage identified on rating plate).

Ammeters and Voltmeters

- Zero on Scale Check mechanical zero; adjust pointer to zero with zero signal applied.
- Suppressed Zero Apply end-scale signal and adjust pointer to correct indication.





Pyrometers

1. Adjustment of Thermocouple Resistance

NOTE: Total thermocouple resistance may be equal to or less than the lead resistance printed on the scale of the indicator setpoint unit. A small resistor is mounted on the back of the case of the indicator setpoint unit. This resistor is connected in series with the thermocouple and its resistance must be adjusted until the resistance of the thermocouple plus resistor is equal to the lead resistance printed on the scale of the indicator setpoint unit. (See Fig. 4.)

Method of Adjustment

Connect negative (-) thermocouple wire to the smaller of the two terminals which support the resistor. Connect an ohmmeter to the larger of the two terminals, which support the resistor, and to the positive (+) thermocouple wire.

DO NOT connect the positive (+) thermocouple wire to the instrument until resistance adjustment is complete.

The resistor is a double wound, pull off style of approximately 10 ohms. Wire can be removed from the body of the resistor without unsoldering. Resistance of the thermocouple-resistor combination is reduced by unwrapping the looped end of wire from the resistor and shorting between the wires. Continue to remove wire and short between the wires until the resistance of the thermocouple and resistor equals the resistance specified on the scale.

Connect the positive (+) thermocouple wire to the positive (+) terminal of the indicator setpoint unit.

2. Zero Adjustment

- a. If meter relay has no T/C break protection, de-energize control unit, disconnect T/C (leave input circuit open), and adjust instrument zero adjustor until pointer indicates ambient temperature; then T/C can be reconnected and control unit energized.
- b. If meter relay has T/C break protection, connect T/C to appropriate terminals, but expose T/C to ambient temperature only, and energize control unit for one-half hour; then, adjust instrument zero adjustor for instrument pointer indication of ambient temperature, if necessary.

NOTES: FOR PYROMETERS WITH T/C BREAK PROTECTION

- With or without T/C connected, and with control unit de-energized, instrument pointer will be off scale below zero. DO NOT adjust zero adjustor.
- With T/C disconnected and with control unit energized, instrument pointer will be beyond full-scale mark. DO NOT adjust zero adjustor.

Adjustment of Control Point

Process Control Division

This adjustment is made using the knob(s) mounted on the front of the indicator. The setting of the control point(s) is indicated by the position of the setpointer. Control action will occur as the indicating pointer passes over the setpointer(s) scale position.

The setpoint(s) may be adjusted from zero to full scale and do not interfere with the indicating pointer. Double setpointers may be positioned to within two angular degrees of each other which is approximately 2% of full scale. Unless otherwise specified on the order, the operation of the setpoints may overlap when the setpoints are brought to their minimum mechanical distance apart.



For best accuracy, allow at least ten minutes warm-up (with lamp energized) before making final setpoint adjustment. This improves the accuracy approximately 0.5%. To check setpoint accuracy, the nominal supply voltage must be used.

MAINTENANCE



DO NOT REMOVE RED LABELS OR USE METALLIC PROBES TO ADJUST CONTROL POINT THROUGH HOLES IN THE SIDE OF INDICATOR SETPOINT UNIT (FRONT UNIT). INTERNAL COMPONENTS MAY BE AT DANGEROUS POTENTIALS. THIS ADJUSTMENT SHOULD BE DONE BY FACTORY OR AUTHORIZED REPAIR PERSONNEL.

To clean the plastic window, wash it with soap and water. To remove grease or oil, use kerosene sparingly. DO NOT use acetone, benzene, carbon tetrachloride, fire-extinguisher fluids, lacquer thinners, or window sprays containing these solvents since they will smear or soften the window.

Wipe the window periodically with a clean, damp chamois. Do not rub with a dry cloth as this is likely to cause scratches and to build up an electrostatic charge which will cause erroneous readings. After cleaning, an antistatic agent should be applied to the window to neutralize any electrostatic charges.

PARTS REPLACEMENT

The 195 and 196 Series Meter Relays utilize a special lamp with leads attached to the lamp and lamp holder assembly (LFE Part No. 1207-246). These replacement parts can be ordered through any authorized LFE distributor or modification center. The lamp is selected and adjusted in the lamp holder in the factory and substitutions should not be made.

In the event of lamp failure, the lamp assembly can be replaced when the control unit is detached from the rear of the indicator setpoint unit, or the cable plug from the remotely located control unit is disconnected. Then, the lamp-access plate (see Fig. 4) must be removed (screws are beneath adhesive labels) to expose the lamp holder which can be pulled out.

PART NO. 1207-246 LAMP AND HOLDER

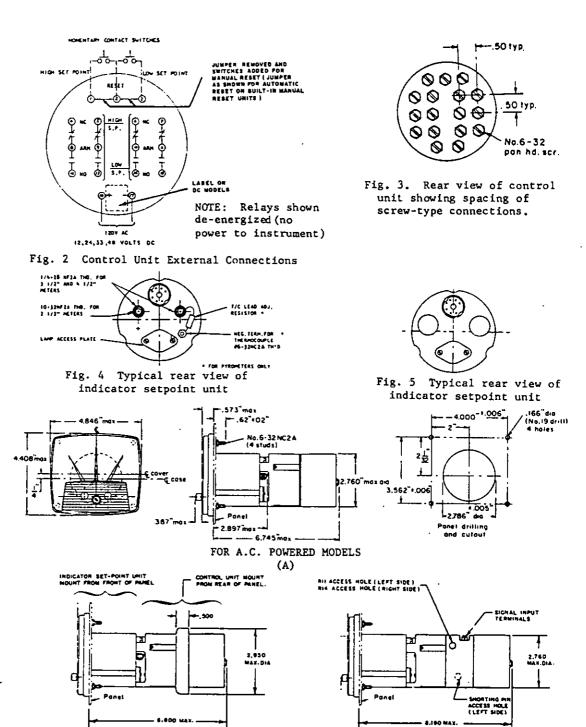
The Part No. 1207-246 lamp has been fixed in the lamp holder at the factory such that the filament will be in the correct position when the keyed assembly is inserted in the indicator setpoint unit. Make sure the lamp-lead terminals are engaged by the screws when the lamp access cover is replaced. (NOTE: If relay operation is not within ±2% of setpoint index, the lamp holder position must be rotated 180°.)

REASSEMBLY

After the new lamp assembly has been installed, make sure the lamp access plate is replaced (and screws are tight) before cable plug from remotely located control unit is reconnected, or control unit is reassembled on rear of indicator setpoint unit.







(NOTE: - OUTLINE DIMENSIONS FOR D.C. MODELS AND SIGNAL AMPLIFIER MODELS APPLY TO ALL SIZES OF METER RELAYS)

FOR SIGNAL AMPLIFIER MODELS

(C)

Fig. 6 195 SERIES Meter Relay, 4½-inch, with control unit rear mounted

- 9 -

CONTONATOR

Process Control Division

FOR D.C. POWERED MODELS

(B)

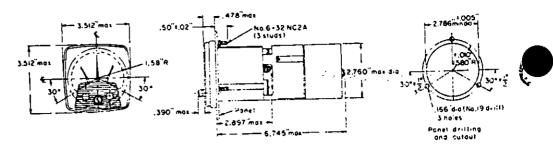


Fig. 7 195 SERIES Meter Relay, 34-inch, with control unit rear mounted

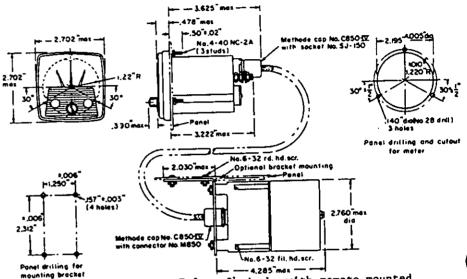


Fig. 8 195 SERIES Meter Relay, 2½-inch, with remote mounted control unit due to small meter size. Remote mounting is the same for all 195 and 196 SERIES if desired.

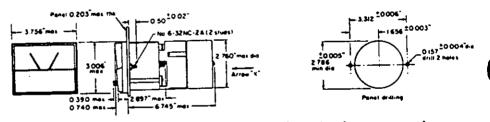


Fig. 9 196 SERIES Meter Relay, 3½-inch, front mounted

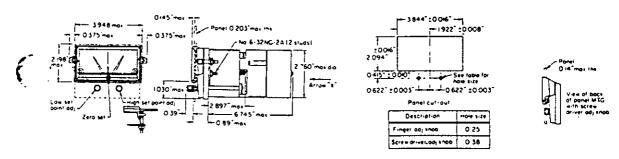


Fig. 10 196 SERIES Meter Relay, 3½-inch, window mounted

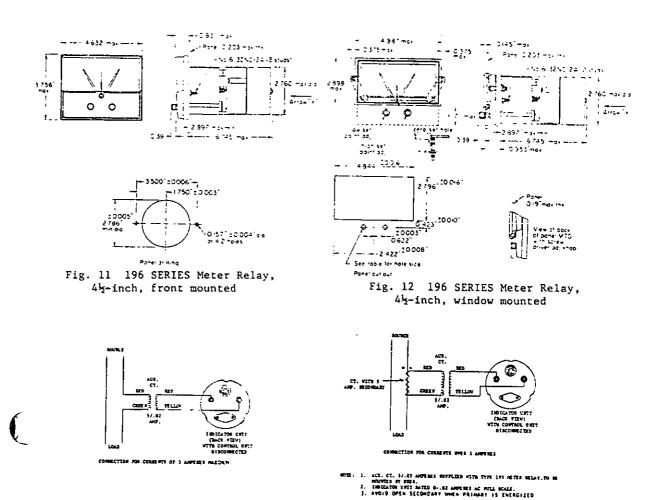


Fig. 13 External connections for Meter Relay with current transformer



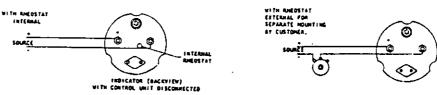


Fig. 14 External connections for Meter Relay with rheostat

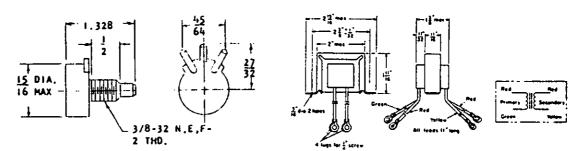


Fig. 15 External rheostat for Meter Relay

Fig. 16 Step-down current transformer for Meter Relay

WARRANTY

LFE Corporation warrants equipment of its manufacture against defect in material and workmanship for a period of one year from date of shipment. LFE Corporation's obligation under this warranty is expressly limited to the repairing or replacing at its factory or at any authorized repair station of equipment returned provided that (a) LFE Corporation is promptly notified in writing by the Buyer upon his discovery of a defect, (b) Upon receipt of written authorization from LFE Corporation, said defective equipment is returned as directed, with transportation charges prepaid by the Buyer and (c) LFE Corporation's examination of such equipment discloses to its satisfaction that the defect exists and was not caused by negligence, misuse, improper installation, accident or unauthorized repair or alteration by the Customer.

LFE Corporation shall not be bound by any terms, conditions, representations or warranties, express or implied, which are not stated herein.

SERVICING/MODIFICATION

If repair is required, the instrument should be adequately packed with a brief note describing the observed problem and shipped prepaid to the nearest Modification Center or Repair Dept., LFE Corporation, 11655 Chillicothe Road, Chesterland, Ohio 44026.

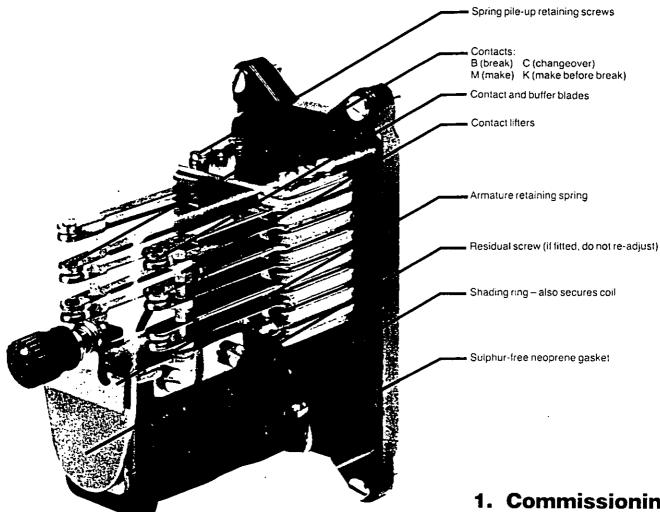




Control products

RELAYS - D2600 plug-in system

Commissioning and Maintenance Instructions



RELAYS MUST NOT BE PLUGGED INTO OR REMOVED FROM THEIR SOCKETS UNLESS THE PROTECTIVE COVER IS FITTED.

1. Commissioning

- 1.1. Visually check that the relay has not sustained damage in transit.
- 1.2. Check cover is properly seated on gasket and undamaged.
- 1.3. Check relay details are to specification,
 - i.e. coil voltage contact type and buildfouling pin (FP) arrangement.

2. Cautionary notes

2.1. Handling of relays.

Handling the relay without the cover can damage the contact springs and is dangerous if the relay is plugged into a live socket.

To remove a relay from the socket, move the relay gently from side to side, not up and down.

2.2. Removing covers.

2.2.1. Removal and replacement of the cover must be carried out with extreme care to avoid damage to the relay.

2.2.2. Always replace the cover.

Leaving the cover off, particularly during installation, can lead to problems at a later date due to foreign matter entering the relay and finding its way between contacts.

2.2.3. Incorrect replacement of covers.

Relays with blow-out magnets (type D2600/B) have holes in their covers to prevent the accumulation of the gases produced by arcing. Covers for other D2600 relays do not have these holes. It is important to see that covers are not mixed. Care should also be taken when replacing covers, to see that the neoprene gasket around the base is correctly positioned and that the rubber washer is in place on the fixing screw.

2.2.4. Solvents or oils must not be applied to the cover.

2.3. Contact isolation.

Should it be necessary to isolate contacts, for example, during testing, then synthetic resinbonded paper (SRBP) no thicker than 0.6mm or a similar lint-free material should be used. Great care should be exercised when inserting or removing the material.

2.4. Sockets used as test points.

With the relay removed, the socket may be used as a test point. However, care must be taken not to damage the contacts by inserting a test prod greater than 0.08mm (0.032 in).

It is recommended that plug blades (D.2608) as fitted to the relays be used as test prods.

3. Preventive maintenance

Under normal operating conditions no maintenance is necessary.

Clifford & Snell relays have considerable built-in safety margins and will give years of trouble-free service when operated within the specified limits.

If the relay is functioning satisfactorily do not attempt to clean away blackening that may occur in the region of the contacts or on the inside of the cover. This is simply the result of hard use with some contact arcing.

4. Contact cleaning

Contact cleaning is unnecessary unless actual failure of the contact to operate has been observed.

Cleaning should be by use of a contact cleaning tool, e.g. a leather-faced spatula.

Abrasive materials must NOT be used.

5. Contact blade adjustment

This procedure is only to be used as an emergency measure when failure of the relay has been observed and no spare unit is available. Contact blades should only be stressed by stroking, they must NEVER be bent or kinked. The limit of travel of the blade is set by adjusting the backing strip, this is directly above or below the contact, depending upon the contact action.

The contact setting values are as follows:

- (a) Minimum pressure between two made contacts 25gm
- (b) Minimum back pressure against push rods 5gm
- (c) Minimum wipe at the contact surface 0.25mm
- (d) Minimum contact gap 0.812mm

After adjustment, visually check contact movement and operation.

N.B. THIS PROCEDURE IS AN EMERGENCY MEASURE AND THE FAULTY RELAY SHOULD BE REPLACED AT THE EARLIEST OPPORTUNITY.

6. Repair

Defective relays should be replaced with a spare and the faulty unit returned for repair to:

Clifford & Snell Ltd., 512 Purley Way, Croydon CR0 4NZ.

7. Technical data

Technical data applicable to the D2600 Relay range is described in publication C90.2.

Whilst every care has been taken in the preparation of this leaflet, no liability is accepted for any consequence of its use. No licence to use any patent should be assumed. All goods are sold subject to our standard conditions of sale which are included in the current price list.

All dimensions quoted are approximate only and subject to change without notice, as are other technical features resulting from continual development and improvement.

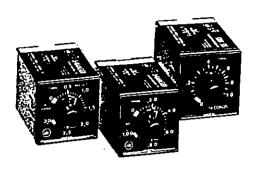
Publication C880.2



Clifford & Snell Limited

AN ECONOMICAL SOLID-STATE TOR
WITH OCTAL PLUG-IN BASE,
THE ATC 319 MAINTAINS EXCELLENT
REPEAT ACCURACY DESPITE WIDE VOLTAGE
AND TEMPERATURE VARIATIONS.
EVEN AFTER LONG PERIODS OF DOWN-TIME.
ONE MODEL HAS FIVE DIAL-SELECTED
ADJUSTABLE RANGES AND PROVIDES
ANY TIMING PERIOD BETWEEN
0.02 SEC AND 30 MIN;
LOWER-COST MODELS INCORPORATE
THREE DIAL-SELECTED RANGES OR
A SINGLE ADJUSTABLE RANGE.





PRODUCT HIGHLIGHTS

WIDE CHOICE OF RANGES

In addition to the short ranges expected of an electronic TDR, the 319 is also available with ranges as long as 100 minutes, for AC or DC operation.

An unusually versatile model, the 319D five ranger has five dial-selected ranges - from 0.3 sec to 30 min - and provides any dial-adjustable timing period between 0.02 seconds and 30 minutes; a lower priced option (model 319D three ranger) has three dialselected ranges in two models (1, 10 and 100 sec and 1, 10, and 100 min). A single 319D model thus accommodates the needs of a wide range of applications, allowing the user to select - easily and precisely - an appropriate range to permit optimum setting accuracy. The dial face automatically displays the selected range.

The 319B offers a choice of five dial-adjustable fixed ranges between 1 sec and 30 sec.

CYCLE PROGRESS INDICATION

Model 319D.

All options incorporate a light-emitting diode (LED) which is on during the time cycle, off at the end of timing. The 5-range option also includes a second LED which separately indicates the status of the output relay: on when energized, off when de-energized.

Model 319B.

A pilot light clearly indicates the control action: it is on during the time cycle, off at the end of timing.

APPROVALS

FM, CSA Recognized under the component program of UL.

HIGH ACCURACY

The 319's timing circuit is not subject to the large plus error that plagues many electronic TDRs after long periods of down-time: it maintains rated accuracy regardless of reset time variations, provided that there is at least 0.1 sec between cycles for Model 319D; or at least 10 sec between cycles for Model 319B. All models hold unusually high repeat accuracy in the face of wide voltage and temperature swings.

OPERATION

DIMENSIONS

Model 319D

Timing begins when the start switch is closed. At the same time, the Timing LED goes on and a relaxation oscillator starts to run at a rate determined by the dial adjustment. The 319D times out — and the Timing LED turns off — when the oscillator count is equal to the level set by the range switch.

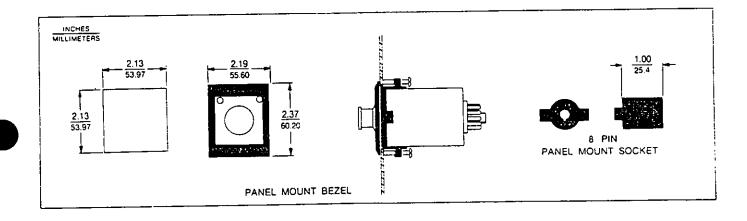
At time-out, the load relay is energized, transferring its contacts, and the timing circuit is automatically de-energized. Reset occurs when the *start* switch is opened or when power is interrupted.

With Model 319D-016, a second LED (labeled Timed Out) turns on when the load relay is energized at time-out; and off when the start switch is opened or power is interrupted.

Model 319B

Timing begins when the start switch is closed, and a capacitor immediately begins to accumulate a charge through a fixed resistor. The 319B times out when the capacitor reaches a voltage level which is determined by the position of the dial adjustment. At time-out, the relay is energized, transferring its contacts, and the timing circuit is automatically de-energized. Reset occurs when the start switch is opened, or power is interrupted.

8 PIN OPTIONAL OCTAL SOCKET



SPECIFICATIONS

For All Models

MODELS

Choice of two.

(319D - AC or DC: 3 or 5 dial-selected

adj. ranges)

(319B - AC; single adi, range)

All models operate in on-delay mode only

LOAD RELAY

TYPE: DPOT (2 Form C)

LIFE: AC: 50,000,000 operations (no load) DC: 100,000.000 operations (no load)

CONTACT RATING:

AC: 7A resistive at 120 or 240V

DC: 3A at 30V

TEMPERATURE RATING

0* to 70*C (32* to 158*F)

WEIGHT

NET: 6 oz

SHIPPING: 10 oz

MOUNTING

Plug-in octal base; mounts in any position. OPTIONAL: surface-mounting socket; panel-

> mounting bezel kit and plug-on socket kit for Model 3190.

HOUSING

Dust, moisture and impact-resistant molded plastic case.

SETTING ACCURACY

10% at full scale

For Model 319D

RANGES AND MINIMUM SETTING

Model 319D-016:

five dial-selected ranges:

0.02 sec - 0.3 sec

0.07 sec - 3.0 sec

0.6 sec - 30.0 sec

3.5 sec — 3.0 min 35.0 sec — 30.0 min

Model 319D-134:

three dial-selected ranges:

0.04 — 1.0 sec

0.2 - 10.0 sec

2.0 - 100.0 sec Model 319D 360:

three dial-selected ranges:

0-1 min — 2.5 sec. 0-10 min — 23.0 sec. 0-100 min — 3.0 min.

REPEAT ACCURACY

Varies as a function of line voltage and temperature but not of reset time (see Recycle Characteristics):

- ± 1% of range or 2.0 ms (whichever is greater), when temperature is constant and line voltage is constant or varies within limits*
- ± 4% of range or 2.0 ms (whichever is greater), when line voltage is constant and temperature varies within limits*
- ± 6% of range or 2.0 ms (whichever is greater), when line voltage and temperature vary within limits*

*Variations of line voltage must be within 95 and 132V; of temperature between 0° and 70°C (32° and 158°F)

RECYCLE CHARACTERISTICS

When 0.1 sec or longer of reset time is allowed after time-out or after power interruption, the next cycle is timed at full repeat accuracy; when only 0.07 sec is allowed, the next cycle is shortened by as much as 1%.

RESET

5 ms if power is interrupted any time after time-out; 70 ms if power is interrupted during timina.

POWER REQUIREMENTS

120V AC: 95 to 132V, 50/60 Hz, 0.011A 240V AC: 190 to 264V, 50/60 Hz, 0.011A 24V AC: 21 to 28V, 50/60 Hz, 0.05A 24V DC: 21 to 28V, 0.05A, 50% ripple max.

For Model 319B -

RANGES AND MINIMUM SETTING

Choice of five ranges:

0.15 — 1 sec

0.2 - 3 sec 0.2 - 6 sec

0.3 - 10 sec 0.5 - 30 sec

REPEAT ACCURACY

Varies as a function of line voltage. temperature and reset time*;

- ± 1% of setting or 15ms, when all three conditions are constant.
- ± 4% of setting or ± 1% of range, when one condition varies.
- ±6% of setting or ±3% of range, when
- two operating conditions vary.
- ± 8% of setting or ± 3% of range, when all three conditions vary.

Variations of line voltage must be within 102 and 132V; of temperature between 75° and 150°F; of reset time between 10 sec and 10 min.

RECYCLE CHARACTERISTICS

When 10 seconds or more of reset time is allowed after time-out or after power interruption, the next cycle is timed at full repeat accuracy; wher only 5 seconds is allowed, the next cycle is shortened by as much as 1.5%; when only 0.5 sec, by as much as 5.0%.

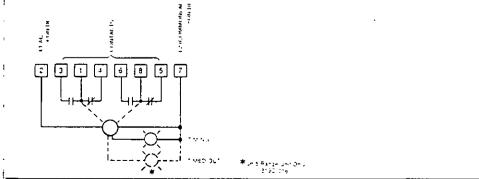
RESET

20 ms if power is interrupted at least 0.1 sec after timeout: 100 ms if power is interrupted during timing.

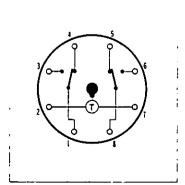
POWER REQUIREMENTS:

120V AC: 95 to 132V, 50/60 Hz, 0.01A 240V AC: 190 to 264V, 50/60 Hz, 0.005A



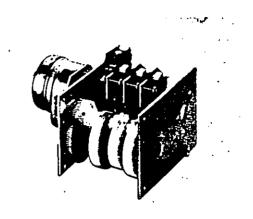


TERMINAL WIRING



A COMPACT AND ECONOMICAL MOTOR-DRIVEN CAM TIMER, THE 324C PRECISELY CONTROLS ONE TO TWELVE LOAD CIRCUITS THROUGH EASILY-SET CREWDRIVER-ADJUSTABLE CAMS. EACH TIMER PROVIDES A WIDE RANGE OF CYCLE TIMES THROUGH A SET OF INTERCHANGEABLE GEARS. THE 324C CAN ALSO BE USED WITHOUT A MOTOR AS A ROTARY CAM LIMIT SWITCH WITH BIDIRECTIONAL SWITCHES.





PRODUCT HIGHLIGHTS

EASY AND PRECISE CAM ADJUSTMENT

With ATC's unique split-cam design, each side of the cam is separately screwdriver-adjustable in either direction: either side determines the precise instant during the cycle when the switch will actuate, the other side determines how long the switch will remain actuated. Adjustments are easy and precise: 1/4 turn of the adjusting screw equals 1/2% of cycle time. A setting disc, calibrated in 1% increments, facilitates program set-up and indicates cycle progress.

APPROVALS

UL, C\$A

ONE TO TWELVE PRECISION SWITCHES

Whether used as a time or sequence programmer, the 324C can be ordered with any number of cam-operated switches from one to twelve. Each SPDT precision switch is rated at 10 amps, 120V AC and is 1/3 hp rated at 120 or 240V AC.

WIDE RANGE OF CYCLE TIMES

The 324C is available with a choice of 14 synchronous motors that provide more than 270 cycle times between 3 sec and 60 hrs. Each motor provides an adjustable range of 21 cycle times, with a ratio of over 2.5:1, through a set of interchangeable gears. Changing gears is a simple operation that takes only a few minutes.

TOP ACCURACY

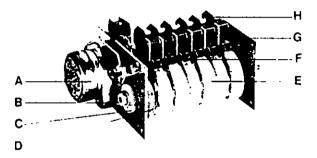
The repeat accuracy and setting accuracy of the 324C are both within ± 1/4%, tops in its field. Follower fingers precisely track the contour of the cams, accurately operating the precision switches with quick-make and quick-break action.

SEQUENCE CONTROL

The 324C can be ordered without a motor and with a 1-inch long shaft extension on either or both ends, for use as a rotary cam limit switch. The unit is then fitted with bidirectional switches.

OPERATION

The 324C comprises eight basic functional assemblies which operate as follows: the synchronous motor (A) drives a hex shaft (B) through a series of interchangeable gears (C) which rotate the setting disc (D) and the cam assemblies (E). Follower fingers (F) track the contour of the split cams, actuating the precision switches (G) at the precise point where the cam face is cut. Loads are connected directly to the switches through their easily accessible terminats (H) that accept standard push-on connectors.



BASIC APPLICATIONS

REPEAT CYCLE.

The timer runs continuously, repeating cycles as long as power is applied to the motor through an external start switch. The timer stops when power is cut off, and resumes the interrupted cycle when power is restored.

STOP CYCLE

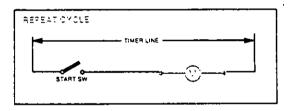
Power is applied to the motor through a start switch which the user wires in parallel with one of the timer's camperated stop contacts and in series with the motor. Whenever the start switch is closed for at least 1% of cycle, the stop contact maintains the motor circuit for one full cycle; the timer then stops.

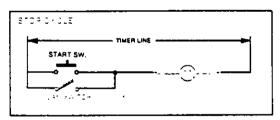
LONG STOP CYCLE.

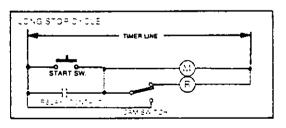
Used when the timer must operate from a momentary start signal that is less than 1% of cycle time, this circuit includes a factory-supplied and wired holding relay. The relay maintains the motor circuit for 1% of cycle until the cam switch transfers. The cam switch maintains the motor circuit for the balance of the cam rotation, ending the cycle when the cam switch opens.

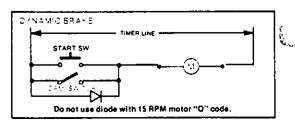
DYNAMIC BRAKE.

This circuit prevents coasting, stopping the timer instantly when power is removed from the motor. The brake consists of a diode assembly (Part No. 230026056) which the user wires in parallel with one of the timer's cam operated stop contacts. It is required in all stop cycle times with a cycle time of 120 seconds or less, except those that use the 15 RPM permanent magnet motor Q which needs no brake.









	617		15	RPM	мо1	OR	P	High To		RPM -Perma			Q *	1	5	RPM I	мот	OR	Α
	CEAP	MOTOR 31 31 100TH		MOTOR PINION 2 30 TOOTH	CODE	MOTOR PINION I 21 Tooth	CODE	MOTOR PINION 3 48 1 TOOTH	CODE	MOTOR PINION 2 30 TOOTH		MOTOR PINION 1 24 TOOTH		MOTOR PINION 3 40 TOOTH		MOTOR PINION 2 10 TOOTH		MOTOR PINION I 21 Tooth	
SECONDS resulting speed at 60 cycles	33 37 31 5 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3	. 373.1.1.0.80	P3A P3B P3C P3C P3C P3F P3G	4 4 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	P2A P2B P2C P2D P2E P2F P2G	5 6 68 7 5 9 16 10	PIA PIB PIC PIE PIE PIG	3 3.6 4 4.5 5 5.5 6	03A 03B 03C 03D 03E 03F 03G	4 4.8 5.33 6 6.66 7.33	020	5 6.66 7.5 8.33 9.16	QIA QIB QIC QID QIE QIF QIF	10 8 12 13 5 15 15 16 5 18 13	43A 43B 43C 43C 43E 43E 43F	12 14 4 15 18 20 22	12B 12C 12D 12F 12G	15 13 20 25 25 27 5 30	418000WFG
SECONDS resulting speed at 50 cycles	900 H H 100 H	Control to the Control of the Contro	P3A P3B P3C F3D P3E P3F P3G		P2A P2B P2C P2D P2E P2F P2G	5 2 8 10 11 12	PIA PIB PIC PIE PIF PIG	3.6 4.3 4.8 5.4 6 6.6 7.2	Q3A Q3B Q3C Q3D Q3E Q3F Q3F Q3G	4.8 5.76 6.4 7.2 8 8.8 9.6	Q2A Q2B Q2C Q2D Q2E Q2F Q2F Q2G	6 7.2 8 9 10 11	QIA QIB QIC QID QIE QIF QIF	10.8 12.95 14.4 16.2 18 19.8	438 438 430 430 436 436 436	14.4 17.29 19.2 21.5 24.4 25.8	A2A A2B A2C A2C A2E A2F A2F A2G	18 21 5 24 27 30 33 36	41A 41B 41C 41C 41C 41C 41C

			5	RPH M	ютс	R	F		2.	5 RPH	мот	OR	G
	CAM SHAFT GEAR	MOTOR PINION 1 10 TOOTH	COOE	MOTOR PINION 2 30 TOOTH		MOTOR PINION I 71 TOOTH		MOTOR PINION 3 10 TOOTH	CODE	MOTGR PINION 2 30 TOOTH		MOTOR PINION I It TOOTH	CODE
MINUTES resulting speed at 60 cycles	30 36 40 45 50 55 60	9 10.8 12 13.5 15.5 16.5	F3A F3B F3C F3D F3E F3F F3G	12 14 4 15 18 20 22 24	F2A F2B F2C F2D F2E F2F F2F	15 18 20 22.5 25 27 5 30	FIA FIS FIC FID FIE FIF FIG	18 21 6 24 27 30 33 36	G3A G3B G3C G3D G3E G3F G3F	21 28 8 32 36 40 44 48	G2A G2B G2C G2D G2E G2F G2F G2G	30 36 40 45 50 55 60	GIA GIB GIC GID GIE GIF GIG
MINUTES resulting speed at 50 cycles	30 36 40 45 50 56	10.8 12.96 14.4 16.2 !8 19.8 21.6	F3A F3B F3C F3D F3E F3F F3G	14 4 17 28 19.2 21.6 24 26 4 28.8	F2A F2B F2C F2D F2E F2F F2G	18 21.5 24 27 30 33 36	FIA FIB FIC FID FIE FIF FIG	21 6 25 92 28 8 32.4 36 39 5 43.2	G3A G3B G3C G3C G3E G3E G3F G3G	28.8 34.56 38.4 43.2 48 52.8 57.6	G2A G2B G2C G2D G2E G2F G2F	36 43 7 48 54 60 66 72	GIA GIB GIC GIC GIF GIF GIF

			1/6	RPH N	OTO)R	L		1/12	RPH N	лото	DR	M	•	1/24	RPH N	ото	R	N
	CAM SHAFT GEAR	MOTOR PINION 3 40 TOOTH	CODE	MOTOR PINION 2 30 TOOTH		MOTOR PINION 1 24 TOOTH	CODE	MOTOR PINION 3 40 1 TOOTH		MOTOR PINION 2 30 TOOTH		MOTOR PINION 1 74 TOOTH		MOTOR PINION 3 40 TOOTH		MOTOR PINION 2 10 TOOTH		MOTOR PINION 1 21 TOOTH	CODE
HOURS resulting speed at 60 cycles	30 36 40 45 50 55 60	4.5 5.4 6.75 7.5 8.25 9	L3A L3B L3C L3D L3E L3F L3F	6 7.2 8 9 10 11	L2A L2B L2C L2D L2E L2F L2G	7.5 9 10 11.25 12.5 13.75	LIA LIB LIC LID LIE LIF LIG	9 10.8 12 13.5 15 16.5 18	M3A M3B M3C M3D M3E M3F M3G	12 14.4 15 18 29 22 24	M2A M2B M2C M2D M2E M2F M2F	15 18 20 22 5 25 27.5 30	MIA MIB MIC MID MIE MIF MIG	18 21.6 24 27 30 33 36	N3A N3B N3C N3C N3E N3F N3F	24 28.8 32 36 40 44 48	NZA NZB NZC NZC NZC NZE NZF NZF	30 36 40 45 50 55 60	NIA NIB NIC NIC NIE NIE NIG
HOURS resulting speed at 50 cycles	30 36 40 45 50 55 60	5.4 6.48 7.2 8.1 9.9 10.8	L3A L3B L3C L3C L3E L3F L3G	7.2 8.64 9.6 10.8 12 13.2 14.4	LZA LZB LZC LZD LZE LZF LZF LZG	9 10.8 12 13.5 15 16.5 18	LIA LIB LIC LID LIE LIF LIG	10.8 12.96 14.4 16.2 18 19.8 21.6	M3A M3B M3C M3D M3E M3F M3G	14.4 17.28 19.2 21.6 24 26.4 28.8	M2A M2B M2C M2D M2E M2F M2G	18 21.5 24 27 30 33 36	MIA MIB MIC MID MIE MIF MIG	21.6 25.92 28.8 32.4 36 39.6 43.2	N3A N3B N3C N3D N3E N3F N3G	28.8 34.56 38.4 43.2 48 52.8 57.6	N2A N2B N2C N2D N2E N2F N2G	36 43.2 48 54 60 66 72	NIA NIB NIC NID NIE NIF NIG

TIME CYCLE ORDERING CODES

Select Time Cycle from table below, if it is available with more than one motor and gearing combination, pick the combination which would best accommodate potential future speed changes. 3 Digit Speed Code identifies motor — gearing as follows.

						ORDERING CODI	E i	. * (Example)		
Mora	a saeeo —							[]		
A	5 rpm	н	1 rph					عدمن سا	T-0.541	Part No.
B	150 rph	J	¹a rph					A	30 Teeth	23004951100
С	mg1 f	L	1/6 rph					В	36 Teeth	23004951200
D	V₂rpm	M	1/12 rph					C	40 Teeth	23004951300
E	15 rph	N	1/24 rph	MOTORs	1502%			0	45 Teeth	23004951400
F	5 rph	P	15 rpm	1	24 Teeth	23004950100		E	50 Teeth	23004951700
G	2.5 rph	a	15 rpm	2	30 Teeth	23004950200		F	55 Teeth	23004951500
		K	Special	3	40 Teeth	23004950300		G	60 Teeth	23004951600

•	150	RPH	мот	OR	В		1	RPM N	10TC)R	C		1/2	RPM	мот	OR	D		15	RPH	мот	OR	E
MOTOR: PINION 3 40 TOOTH	CODE	MOTOR PINION 2 IC TOOTH	CODE	ROTON I NOINIS IS KTOOT	CODE	MOTOR PINION 3 10 TOOTH	C00£	MOTOR 2 MOTOR 2 MOTOR 1001H		MOTOR PINION I 21 TOOTH	CODE	MOTOR PINION 3 10 TOOTH		MOTOR PINION 2 30 TOOTH		MOTOR PINION 1 21 TOOTH		MOTOR PINION 3 40 TOOTH	CODE	MOTOR PINION 2 30 TOOTH		MOTOR PINION I 2: TOOTH	
13 21 5 21 21 30 31 35	834 838 830 830 830 830 830	24 28 8 32 11 11 48	B2A B2B B2C B2C B2E B2F B2G	36 36 45 55 55 60	BIBLO BILL BILL BILL BILL BILL BILL BILL	45.4.0.5.5.5.5.90	C3A C3B C3C C3C C3E C3F C3F	60 72 30 90 100 110 120	C2A C2B C2C C2C C2E C2F C2F C2F	75 90 100 112 5 125 137 5	CIA CIB CIC CIC CIE CIG	90 108 120 135 150 155 180	03A 03B 03C 03C 03C 03C	120 144 150 130 200 220 240	D2A D2B D2C D2D D2E D2F D2F	150 180 200 225 250 275 300	DIA DIB DIC DIO DIC DIC DIC DIC	180 215 240 270 300 330 360	E3A E3B E3C E3C E3C E3C E3C E3C E3C	240 288 320 350 450 440 480	E2A E2C E2C E2E E2F E2F E2G	360 360 400 450 560 600	EIA EIB EIC EIC EIF EIF
21 5 2 25 9 2 28 4 39 5 5 4 39 5 2	834 838 830 830 835 836	28 8 34,55 38.4 43.2 48 52.8 57.6	B2A B2B B2C B2D B2E B2F B2F	30 2 48 4 50 60 60 7	BIB BIC BIE BIE BIG	54.8 54.8 72 81 90 99	034 038 030 035 035 035 036	72 85 4 95 108 120 132	C24 C2B C2C C2C C2E C2F C2F C2G	90 108 120 135 150 155 180	CIA CIB CIC CID CIE CIF CIG	108 129 5 144 162 180 198 215	034 038 030 030 036 036 036	144 172.8 192 216 240 264 238	024 028 020 020 020 026 02f 026	180 215 240 270 300 330 350	D14 D18 D10 D10 D15 D16	216 259 2 288 324 360 395 432	E34 E38 E30 E30 E35 E3F E3G	233 345.6 384 432 480 528 575	E2A E2B E2C E2D E2E E2F E2F	350 432 480 540 600 660 720	EIA EIB EIC EIC EIE EIF EIG

1 RPH MOTOR							1/2	RPH	MOT	OR	J
MOTOR PINION 1 40 Tooth	CODE	MOTOR PINJON 2 JO TOOTH	CODE	MOTOR: PINION: 21 TOOTH	CODE	MOTOR : PINION 3 40 TOOTH		MOTOR PINION 2 30 TOOTH	CODE	MOTOR PINION 1 24 TOOTH	CODE
45 54 67.5 75 82 5 90	H3A H3B H3C H3D H3E H3F H3G	60 72 80 90 100 110	H2A H2B H2C H2D H2E H2F H2G	75 90 100 112.5 125 137.5 150	HIA HIC HIC HIE HIF	90 103 120 135 15J 165 180	13A 13B 13C 13D 13E 13F 13G	120 144 160 180 200 220 240	124 128 120 120 121 125 127 126	150 180 200 225 250 275 300	J! A J1B J1C J10 J1E J1F J1G
54.8 54.8 72 81 90 99	H3A H3B H3C H3D H3E H3F H3G	72 85.4 95 108 120 132 144	H2A H2B H2C H2C H2E H2F H2G	90 108 120 135 150 165 180	HIA HIB HIC HID HIE HIF	108 129.6 144 162 180 198 215	13A 13B 13C 13D 13E 13F 13G	144 172.8 192 216 240 254 288	J2A J2B J2C J2D J2E J2F J2F J2G	180 216 240 270 300 330 360	JIA JIB JIC JID JIE JIF JIG

Motor Europe BBO Carried a NEV

The ability of the 324C to trip a number of load contacts simultaneously is determined in the chart below. Pick the vertical column that corresponds to the total number of contacts you need and proceed down the column to a point where it intersects the horizontal column that corresponds to the fastest time cycle you intend to use. If the intersection of the two columns is in the gray, there is no limitation to the 324's ability to trip contacts simultaneously; if not, the limit is noted in the intersected square.

Two	One				To	tat N	nwp	er o	f Co	nlac	:Is		
Motors	Motor	1	2	3	4	5	6	7	8	9	10	11	12
	5	Ī	ī	l	_		_		_		_		_
3	6			1	1	· 1	_	_	_	_	-	-	_
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10	20	ĭ							, 7	6	6	5	5
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171/2	35	į .			NO	LIM							
20	40	ļ.											

*THIS TABLE APPLIES TO Q MOTOR ONLY

									OF HEF		NTA	CTS	.			
•	Time cycle	Total Number of Contacts														
	seconds one motor	1	2 3 4 5 6 7 8 9 10 11 12													
-	3.0								6	5	4	3	2			
	3.6									8	7	6	5			
	4.0										9	8_	l . <u>′.</u>			
	4.5				NΩ	LIM	ıŦ						10			
	4.8				.,,	C	• •						11			
	5.0															
,	All slower cycles listed for this motor															

CYCLE TIMES

More than 270 cycle times from 3 sec to 60 rs, from a choice of interchangeable stors and gears; each motor provides more sian 20 cycle times. (see Speed Charts).

REPEAT ACCURACY

= 1/4 % of cycle time.

SETTING ACCURACY

± 1/4 % of cycle time.

FRAME SIZES

3. 6, 9 and 12 cam frame sizes are provided.

CAMS

NUMBER: 1 to 12 (or multiples up to 12, by combining timer assemblies); cams may be factory-set.

CUT: Standard or "50%" cut", as specified (standard cams allow contact closure adjustment of 1 to 45% or 55 to 99%, "50% cut" cams allow contact closure adjustment of 12 to 52% or 48 to 88%; custom cams available with 2, 3, 4 or more cuts.

CONSTRUCTION: Two-inch diameter; split type: made of Defrin.

LIFE EXPECTANCY

MECHANICAL: over 10,000,000 operations. CONTACTS: over 1,000,000 operations at less than 1 amp.

LOAD SWITCHES

TYPE: Precision switches: one for each cam. CONTACT ACTION: SPDT (Form C). CONTACT RATING: 10 A at 120 V AC (non-inductive). 1/3 HP at 125/250 V AC. MINIMUM CONTACT ACTUATION TIME: 1% of cycle time

DRIVE MOTORS

SPEED: choice of 14
(see Time Cycle Ordering Codes).
TYPE: Synchronous: permanently
lubricated: integral slip clutch for manual
advance: anti-backup to prevent damage
to switches.

VOLTAGE: 120V AC, 50 or 60 cycles;
optional: 24 or 240 V AC, 50 or 60 cycles.
POWER CONSUMPTION: 12 watts max.
DUAL DRIVE: two motors may be used, for
dual-speed and special applications.

toroue-speed Capabilities: At cycle times of 30 sec or longer, the 324 can drive and switch 12 contacts simultaneously; below 30 sec, the motor may be limited in its ability to drive or switch a number of contacts simultaneously. (See speed chart ...les).

TEMPERATURE RATING

32 to 140°F. (0 to 60°C.)

WEIGHT

NET: from 1 ½ lbs. for the 3 cam unit up to 3 ½ lbs. for the 12 cam unit SHIPPING: from two lbs. for the 3 cam unit up to 4 lbs. for the 12 cam unit

ENCLOSURES (Optional)

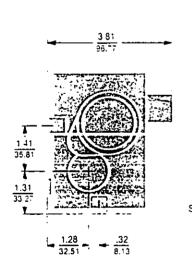
(See last pages of Catalog for detailed description).

NEMA 12 molded case for one model 324 with maximum of 3 cams.

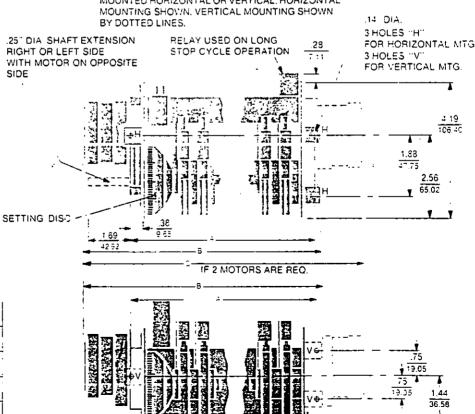
ME1 5 2 43

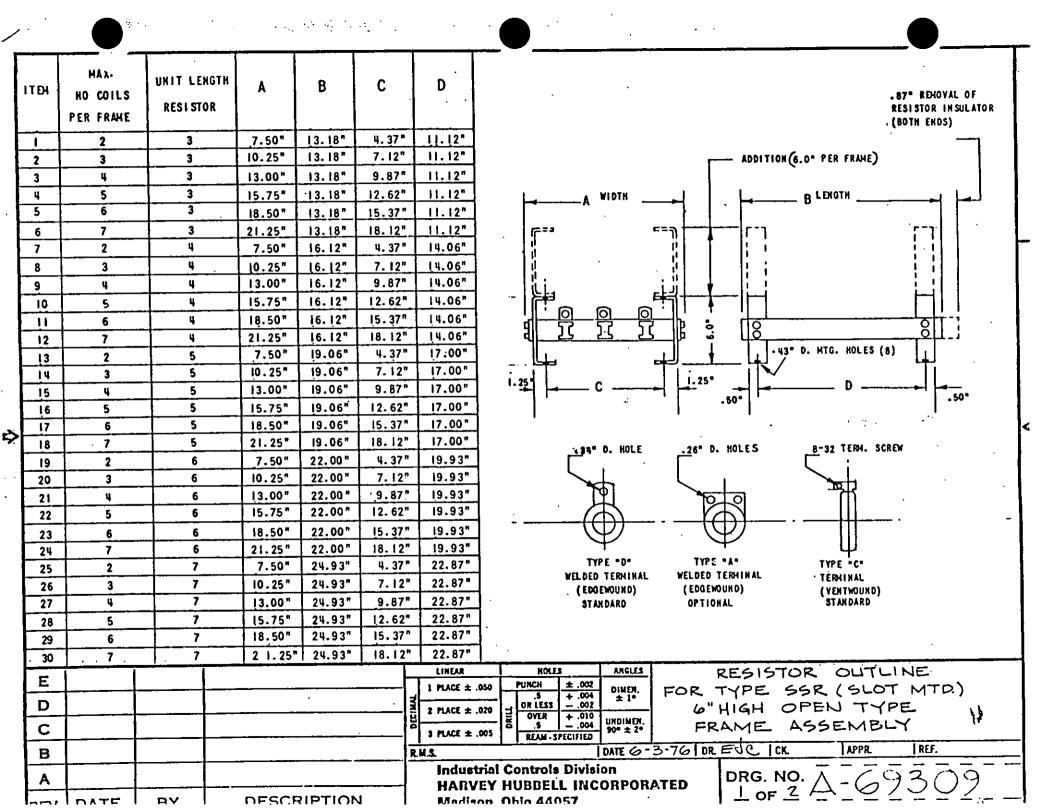


NOTE: THREE MOUNTING FEET, LOCKWASHERS AND SCREWS
SUPPLIED WITH EACH TIMER, TIMER CAN BE
MOUNTED HORIZONTAL OR VERTICAL, HORIZONTAL
MOUNTING SHOWN, VERTICAL MOUNTING SHOWN
BY DOTTED LINES.



Number of Cams	Dim A	Dim B	Dim C
3	3.81 96.84	5.72 145.29	7.22
6	5.69 144 5	7.59 192.79	9.09
9	7.56 192.02	9.47	10.97 278.64
12	9,44	11.34 288.04	12.84 326.14





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	MID TAP TERM, ASSEM. (VENTW.) IS.I A. MAX.	A-25414	309 10-001		5		 -	├ ──	<u> </u>			
	HID TAP TERM. ASSEM. (CM.) 34A. HAX.	A-25209	17578-001		6		╄		 			
7	HID TAP TERM, ASSEM. (EW.) 125 A. HAX-	4-25183	17577-001	ļ.,	7		 	↓ -	 		_	
8	COIL JUMPER (2-5/8"CTRS-) (EW)		9289-000		8			 	1			
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2	S/16-18 SCREW ASSEM- (JUMPER TO TERM-) (EW)	0-69262	69 262 - OC 2	12	ł							
3	S/16-18 SCREW ASSEM- (WIRE TO TERM-) (EW.).	8-69262	69 262-004	2	1	•						
14	3/8-16 SCREW ASSEM- (END PLATE MTG-)	8-69262	69262-010	1-4	┨.	•		•	L I			
15		+	 	+	1	•	• .	•		•		
16	MANUE BLATE	R-CALHI-OA	6 58441-006	+	1	•		•				
17	NAME PLATE	A-47788	47768-007	1 2	1 .							
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ADDENDUM I

INSTRUCTIONS

Solid-State DC Overcurrent Relay

ITE-76 DC OVERCURRENT RELAY

Catalog Series 206

Sensor Operated

For Transit and Other DC Applications

BBC Brown Boveri, Inc.

ITE-76 DC Overcurrent Relays with NC Contact Outputs

SCOPE: This Addendum applies to ITE-76 relays, sensor operated, with (1) NC

and (1) NO contact.

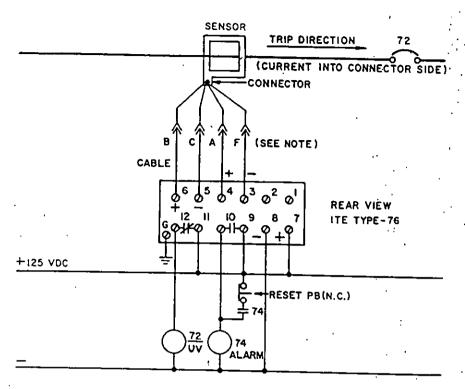
For example: Cat. #206A2280 - Instantaneous only.

Cat. #206D2280 - Rate of Rise only.

SPECIAL INSTRUCTIONS: Refer to applicable information in IB 7.5.1.7-1, except

use Figure 2A and Figure 4A on next page for external

connections and test circuits.



NOTE: FOR REVERSE TRIP DIRECTION, REVERSE B& C(B TO 5, C TO 6)

FIGURE 2A EXTERNAL CONNECTIONS (TYPICAL)

D.CT OVERCURRENT RELAY

IB 7.5.1.7-1 Page 13A

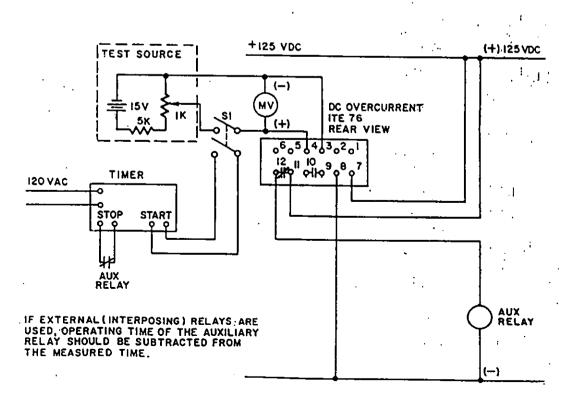


FIGURE 4A CALIBRATION TEST SCHEMATIC (Typical)

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INTRODUCTION

These instructions contain the information required to properly install, operate, and test the ITE-76 sensor operated, D.C. Overcurrent Relay.

The relay is housed in a semi-flush drawout relay case suitable for conventional panel mounting.

The connections to the relay are made at terminals located on the rear of the case and clearly numbered, one through twelve.

The controls for setting the relay are located on the front panel behind a removable clear plastic cover. The relays are factory calibrated.

The test button and target indicator are also located on the front panel. The target is reset by means of a pushbutton extending through the relay cover.

A companion sensor is mounted around the dc bus and connects to the relay by means of a special cable.

PRECAUTIONS

The following precautions should be taken when applying these relays:

- Incorrect wiring may result in damage. Be sure wiring agrees with the connection diagram for the particular relay before the relay is energized. Be sure control power is applied in the correct polarity.
 - 2. Apply only the rated control voltage marked on the relay front panel.
- Do not attempt to manually operate target vanes on CIRCUIT-SHIELD relays. Although the targets return their indication under shock, they can be damaged by manual operation with a pencil or pointed object.
- 4. The entire circuit assembly of the relay is removable. This board should insert smoothly. Do not use force.
 - 5. Follow test instructions to verify that the relay is in proper working order.

CAUTION: since troubleshooting entails working with energized equipment, caution should be taken to avoid personal shock. Only competant technicians familiar with good safety practices should service these devices.

6. The Hall-effect sensor must be considered to be at ground potential. Maintain appropriate air clearance to bus bars to provide necessary dielectric strength.

PLACING THE RELAY INTO SERVICE

1. RECEIVING, HANDLING, STORAGE

Upon receipt of the relay (when not included as part of a switchboard) examine for shipping damage. If damage or loss is evident file a claim at once and promptly notify the nearest Brown Boveri Sales Office. Keep the relay clean and dry and use normal care in handling to avoid mechanical damage.

2. INSTALLATION

Mounting

The outline dimensions and panel drilling and cutout information is given in Figure. 1.

Connections

A Typical connection diagram is shown in Figure 2.

The 176-76 relay has a metal front panel which is connected through printed circuit board runs and connector wiring to a terminal at the rear of the relay case. The terminal is marked "G" and is located as shown in Figure 1. In all applications this terminal should be wired to ground.

The relay requires four leads for connections to a DC current sensor: two for sensor output and two for sensor bias (control) current. Twisted or twisted and shielded pairs are recommended, #22AVG or larger. Normally, a relay-sensor cable (609970 or 609885) terminating in a 7-pin male connector (Positronic GH7MSCLSH19C) is supplied with the relay.

Trip direction of a standard relay is determined by the bus current in the sensor window (magnetic field) and sensor cable connections as shown in Fig. 2.

The positioning of the Hall-effect sensor with respect to the d.c. current carrying bus bar is critical to the calibration of the system and must be determined by test for each equipment configuration. In addition, the sensor must be considered to be at ground potential and appropriate clearances must be maintained to meet the dielective strength requirements of the installation. Contact the factory if additional information is required on these points. Once sensor position and calibration has been properly determined for a given equipment configuration, and individual calibration for each frame of gear is not necessary.

3. SETTINGS

The ITE-76 may be provided with any combination of the following three functions depending on the requirements of the application:

Instantaneous Function:

A rotary switch provides four pickup settings for the instantaneous function in multiples of sensor ampere rating: 1,2,3,4x. For example, with a sensor rated 500 amperes and a setting of 4x, the instantaneous function will trip for currents higher than 2000 amperes.

Long Time Function:

A tap block on the upper left of the front panel provides four pickup settings in multiples of sensor ampere rating: 0.5, 0.75, 1.0, 1.25x.

The tap block located on the upper right side of the front panel provides four time delay settings: 5, 10, 15, 20 seconds.

Rate-of-Rise Function:

A potentiometer located on the left side of the front plate provides a setting of the di/dt pickup in multiples of sensor rating in amperes per second: 0.2 to 4x.

A continuously adjustable dial with a range of 0.05 to 0.4 seconds is used to set the required time delay. The rate-of-rise of current must be above pickup for the length of time set on this dial before the relay's output contacts will transfer.

Sensor Control (Bias) Current: (CAL BIAS)

Internally mounted trimmer potentiometer is provided to set sensor bias during calibration (normally $20\,$ mAdc).

Trip Direction:

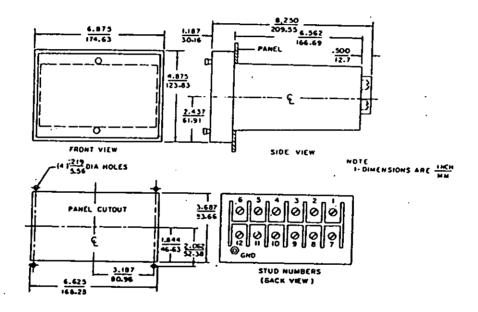
All trip functions are unidirectional. The ITE-76 relay produces trip output if the input signal is positive at terminal 4 with respect to terminal 3 and is above the trip settings.

Operation Indicators:

Target indicators are provided on the Instantaneous and Rate-of-Rise tripping functions. The targets retain their indication until manually reset. Control power must be present to reset.

CAL NULL Control:

This potentiometer is used to null the offset voltage of internal amplifier UI during calibration. This adjustment is made at the factory and should not need adjusting in the field.



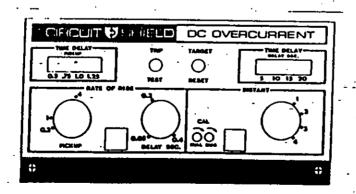


FIGURE 1: Relay Outline, Panel Drilling, and Front Panel Layout

- APPLICATION DATA

These relays have been designed especially for use with main and feeder circuit breakers to control the supply of D.C. power to the third-rall, or catenary of transit systems. Several models are available to provide various combinations of protective functions which open the appropriate circuit breaker to isolate the faulty section of the power-distribution system.

The relays are usually mounted on metal-clad switchgear or switchboards, and operate in conjunction with BBC supplied Hall-effect DC current sensors of appropriate current ratings; mounted on BBC Type FBK DC circuit breakers. In standard applications, rated output of sensors is 50mV at a bias (control) current of 20 mAdc supplied by the ITE-76 relay.

System designers who elect to purchase this ITE-76 and companion DC sensors for installation in equipment around or adjacent to DC busses or cables, must check the physical configuration for calibration by comparing sensor output with readings from a separate measuring device such as a main circuit shunt. Sensor positioning can then be adjusted, or a pick-up multiplier could be applied to relay front settings, or the relay recalibrated, as best suits the particular application. Contact the factory for additional information on sensor positioning and calibration of the relay/sensor combination.

Solid-state components measure the output of the sensor, and compare it to the pre-set tripping levels provided by the front accessible, calibrated controls. When an abnormal condition is detected, the Type ITE-76 relay closes its contacts to energize the shunt-trip coil of the circuit breaker.

An example of a typical application is shown in Fig. 3 with reverse current trip in the main circuit and forward trip in the feeder circuits.

Instantaneous Function

Protection against high current short circuit faults is provided by the instantaneous function. The dial setting times the sensor rating gives the pickup current. A setting of twice the maximum train current or feeder rating is often used in transit systems: A 500A sensor and IX setting typically serves as a reverse current protection on main circuit breakers.

Long Time Function

The time delay function provides a definite time selective operation for coordination. Protection against low current arcing faults that are below the protected zone of conventional AC overcurrent devices is provided with the Type 76 overcurrent relays. This function is particularly suited to transit systems where the load usually fluctuates. The settings depend on the load current profile and the train acceleration time.

Rate-Of-Rise Detector

Faults, especially arcing faults at the end of a track-section, cannot usually be detected by overcurrent devices since trains starting in the section will often draw more current than the remote fault. If left undetected, the arc may cause erosion of the track and elevated structure. These considerations, as well as those involving personnel safety, require fast and reliable isolation of these faults.

The Rate-of-Rise Detector of the type ITE-76 overcomes the problems associated with overcurrent devices. In most cases, protection can be provided against faults in the most remote section, even though the fault current is less than load currents.

The choice of relays and proper settings can be shown by the following example: A typical DC distribution system for a transit system might consist of several rectifiers, each rated 8000A de continuous. The tracks (or catenaries) are supplied through 4000A de feeder breakers, with 4000 amp 50 mV sensors.

Assume the track resistance to be .04 ohm per mile total, and the track inductance to be .0016 henry per mile, giving a circuit time constant $(T_1$ =L/R) of .04 seconds. Also assume that the longest track section is 2.5 miles.

The various trains in service in modern transit systems require peak starting currents varying in the range of 750 to 1200 amperes per car. These figures apply to both chopper and cam-type starters. For a six car train, an average peak can be higher if trains can start simultaneously. Safe practice is to allow for two trains, or 12 KA.

Allowing for 200V arc-drop, an arcing fault at the far end of the 2.5 mile section produces:

$$t_F = \frac{\overline{\epsilon_1} - v_a}{r_1 x} = \frac{600 - 200}{.04 \times 2.5} = 4 \text{ kA}$$

Since the load current is higher than the fault current, this application requires the R/R Detector. The R/R circuit initiates a timing cycle every time the load or fault current rate-of-rise is above its pickup setting. If the rate-of-rise drops below the setting prior to the expiration of the selected delay time, fast resetting of the timer prepares the relay for the next cycle. Otherwise, the relay times out and produces the trip output.

The relay has a signal filter to suppress 360-720HZ current ripple of transit rectifiers. Rate-of-decay or negative R/R of the current is rejected by the detector.

In applying the R/R Detector, a compromise must be made between its reach and security against nuisance trips on train-starts.

Greatest security against nuisance trips on train starts is provided with the longest time delay setting. To determine whether this will obtain a reach adequate for proper system protection, use this time delay value for I in the following equation.

With the rate-of-rise delay T set at .1 second, and rate-of-rise pickup DI at 8 kA/sec., the reach is approximately

$$x = \frac{\varepsilon_1 - v_a}{\varepsilon_1 \quad (DI)} e^{-T/T_1}$$

$$\frac{=600}{1.6 \times 8}$$
 e -.1/.04

So the detector will reach beyond the end-zone, and clear the minimum fault condition.

The settings can be made several ways, since the reach is determined by both I and DI. Good results are obtained by assuming a DI, then calculating the proper I from the following

$$T = T_1 \ln \left(\frac{I_1}{I_1} \times \frac{1}{DI}\right)$$

Assume DI = 12kA per second. The arcing fault at 2.5 miles gives I_1 = 4kA, and \overline{I}_1 = .04, therefore, in order to just see this fault, set

$$T = .04 \text{ ln } (\frac{4}{.04} \times \frac{1}{12})$$

The above calculations are based on ideal conditions. Consideration should be given to current rate-of-rise and its duration under the following dynamic load conditions and the settings matched to the actual operating conditions of the particular system:

- Initial inrush current to charge vehicle filter capacitors.
- Step current and its decay during acceleration of cam-controlled cars.
- Transfer from series to parallel motor conditions.
- Track cross-over and gap effects.
- Manual power cut back and restoration in chopper-controlled cars at 30-50 HPH.
- Fault current in trolley systems with short time constants.
- Regeneration power absorbtion in some systems.

Recapping the parameters used in the above example:

- L = track inductance (mH per mile)
- R = track resistance (ohms per mile)
- $T_1 = L/R = circuit time constant (msec)$
- T = time delay setting, rate-of-rise element
- E * system voltage
- Va = arc voltage
- X = distance to fault (miles)
- IF " fault current (kiloamps)
- DI = rate-of-rise of fault current (KA/sec)

Specifications

Input Signal

From Hall Effect Sensor, nominal

50mV dc at sensor rating.

Max Continuous Input

Greater than 100x nominal.

Control Power

125Vdc nominal, 140Vdc max,

@ 0.05A max standby.

Output Circuit Rating :

(at 125Vdc)

Thyristor (SCR) Output: 30 amos DC for 0.1 second 5 amps DC for 1 second

1 amp DC continuous

Contact Output:

3 amps continuous

1 amp opening resistive 0.3 amp opening inductive

The following apply to the thyristor output circuit:

a. Be sure the trip circuit is interrupted by an "a" contact to remove high currents. Thyristor output circuits have inherently high momentary current ratings and low continuous current ratings. Never exceed the ratings.

b. Load (trip coils or auxiliary relays) must draw at least 0.10 amps to insure operation. SCR's require a minimum current to remain conducting after triggering. Place resistance in parallel with a low current coil to guarantee the holding current if necessary.

Temperature

Nominal

25°C Ambient

Addition ± 5% Tolerance -15°C to +55°C

Must Operate

-30°C to +70°C

Tolerances

Rate of Rise Pickup Time Pickup

±10 percent

Time Delay

Instantaneous Pickup

Rate of Rise Time

a) For input signal from 100 to 150 pct of pickup. Time Tolerance will be ±20 pct or 20 ms. whichever is greater.

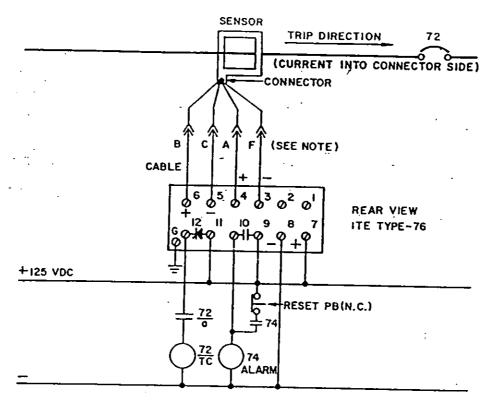
b) For input signal above 150 pct of pickup, Time Tolerance will be ±10 pct or 10 ms. whichever is greater.

Characteristics of Common Units

Catalog Number.	Rate-of-Rise Function	- Instantaneous Function	Time Delay Function
206A2240		•	
206C2240			•
20602240	*		
206F2240	*		
206G2240	•	•	•
206H2240		•	*

Rate of Rise Function: Pickup 0.2 - 4x Sensor Rating. Delay 0.05 - 0.4 sec. Instantaneous Function: Pickup 1, 2, 3, 4x Sensor Rating.

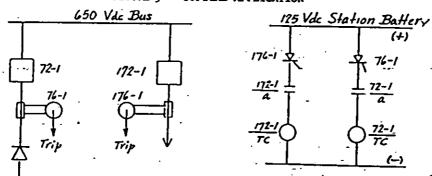
Time Delay Function: Pickup 0.5, 0.75, 1.0, 1:25x Sensor Rating. Delay 5, 10, 15, 20 seconds.



NOTE: FOR REVERSE TRIP DIRECTION, REVERSE B & C(B TO 5, C TO 6)

FIGURE 2 EXTERNAL CONNECTIONS (TYPICAL)

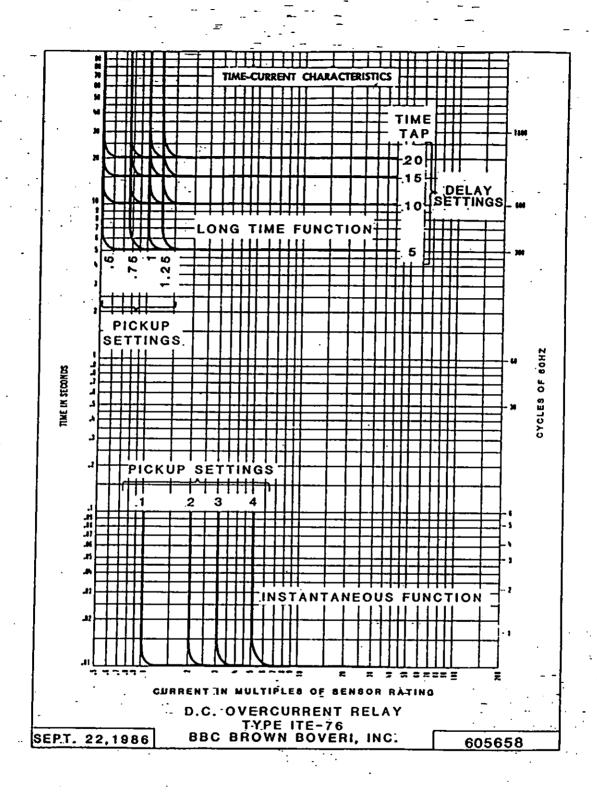
TYPE ITE-76 FIGURE 3 - TYPICAL APPLICATION

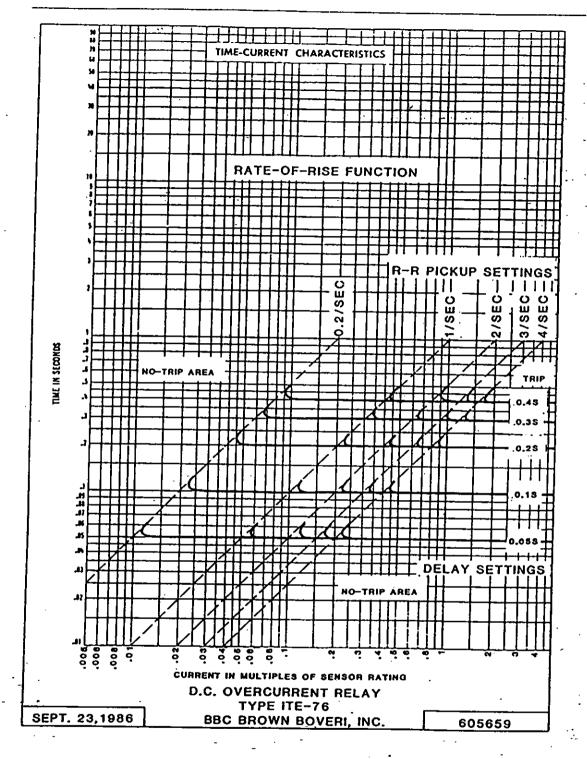


DEVICE LEGEND

Cathode Circuit Breaker Feeder Circuit Breaker

Type ITE-76, with Instantaneous Only. Trip Direction as shown Type ITE-76, with Rate of Rise Detector Only. Trip Direction as shown





Note: the above figure is not a "conventional" time-current characteristic, as would be used in coordination work. Rather, it is an attempt to illustrate the Pickup and Time settings associated with the Rate-of-Rise function.

TESTING

1. MAINTENANCE AND RENEWAL PARTS

No routine maintenance is required on these relays. Follow test instructions to verify that the relay is in proper working order. We recommend that an inoperative relay be returned to the factory for repair; however, a schematic diagram is available on request for those who wish to attempt repairs.

A circuit card extender is available which is helpful when calibrating or troubleshooting. The ITE-76 uses the 18 point extender, catalog number 200X0018.

Drawout circuit boards of the same catalog number are interchangeable. Removing or installing a circuit board with the unit in service may cause an undesired operation. The board is withdrawn by using the metal pull knobs on the front panel. The circuit board is identified by the catalog number on the front panel and a serial number stamped on the bottom of the board.

2. HIGH POTENTIAL TESTS

High voltage insulation tests are not recommended for the relay circuits. The relay has been tested at the factory. If a control wiring insulation test is required, withdraw the circuit board from the case (partial withdrawal to break the printed circuit connections is sufficient).

3. BUILT-IN TEST FEATURE

Test should be made on a de-energized main circuit. If test must be made on an energized circuit, be sure to take all necessary precautions. Control power must be available to make this test.

The built-in test is provided as a convenient functional test of the relay and associated trip circuit. The test function works as follows: when you depress the button labelled TRIP, the pickup circuit of the relay is actuated. The output contacts operate to trip the associated breaker, and the target is displayed. The test button must be held down continuously for the operating time set on the relay in order to obtain an operation.

Inst. Test

Set the INST pickup setting to 1 P.U. Push the trip test button. This will simulate an overcurrent condition which will cause an instantaneous breaker trip. The instantaneous target will show orange.

R/R Test

Set the R/R pickup and R/R delay to any setting. Set the INST pickup setting at 4 P.U. Push the trip test button. This will simulate a rate-of-rise fault condition which will cause a breaker trip. The R/R target will show orange.

Be sure to return dials to original positions at the conclusion of these tests.

4. ACCEPTANCE TESTS

Mounted in Switchgear

Verification of trip points with an energized main circuit by lowering the trip settings can only be done in some industrial DC supply applications with constant loads. Load currents in transit systems fluctuate and normally can not be preset. Thus, a high current DC current supply may be needed if a sensor and relay calibration check is required. In the latter case, calibration of the instantaneous trip can be performed as follows:

Set the instantaneous pickup setting on the 2X position. All other settings located on the front panel should be set at maximum values.

Apply test current of twice sensor rating to the main circuit. Slowly turn the Inst. calibration potentiometer R23 (internal) CCW until the relay just operates. Decrease the amperes into the main circuit and check the pickup by gradually increasing the amperes. Touch up the calibration adjustment until pickup occurs at exactly twice sensor rating. NOTE: 18-pt. extender boards for this and other tests can be ordered from BBC.

Bench Test

),

INST - PICKUP

- 1. Set inst dial to required value.
- With DC control power off, set signal voltage to 95% of the trip value, in millivolts of DC. (lx = 1 per unit = 50mv dc)
- With DC control on, apply test voltage. The relay should not trip. (i.e., no inst target indication)
- 4. With DC control voltage off, set signal voltage to 105% of pickup value. Apply DC.
- 5. Check for a target indication. Remove test signal. Reset target.
- 6. Internal potentiometer R23 can be used to trim this operating point.

RATE OF RISE - PICKUP

- 1. Set R/R dial to 1 PU. Set R/R time dial to 0.05 sec.
- With DC off, (adjust the sawtooth output of a signal generator) to 47.5mv/sec. (95% of required value.) Use a frequency of 1Hz on the signal generator.
- With DC control voltage on, apply test signal. The relay should not trip. (i.e., no R/R target indication)
- 4. With DC off, adjust test signal to 50mv/sec.
- 5. With DC on, apply sawtooth. The relay should trip giving an R/R target.
- Reset target by pressing the reset pushbutton.
- The rate-of-rise pickup dial is continuously adjustable. Therefore, the relay may be calibrated for any desired pickup setting by repeating steps 1-6 for that value.

RATE OF RISE - TIME CURVE

- Set R/R delay dial to maximum position. 0.4 seconds.
- 2. With DC off, set R/R pickup dial to 1 PU.
- 3. Adjust test equipment for a 100mv/sec. sawtooth.
- 4. With DC on, apply test sawtooth. The relay should trip in a time within 0.4 seconds $\pm 10\%$. Check for R/R target indication.
- Reset target by pressing the reset pushbutton.
- The R/R Time Delay dial is continuously adjustable. Therefore, the relay may be calibrated for any desired delay by repeating steps 1-6 for the desired setting.

TIME DELAY - PICKUP

- 1. Set time pickup tap pin to required value. Set delay tap to 5 seconds.
- With DC control source off, preset test voltage to 95% of pickup value. (1x = 1 per unit = 50mv)
- With DC source on, apply test voltage. No trip should occur. (Wait 20 seconds.)
- 4. With DC off, preset test voltage to 105% of pickup value.
- . With DC on, apply test voltage. The relay should trip. (Allow sufficient time.)

TIME DELAY - DELAY CURVE

- 1. Set time delay pickup dial to required value.
- Set time delay dial to required value, per time current curves.
- 3. With DC off, preset test voltage to 120% of PICKUP value.
- With DC on, apply test voltage. The relay should trip in the set time ±10%.

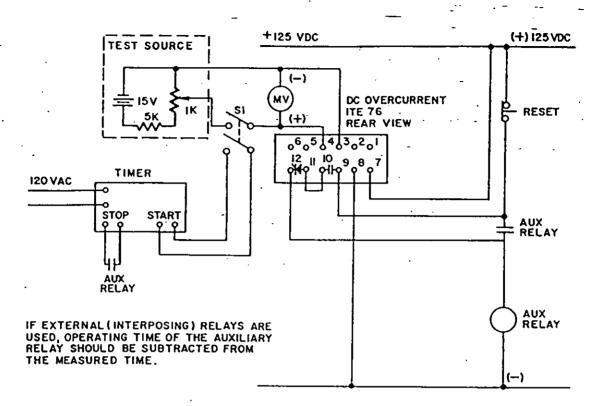


FIGURE 4 CALIBRATION TEST SCHEMATIC (Typical)

NOTES:

- For testing rate-of-rise function, test source must be replaced with a signal generator that provides a sawtooth output waveform. As an alternate, some oscilloscopes provide a swwep signal output (sawtooth wave) that can be used as the signal source.
- Operating time of the auxiliary relay used in the test scheme should be subtracted when making timing tests.



BBC Brown Boverl, Inc. 35 North Snowdrift Road Allentown, PA 18106 Phone: (215) 395-7333

Issue A (12/86) Supersedes 18.5.7-2

These instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation, or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes the matter should be referred to Brown Boveri.

SINGLE LEG ASSY. 609544 Brown Boveri Electric, Inc. REV. Manufacturer of I-T-E Electrical Power Equipment SIZE / SHEET NO. CONT. ON NEXT ASSY. BY DEA місво. сно. APP. DATE 12(12/82 DATE 12/12/83 P.O. DATE 12-9-83 S.O. PROD. CLASS THIS DRAWING IS THE PROPERTY OF BROWN-BOVERI ELECTRIC, INC. AND CONTAINS PROPRIETARY AND CONFIDENTIAL INFORMATION WHICH MUST NOT BE DUPLICATED. USED, OR DISCLOSED OTHER THAN AS EXPRESS-LY AUTHORIZED BY BROWN-BOVERI ELECTRIC, INC. STANDARD TOLERANCE INFO. ON DR. 52016 DIMENSIONS ARE IN INCHES TOLERANCES - UNLESS OTHERWISE SPECIFIED - 3 PL. DEC. + 2 PL. DEC. ± - 6.36 .45 .42 1.0 max. 000 FO 1.65 REF DO EO .55 REF .52 PIN CONN.IDENT. .72 (2).265 DIA FRONT VIEW MTG HOLES EPOXY MOULDING OUTLINE 1.44 1.81 10 DRAFT . 81 NOTE: EVISION 1- WHEN MOUNTING USE 1/4-20 OR SMALLER NON- MAGNETIC HARDWARE, AND (1) 612310-001 MTG CLIP OR SIMILAR NON- MAGNETIC PLATE. 2-ALL DIMENSIONS FROM BOTTOM OF MOULDING (TO INCLUDE I°DRAFT]. 4 3 2 609877-K2 SENSOR , C PC - 4000 - 6 609877- KI SENSOR , CPC - 500 0-K5 K4 K3 K2 K 1 PC.NO. DRAWING DESCRIPTION FORM 88-826 NUMBER ŘEV.



INSTALLATION AND OPERATING INSTRUCTIONS

TEMPERATURE CONTROLS

MODELS 2E206, 2E207 & 2E728

FORM 551421 55881

DAYTON ELECTRIC MANUFACTURING CO. CHICAGO 60648

0383/490/

READ INSTRUCTIONS CAREFULLY BEFORE ATTEMPTING TO INSTALL OR OPERATE THE DAYTON TEMPERATURE CONTROLS!

RETAIN INSTRUCTIONS FOR FUTURE REFERENCE.



Figure 1

Description

The single stage Models 2E206 (SPDT) and 2E728 (SPST) and the two stage Model 2E207 (SPDT) are designed to control automatic ventilation or heating systems. The 30° to 110°F temp range permits use for many space applications.

NOTE: Not for use where a National Electrical Code Article 547 approved control is required.

The enclosed switches are protected against dust and other foreign materials. A compact helical temperature element, treated to minimize corrosion, is firmly attached to the exterior of the case and when the thermostat is mounted with bulb pointed down, it is protected from falling objects, dirt, etc.

Specifications

MODEL 2E728: One SPST switch (one set of contacts , opens on temperature drop).

MODEL 2E206: One SPDT switch (one set of contacts opens on temperature rise as the other set closes simultaneously).

MODEL 2E207: Two SPDT switches, with one-stage operating 3°F higher than the other stage.

Range: 30° to 110°F. (140°F. maximum overrun temperature).

Differential: Approximately 31/2°F. (Each switch has this differential on Model 2E207).

Temperature between stages: (Model 2E207) This difference is fixed; the low stage makes contacts R to Y at the dial setting while the high stage makes contact approximately 3°F above the dial setting.

Case: 062" cold rolled steel. Gray baked enamel finish. Cover: .025" cold rolled steel. Gray baked enamel finish.

Contact Unit: Snap-acting contacts in dust-tight tamper proof enclosure.

UL Listed.

ELECTRICAL RATINGS

MODELS 2E206 & 2E728

	Voltage, AC	120	208	240	277
Full loa	ed amps	16.0	9.2	8.0	_
Locked	d rotor amps	96.0	55.2	48.0	
Non-in resista	2E728 SPST: ductive or ince load amps* mp loads)	22.0	22.0	22.0	22.0
Model 2E206: When connected Non- SPST		22.0	22.0	22.0	22.0
Ind.	When connected — SPDT	16.0	9.2	8.0	7.2
Piiot d	uty	12	5 VA, 24.	/600 V.A	ı,C.

*SPST RATING.

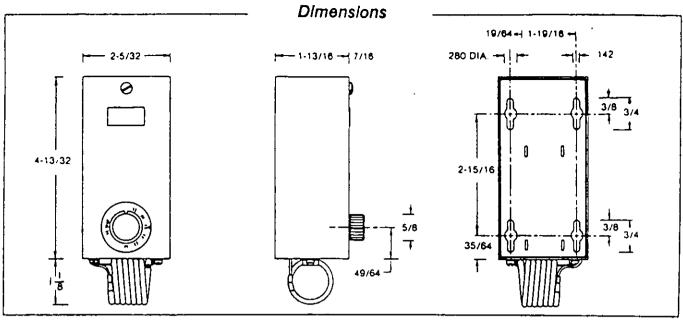
MODEL 2E207

Voltage, AC	120	208	240
Full load amps	16.0	9.2	8.0
Locked rotor amps	96.0	55.2	48.0
Non-inductive or resistance load amps (not lamp loads)	16.0	9.2	8.0
Pilot duty	125 \	/A, 24/277 V	A.C.

NOTE: When used as a two circuit switch, the total connected load must not exceed 2000 VA.

General Safety Information

- Disconnect power supply before wiring connections are made to prevent possible electrical shock or damage to equipment.
- All wiring should conform to the National Electrical Code and local regulations.
- 3. Loads exceeding the rating of the thermostat should be handled with a relay or motor starter.
- 4. These thermostats are designed to function as operating controls only, and do not have temperature limit ratings. Where critical or high value products are to be maintained, an approved temperature limit should be wired in series with these thermostats. In less critical applications, a second thermostat with alarm contacts can be used to provide redundancy.



Performance specifications appearing herein are nominal and are subject to accepted manufacturing tolerances and application variables.

Figure 2 — Dimensions

Installation

LOCATION

Mount control 5' to 6' above the floor where it will be exposed to the average temperature of the controlled space. Do not mount control where it will be affected by unusual heat or cold such as directly exposed to body heat or in sunlight. Avoid locations near a door, window or other opening. Do not mount on an outside wall.

MOUNTING

CAUTION: Do not dent or deform the sensing bulb of this control. A dent or deformation will change the calibration and cause the control to cycle at a temperature lower than the dial setting.

CAUTION: On rough mounting surface use top two mounting holes only. When you mount this control on an uneven surface and pull all four mounting screws down tight, you can twist the case enough to affect thermostat calibration and operation.

WIRING

All wiring should be done in accordance with applicable codes, ordinances and regulations, Figures 3, 4, and 5 illustrate typical wiring of Models 2E206 and 2E728 for control of heating, cooling, and a combination heating-cooling control system.

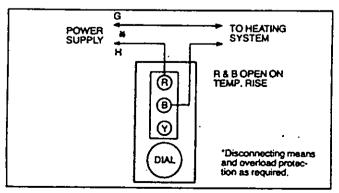


Figure 3 — Model 2E206 in typical heating control circuit.

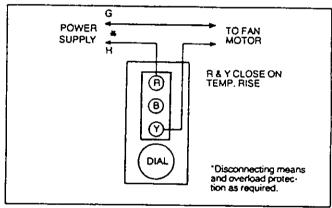
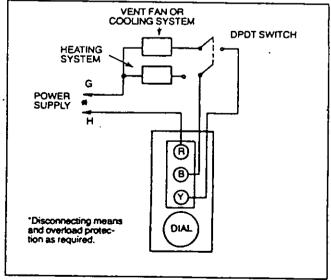


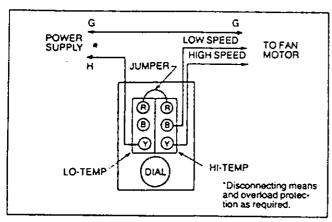
Figure 4 — Models 2E206 & 2E728 in typical ventilating or cooling control circuit. (Terminal B is not used on Model 2E728.)



<u>Figure 5 — Model 2E206 in control of heating and ventilating systems.</u>

Installation (Continued)

Figure 6 shows typical wiring for the control of a two speed ventilating fan. When control temperature element reaches the dial settings of Model 2E207, the low temperature switch starts the fan on low speed. If the space temperature continues to rise, the high temperature switch supplies power to the high speed motor winding while disconnecting the low speed winding.



<u>Figure 6 — Model 2E207 in typical two-speed</u> ventilating fan control circuit.

Figure 7 shows Model 2E207 in a typical hook-up for a two-volume fan application. The fan will start when the temperature element reaches the dial setting. If the temperature continues to rise, the damper motor will be energized by the high temperature switch.

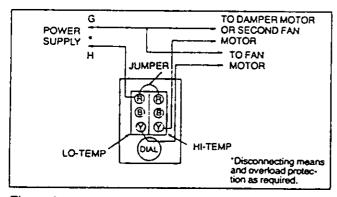


Figure 7 — Model 2E207 in control of single speed ventilating fan and volume-increase damper motor.

Model 2E207 can also be used to control a combination heating and ventilating or cooling system, as shown in Figure 8. A temperature increase to the dial setting will turn off the heating system when the R-B contacts of the low temperature switch break. An increase in temperature of about 3°F will turn on the fan or cooling system through the R-Y contacts of the high temperature switch.

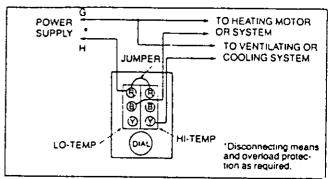


Figure 8 — Typical wiring of heating and cooling devices to Model 2E207 two-stage thermostat (automatic changeover).

Figure 9 illustrates typical wiring of Model 2E207 for control of two stages of heating. As the space temperature decreases to the dial setting, the high temperature switch will make R-B turning on the first stage of heating. If the temperature continues to drop (about 3°F.) the low temperature switch will make R-B turning on the second stage of heating.

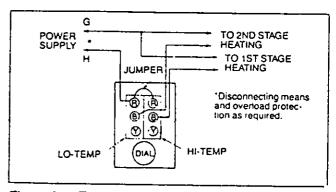


Figure 9 — Typical wiring of two-stage heating.

CHECKOUT PROCEDURE

Before leaving the installation, a complete operating cycle should be observed to see that all components are functioning properly.

Check for correct operation in the following manner:

- Models 2E206 & 2E728 Ventilating or Cooling System: Turn dial clockwise to a setting above space temperature. Fan or cooling system should be off. When dial is turned counterclockwise, the fan or cooling system should turn on approximately at the dial setting.
 - Model 2E206 Heating System: Turn dial clockwise above the space temperature; the heating unit should be on. When dial is turned counterclockwise, the heating unit should turn off approximately at the dial setting.
- Model 2E207. If hook-up is similar to Figure 6, fan should start at approximately space temperature and should change to high speed as the dial is turned counterclockwise to a lower temperature setting. If wiring is similar to Figure 7, the damper should open as the dial is turned counterclockwise. The devices should act in reverse sequence when the dial is turned clockwise.

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Operation

Figure 10 illustrates the operation of Model 2E207. On a temperature increase to the dial setting, the circuit between R and Y of the low stage switch (RYL) closed. Simultaneously the circuit between R and B (RBL) opens. On a further increase in temperature the high stage switch operates and closes (RYH) while simultaneously opening (RBH). The reverse sequencing takes place on a temperature fall.

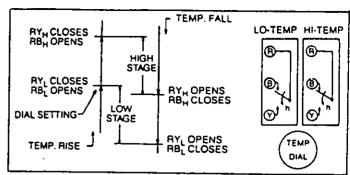


Figure 10 — Operational diagrams of Model 2E207.

Trouble Shooting Chart

	trouble on our and or	
	MODELS 2E206 & 2E728	
SYMPTOM	POSSIBLE CAUSE(S)	CORRECTIVE ACTION
Cooling or fan does not operate	Improper wiring Thermostat dial set above space temperature	Check wiring. Set dial to lower temp.
Cooling or fan runs continuously	Improper wiring Thermostat dial set below space temp.	Check wiring. Set dial to higher temp.
	MODEL 2E206	
SYMPTOM	POSSIBLE CAUSE(S)	CORRECTIVE ACTION
System operates in reverse.	Improper wiring	Check wiring.
Heating unit does not operate.	Improper wiring Thermostat dial set below space temp.	Check wiring. Set dial to higher temp.
Heating unit runs continuously	Improper wiring Dial set above space temperature	Check wiring. Set dial to lower temp.
	MODEL 2E207	
SYMPTOM	POSSIBLE CAUSE(S)	CORRECTIVE ACTION
Cooling or fan does not operate.	Improper wiring Thermostat dial set too high	Check wiring. Adjust dial to lower setting.
Cooling or fan runs continuously	Improper wiring Thermostat set too low	Check wiring. Adjust to higher setting.
Heating does not operate. (Figure 9).	1. Improper wiring 2. Thermostat set too low	Check wiring. Adjust thermostat to higher setting. First stage of heating should come on when dial setting equals space temp. As dial is adjusted to higher temp. (3° F.) second stage of heating unit should come on.
Heating system runs continuously	Improper wiring Thermostat set too high	Check wiring. Adjust to lower setting.
System runs in reverse.	Improper wiring	Check wiring.

LIMITED WARRANTY

Deyton temperature controls, Models 2E206, 2E207 & 2E728, are warranted by Deyton Electric Milg. Co. (Deyton) to the original user against defects in workmanship or materials under normal use (rental use accluded) for one year after date of purchase. Any part which is determined to be defective in material or workmanship and returned to an authorized service location, as Deyton designates, shipping costs prepaid, will be repaired or replaced at Deyton's option. For warranty claim procedures, see "Prompt Disposition" below. This warranty gives purchasers specific legal rights, and purchasers may also have other rights which very from state to state.

WARRANTY DISCLAIMER. Deyton has made a diligent affort to illustrate and describe the products in this literature accurately; however, such illustrations and descriptions are for the sole purpose of identification, and do not express or imply a warranty that the products are merchantable, or fit a particular purpose, or that the products will necessarily conform to the illustrations or descriptions.

Except as provided below, no warranty or affirmation of fact, expressed or implied, other than as stated in "LIMITED WARRANTY" above is made or authorized by Deyton, and Deyton's liability in all events is limited to the purchase price paid.

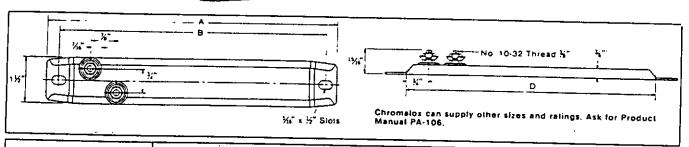
Certain aspects of disclaimers are not applicable to consumer products; e.g., (a) some states do not allow the exclusion or limitation of incidental or consequential demages, so the above limitation or exclusion may not apply to you; (b) also, some states do not allow limitations on how long an implied warranty lasts, consequently the above limitation may not apply to you; and (c) by law, during the period of this Limited Warranty, any implied warrantes of merchantability or liness for a particular purpose applicable to consumer products purchased by consumers, may not be excluded or otherwise disclaimed.

PROMPT DISPOSITION. Depton will make a good faith effort for prompt correction or other adjustment with respect to any product which proves to be defective within warranty. For any product believed to be defective within warranty, first write or call dealer from whom product was purchased. Dealer will give additional directions. If unable to resolve satisfactority, write to Deyton at address below, giving dealer's name, address, date and number of dealer's invoice, and describing the nature of the defect. If product was damaged in transit to you, file claim with carmer.

DAYTON ELECTRIC MFG. CO., 5959 W. HOWARD ST., CHICAGO, ILLINOIS 60648

Type OT-1½" wide
Two off-set bolt terminals
It one end





			1	Ru	st-resis	ting iron sh	eath		Ch	voma s	teel sheath	· · · · · · · · · · · · · · · · · · ·	$\overline{}$
Dir	mensions –		;	See pg.	178 fo	max. shea	th temp.	s	ee pg. 1	78 for r	nax, sheath	temn	
Overall Length	Mig. Hole Center	Mig. Tabs	Volts	Walls	Watts Per Sq. In,	Catatog Number	Product Code No. (PCN)	Volt		Walts Per Sq. In.	Catalon	Product Code No. (PCN)	Appro Net Wt. Lb
71/2	61/2	6	120 240	150 150	11 11	OT-715 OT-715	129314 129322	120 240	200 200	15 15	OT-702 OT-702	129613 129621	.50
8	7	61/2	120 240	150 °	10 10	OT-815 OT-815	129330 129349	120 240	250	17	OT-802	129630	.50
			120 240	175 175	12 12	OT-817 OT-817	129357 129365	120	400 400	27	OT-802	129648 129656	.56
101/2	91/2	9	120 240	250 250	10 10	OT-1025 OT-1025	129373	120	350	27 15	OT-804 OT-1003	129664 129672	.56, .75
				••••	٠.	******	129381	120	350 400	15	OT-1003	129680 129699	.75 .88
12	11	101/2	120	250	8	OT-1225	129390	120	400 250	- <u>17</u> - <u>8</u>	OT-1004 OT-1202	129701	.88
			240	250		OT-1225	129402	240 120	250 350	8	OT-1202 OT-1203	129710 129728	.88 .88
		ı		•••				240	350 500	14	OT-1203 OT-1205	129736 129744	.88
14	13	121/2	120	300	8.	OT-1430	129410	240	500	17	OT-1205	129752 129760	.88 .88
151/4	141/4	13¾	240	300	8	OT-1430	129429	120 240	500 500	14 14	OT-1405 OT-1405	129779 129787	1.0 1.0
			120 240	325 325	8	OT-1532 OT-1532	129437 129445	120 240	500 500	12 12	OT-1505 OT-1505	129795 129808	1.13
17%	16%	16%	120 240	350 350	6.5 6.5	OT-1835 OT-1835	129453 129461	120 240	500 500	10 10	OT-1805 OT-1805	129816 129824	1.38
			120 240	375 375	7	OT-1837 OT-1837	129470 129488	120 240	750 750	15 15	OT-1807 OT-1807	129832 129840	1.38 1.38 1.38
·			120 240	500 500	10 10	OT-1850 OT-1850	129496 129509	120 240	1000 1000	19 19	OT-1801 OT-1801	129859 129867	1.38 1.38
191/2	181/2	18	120 240	350 350	6 6	OT-1935 OT-1935	129517 129525	120 240	500 500	9	OT-1905 OT-1905	129875	1.5
			120 240	500 500	8 8	OT-1950 OT-1950	129533 129541	120 240	750 750	13.5 13.5	OT-1907 OT-1907	129883 129891 129904	1.5
			•••	•••				120 240	1000 1000	18 18	OT-1901 OT-1901	129912 129920	1.5 1.5 1.5
Z1 	20		120 240	500 500	8	OT-2150 OT-2150	129550 129568	120 240	750 750	12 12	OT-2107 OT-2107	129939	1.63
3%	22¾		120 240	500 500	7	OT-2450 OT-2450	129576 129584	120 240	500 500	7	OT-2405	129947 129955	1.63
			120 240	750 750	10 10	OT-2475 OT-2475	129592 129605	120 240	750 750	7	OT-2405	129963 129971	1.81
								120	1000 1000	14	OT-2407 OT-2401		1.81 1.81
				•••		******		120	1500 1500 1500	19	OT-2401		1.81

Specify: Quantity catalog no PCN volts waits strip heaters. For additional features (page 179) available for Type OT add without inounling tabs, secondary insulation bushings. PCN 255716 protective terminal cover—catalog no OT-AC-1. PCN 129242, set of two ceramic post.

POTENTIAL TRANSFORMER

Model 465

FREQUENCY: 50 & 60 Hz.

STANDARD SECONDARY VOLTAGE: 120 Volts

INSULATION CLASS: 600 Volts, 10 Kv. Bil.

ACCURACY CLASS: 0.6 W., 1.2X at 60 Hz

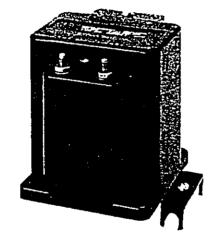
THERMAL RATING: 150 VA at 30°C amb., 100 VA at 55°C amb.

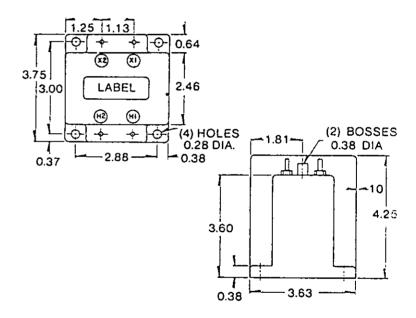


All models on this page U.L. recognized - file no. E93779.

- The model 465-380 is designed specifically for 50 Hz operation.
- This page contains a circle diagram for the estimation of the errors for other than rated burdens.
 See elsewhere in this P.T. section for a description of its use.
- · Approximate weight: 7.75 lbs.

- Terminals are brass studs No. 10-32 with one lockwasher, flat washer & regular nut.
- The core and coil assembly is encased in a thermoplastic shell and filled with resin.
- These transformers are designed for operation line-to-line. They may also be operated line-to-ground or line-toneutral, at reduced voltage, (58% of rated volts).
- It is desirable to use the proper size fuse in the secondary to protect the P.T. Use a 1.6 amp fuse with Model 465.
- With three exceptions these transformers are ANSt C57.13 group 1. Those marked * are group 2.
- Other ratios available upon request.





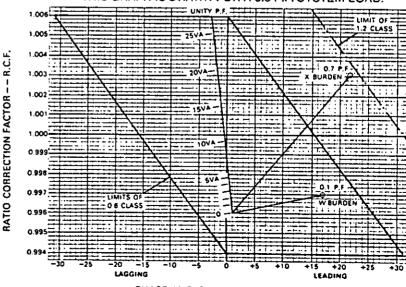
APPLICATION AND ORDERING DATA

	RATING 69 69.4:120 20 120:120 88 208:120 60 240:120	
CATALOG NO.		TURNS RATIO
465-069	69.4:120	0.58:1
465-120	120:120	1:1
465-208	208:120	1.73:1
465-240	240:120	2:1
465-288	288:120	2.4:1
465-300	300:120	2.5:1
*465-480	480:120	4,1
*465-600	600:120	5:1
*465-380	380:120	3.17:1 for 50HZ

ANSI. C.57.13., burden data....

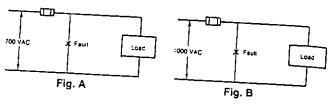
BUADEN	FACTOR	VOLT-	ANGLE
W	0.1	12.5	84.3*
х	0.7	25.0	45.6*
М	0.2	35.0	78.5°
Y	0.85	75.0	31.8*
Z	0.85	200.0	31.81
ZZ	0.85	400.5	31.8*

POTENTIAL TRANSFORMER CIRCLE DIAGRAM
THIS GRAPH IS DRAWN FOR A 0.6 P.F. SYSTEM LOAD.



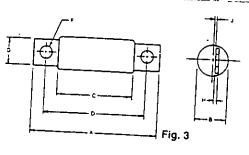
Amp-trap®-Form 101 Semiconductor Fuses

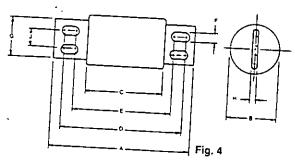
A100P



I2t Data For A100P Fuses—1000 Volts AC

FUSE AMPERE RATING MELTING CLEARING 1 FUSE 1 FUSE AT 700VAC (FIG. A) X 10 ³ A ² S X 10 ³ A ² S	T Data For A lot	P Fuses—1	000 Volts AC				
AMPERE RATING MELTING 1 FUSE AT 700VAC (FIG. A) 1 FUSE AT 1000VAC (FIG. B) 1 FUSE AT 700VAC (FIG. B) 1 FUSE AT 1000VAC (FIG. B)	 	I ² t DATA (AMPER	E ² SECONDS)	J	121 DA	TA (AMPEREZ	
X 10 ³ A ² S	AMPERE MELT	1 FUS AT 700\ (FIG. A	SE 1 FUSE VAC AT 1000VAC	AMPERE		CLEARING 1 FUSE	CLEARING 1 FUSE
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	25	12S × 103A	(/ (G, D)	1	V 103420	(FIG. A)	AT 1000VAC (FIG. B)
1.0	40 .2 50 .66 60 .86	1.5	2.9 4.5	250 300	12 15 22	48 59	91
100	70 1.2			400	<u>-</u>		220
200 9.6 21 41 700 120 470 880 9.6 38 72 1,000 240 950 1,900	100 2.4 125 3.8	9.5	12 18	600 650	60 86	240 340	290 450 650 760
Fig. 3	300		41	800	150	610	880 1,200
	4						
	catalog		TOURS AL			1	5





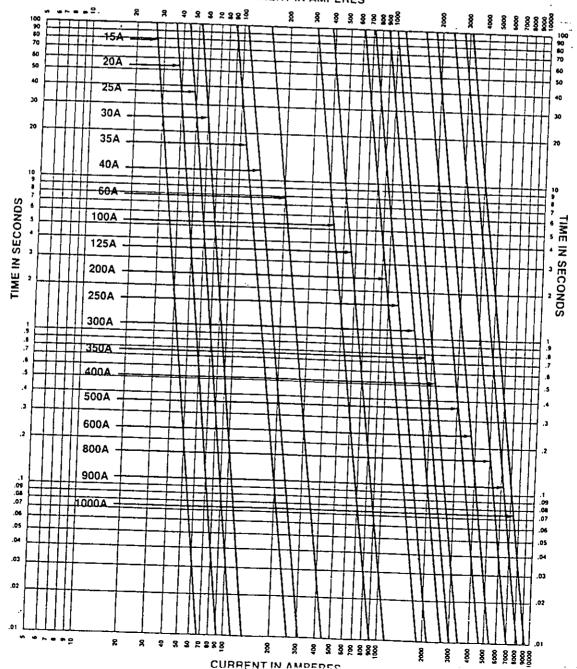
Dimensions For A100P Fuses—1000 Volts AC

FIG.	CATALOG NUMBER	MOUNTING				DIMEN	ISIONS-	JNCHE			
1	A100P15-30	TYPE	A	В	С	D	E	F	G	Н	.
2 2 2	A100P35-60 A100P65-100 A100P110-200	4 4 4	25/8 5 5 5 ²³ / ₃₂	1 17/32 11/2	3½ 3½ 3½ 3½ 3½	45/16 45/16	43/16	- 5/16 5/16	3/4	- 1/8 3/16	-
2 2 3 4	A100P225-400 A100P450-600 A100P650-800 A100P850-1000	4 4 4	5 ²³ / ₃₂ 7 ²³ / ₃₂ 7 ⁷ / ₁₈ 8 ⁷ / ₃₂	2 2½ 2½ 3½	315/32 315/32 315/36 415/32	4 ²⁵ / ₃₂ 4 ²⁵ / ₃₂ 5 ⁷ / ₈ 5 ¹⁵ / ₁₈	45/32 45/32 59/16	13/32 13/32 17/32 5/8	1 11/2 2 2 2	1/4 1/4 3/6 3/8	

Amp-trap®-Form 101 Semiconductor Fuses

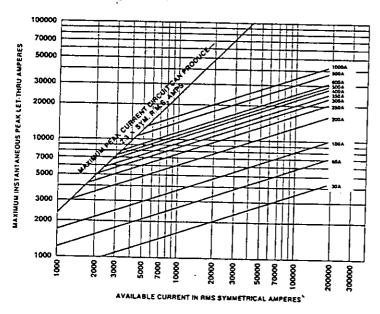
A100P

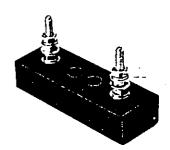
Melting Time—Current Data—A100P Fuses 15-2000 Amperes, 1000 Volts AC/DC CURRENT IN AMPERES



Amp-trap®-Form 101 Semiconductor Fuses A100P

Peak Let-Thru Current Data A100P Fuses 30-1000 Amperes, 1000 Volts AC





Single Pole Fuse Blocks⁺ For A100P Fuses

FUSE AMPERE RATING	FUSE BLOCK CATALOG NUMBER
35-100	P266G
125-400	P266L

^{*}Dimensions are shown on page 111.

Standard Fuse Ampere Ratings* For A100P Fuses

AMPERE RATING	MOUNTING TYPE	AMPERE RATING	MOUNTING TYPE	AMPERE RATING	MOUNTING TYPE
15	1	70	4, 4TI	350	4, 4Ti
20	1 1	80	4, 4Ti	400	4, 4Ti
25	1 1	100	4, 4TI	500	4, 411 4, 4TI
30	1 1	125	4, 4TI	600	
35	4	150	4, 4TI	650	4, 4TI 4
40	4	200	4, 4Ti	700	4
50	4, 4TI	225	4	800	4, 4TI
60	4, 4TI	250	4, 4TI	1,000	•
65	4	300	4, 4TI	1,000	4

Includes standard ampere ratings and the mounting types available in each ampere rating.

Amp-trap®—Form 101 Fuse Blocks

A13X/A25X/A50P A60X/A70P/A70Q/A100P

ORIES

uffix TA) is ses. This fuse ed on the ation. The sed to discretion. On the ng or e effect on pere or ctuator will sto the oil ass an open.



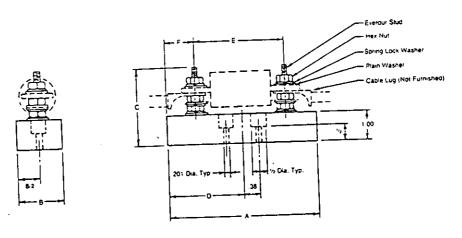
on extends from per Actuator of n fuse opens.

es resistive. imum. Two vailable. type terminals with push-on



log Number AOS 3

Dimensions:



Fuse Block Dimensions—For Type 4 Form 101 Amp-trap® Fuses

е віоск	Dimensions				DIMI	ENSIONS	-INC	HES		STU
	AMPERES	CATALOG	FOR USE	T	В	С	D	E	F	SIZ
VOLTS	AMPERES	NUMBER	<u> </u>	41/2	11/2	21/2	21/4	21/16	17/32	1/4-
130	70-450	P243D P243G	A13X, A13Z A13X, A13Z	41/2	11/2	21/2	21/4	27/10	17/32	5⁄16- 5∕16-
130	500-600	 	A25X, A25Z	41/2	11/2	21/2	21/4	27/16	11/32	716
250	35-60 70-200	P243G P243	A25X, A25Z A25X, A25Z	4½ 4½	11/2	21/2	21/4	2% 2%	11/32	5/16
200	225-600	P243G		41/2	11/2	21/2	21/4	27/16	11/32	5/16 1/4
500	35-60 70-200	P243G P243E	A50P A50P	41/2	11/2	21/2	21/4 3	27/6 3%32	123/64	3/0
300	225-600	P266C	A50P	41/2	11/2	21/2	21/4	35/8	7/16	1/4
	35-200	P243C	A60X, A60Z A60X, A60Z	6	2"	3	3	41/16	31/32	3/1
600	225-600	P266A		41/2	11/2	21/2	21/4	35/6	7/16	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
700	35-100 125-400	P243C P266A	A70P, A70Q A70P, A70Q	6 8	2 21/2	3	3 4	4½16 53/32	31/32 1 ²⁹ /64	3/
700	450-600	P266F	A70P, A70Q			21/2	3	41/4	7/6	1 7
1000	35-100 125-400	P266G P266L	A100P A100P	6	2 2	3	3	421/32	43/84	<u> </u>

DRAWING REFERENCE LIST

4482-A2	_	DRAWING REFERENCE LIST
4482-D3	_	CATHODE BREAKER ELEMENTARY
4482-D4	_	TRACK FEEDER BREAKER ELEMENTARY
4482-D5	_	GAP AND STORAGE TRACK FEEDER ELEMENTARY
4482-D6		COMMON CIRCUITS ELEMENTARY
4482-D7	_	ANCHORING DETAIL
4482-D11	_	
4402 DII		ELEVATION AND SECTIONS VIEWS - WINDHAM LANE SUBSTATION
4482-D12	-	ELEVATION AND SECTION VIEWS - LANSDOWNE WAY SUBSTATION
4482-D13	-	ELEVATION AND SECTION VIEWS - U-STREET SUBSTATION
4482-D14	-	ELEVATION AND SECTION VIEWS - MOUNT VERNON SQUARE SUBSTATION
4482-D15	-	ELEVATION AND SECTION VIEWS -
		MOUNT VERNON SQUARE TIE BREAKER STATION
4482-D16	_	ELEVATION AND SECTION VIEWS -
510		NOYES LANE TIE BREAKER STATION
		NOTES DAME THE BREAKER STATION
4482-D17	_	ELEVATION AND SECTION VIEWS -
_		HILDAROSE DRIVE TIE BREAKER STATION
		' DYFILE DYPAKTY DIVIDA
4482-D18	_	ELEVATION AND SECTION VIEWS -
		WHEATON TIE BREAKER STATION
4482-D19	_	ELEVATION AND SECTION VIEWS -
		SHAW TIE BREAKER STATION
4482-D21	_	POWER DIAGRAM - WINDHAM LANE SUBSTATION
4482-D22	_	POWER DIAGRAM - LANSDOWNE WAY SUBSTATION
4482-D23	-	POWER DIAGRAM - U-STREET SUBSTATION
4482-D24	_	POWER DIAGRAM - MOUNT VERNON SQUARE SUBSTATION
		The second of the second secon
4482-D25	_	POWER DIAGRAM - MOUNT VERNON SQUARE
		TIE BREAKER STATION
4482-D26	_	POWER DIAGRAM - NOYES LANE TIE BREAKER STATION
4482-D27		POWER DIAGRAM - HILDAROSE DRIVE
		TIE BREAKER STATION
4400 500		
4482-D28	_	POWER DIAGRAM - WHEATON
		TIE BREAKER STATION

wf:BN6

MICRO FILMED

DRAWN BY				<u> </u>	
5-89	CONTROLLED POWER LIMITED PARTNERSHIP		SIL	11/2/89	Removed Ai - Does not exist
SCALE	1501 RAFF RD SW	NO	BY	DATE	DESCRIPTION
CHK.D	CANTON, OHIO 44710	REVISIONS			
APP D	TITLE DRAVING REFERENCE LIST	DWG NO 448	32-A2		SHEET 1 of 3

DRAWING REFERENCE LIST

4482-D29	-	POWER DIAGRAM - SHAW TIE BREAKER STATION
4482-D31	-	UNIT INTERCONNECTIONS - WINDHAM LANE SUBSTATION
4482-D32 4482-D33	-	UNIT INTERCONNECTIONS - LANSDOWNE WAY SUBSTATION UNIT INTERCONNECTIONS - U-STREET SUBSTATION
4482-D34	-	UNIT INTERCONNECTIONS - MOUNT VERNON SQUARE SUBSTATION
4482-D35	-	UNIT INTERCONNECTIONS - MOUNT VERNON SQUARE TIE BREAKER STATION
4482-D36	-	UNIT INTERCONNECTIONS - NOYES LANE TIE BREAKER STATION
4482-D37	-	UNIT INTERCONNECTIONS - HILDAROSE DRIVE TIE BREAKER STATION
4482-D38	-	UNIT INTERCONNECTIONS - WHEATON TIE BREAKER STATION
4482-D39	-	UNIT INTERCONNECTIONS - SHAW TIE BREAKER STATION
4482-D41	- .	CONNECTION DIAGRAM - CATHODE BREAKER WITH CURRENT TRANSDUCER
4482-D42	-	CONNECTION DIAGRAM - CATHODE BREAKER WITH CURRENT, VOLTAGE AND WATT TRANSDUCER
4482-D43	_	CONNECTION DIAGRAM - 4000A TRACK FEEDER
	-	CONNECTION DIAGRAM - GAP OR STORAGE TRACK FEEDER
4482-D45	-	CONNECTION DIAGRAM - TRACK FEEDER WITH AUXILIARY CIRCUITS
4482-D46	-	CONNECTION DIAGRAM - 6000A TRACK FEEDER
4482-D47	-	EQUIPMENT INTERCONNECTIONS - NOYES LANE TIE BREAKER STATION
4482-D48	-	EQUIPMENT INTERCONNECTIONS - HILDAROSE DRIVE TIE BREAKER STATION

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MICRO FILMED

9-5-89						
SCALE	CONTROLLED POWER LIMITED PARTNERSHIP	NO	BY	DATE	DESCRIPTION	-
CHK.D	CANTON, OHO 44710	REVISIONS				
APP'D ECN	DRAWING REFERENCE LIST	DWG. NO. 4482-A2		\2	SHEET 2 of 3	

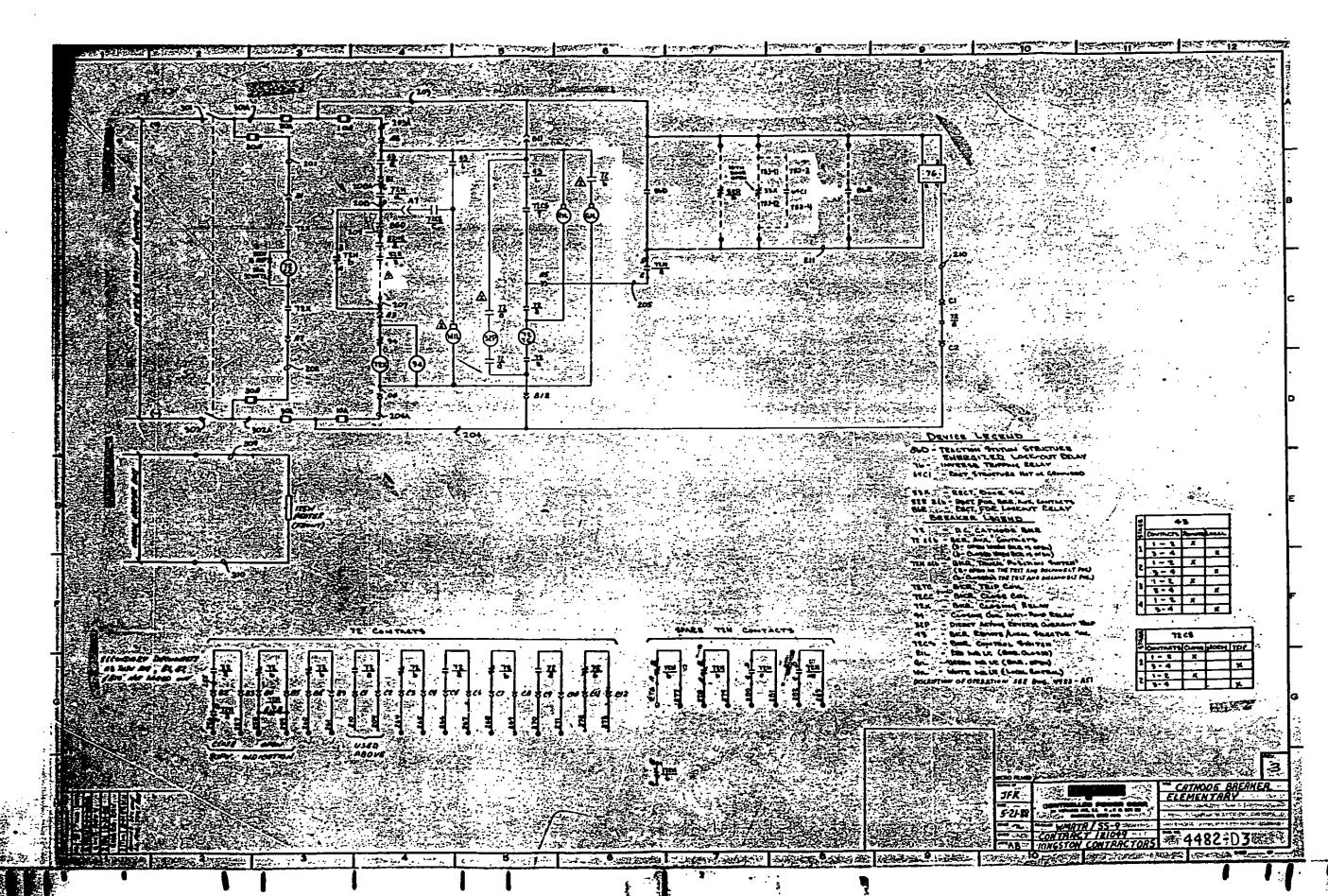
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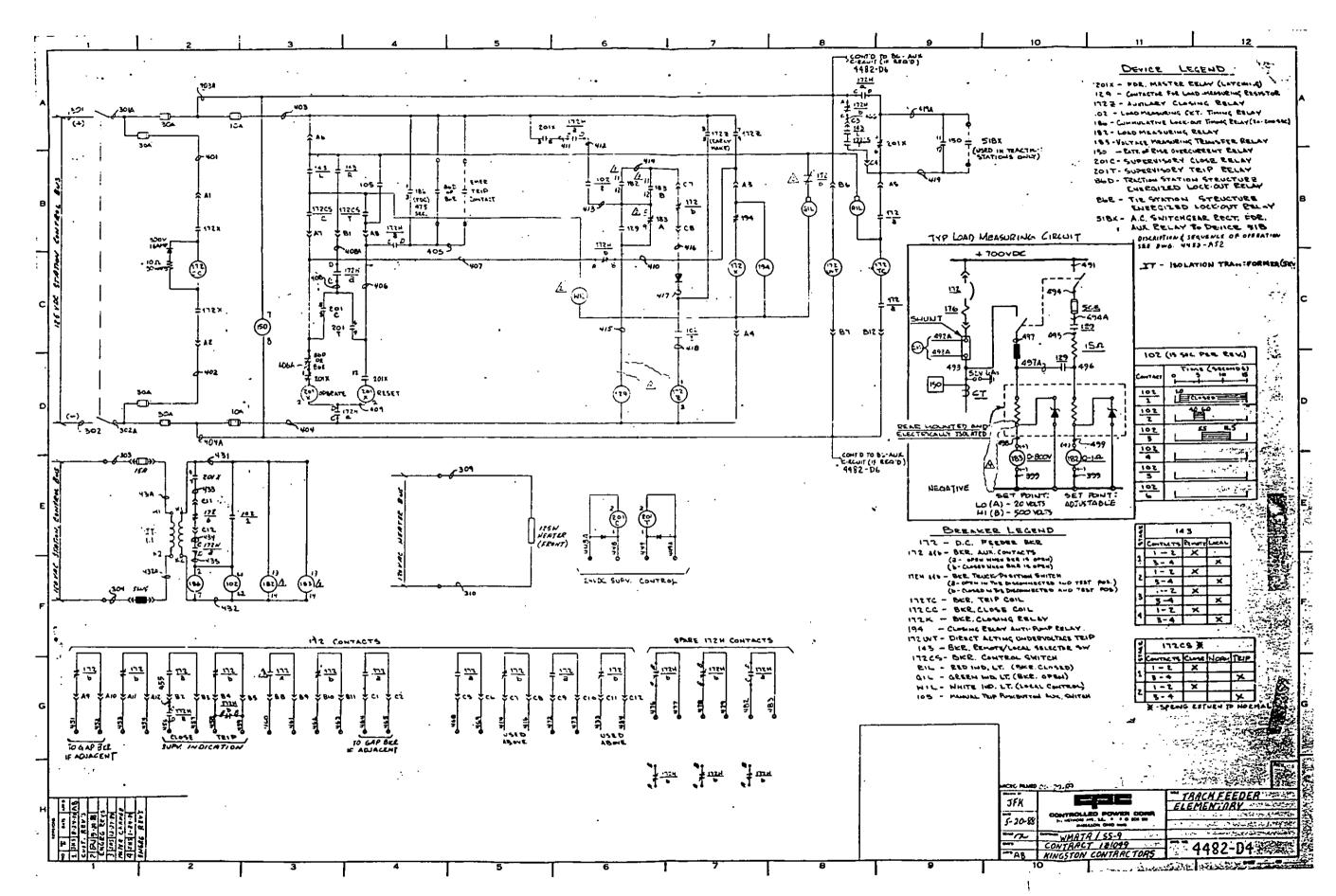
4482-D49	-	EQUIPMENT INTERCONNECTONS - MOUNT VERNON SQUARE TIE BREAKER STATION
4482-D50	-	EQUIPMENT INTERCONNECTIONS - WHEATON TIE BREAKER STATION
4482-D51	-	EQUIPMENT INTERCONNECTIONS - SHAW TIE BREAKER STATION
4482-C108	_	REAR VIEW - WINDHAM LANE SUBSTATION
4482-C109	_	REAR VIEW - LANSDOWNE WAY SUBSTATION
4482-C110		DEAD VIEW - LANSDOWNE WAI SUBSTAILON
		REAR VIEW - U-STREET SUBSTATION
4482-C111	-	REAR VIEW - MOUNT VERNON SQUARE SUBSTATION
4482-C112	-	REAR VUEW - MOUNT VERNON SQUARE TIE BREAKER STATION
4482-C113	_	REAR VIEW - NOYES LANE TIE BREAKER STATION
4482-C114	-	REAR VIEW - HILDAROSE DRIVE TIE BREAKER STATION
4482-C115		REAR VIEW - WHEATON TIE BREAKER STATION
4482-C116		REAR VIEW - SHAW TIE BREAKER STATION
4482-D164	-	EQUIPMENT INERCONNECTIONS - LANSDOWNE WAY SUBSTATION
4482-D165	-	EQUIPMENT INTERCONNECTIONS - WINDHAM LANE SUBSTATION
. 4482-D166		EQUIPMENT INTERCONNECTIONS - MOUNT VERNON SQUARE SUBSTATION
4482-D167	_	EQUIPMENT INTERCONNECTIONS - U-STREET SUBSTATION
4482-A51	_	DESCRIPTION OF OPERATION - CATHODE BREAKERS
	-	
4482-A52	-	DESCRIPTION OF OPERATION - TRACK FEEDER BREAKERS

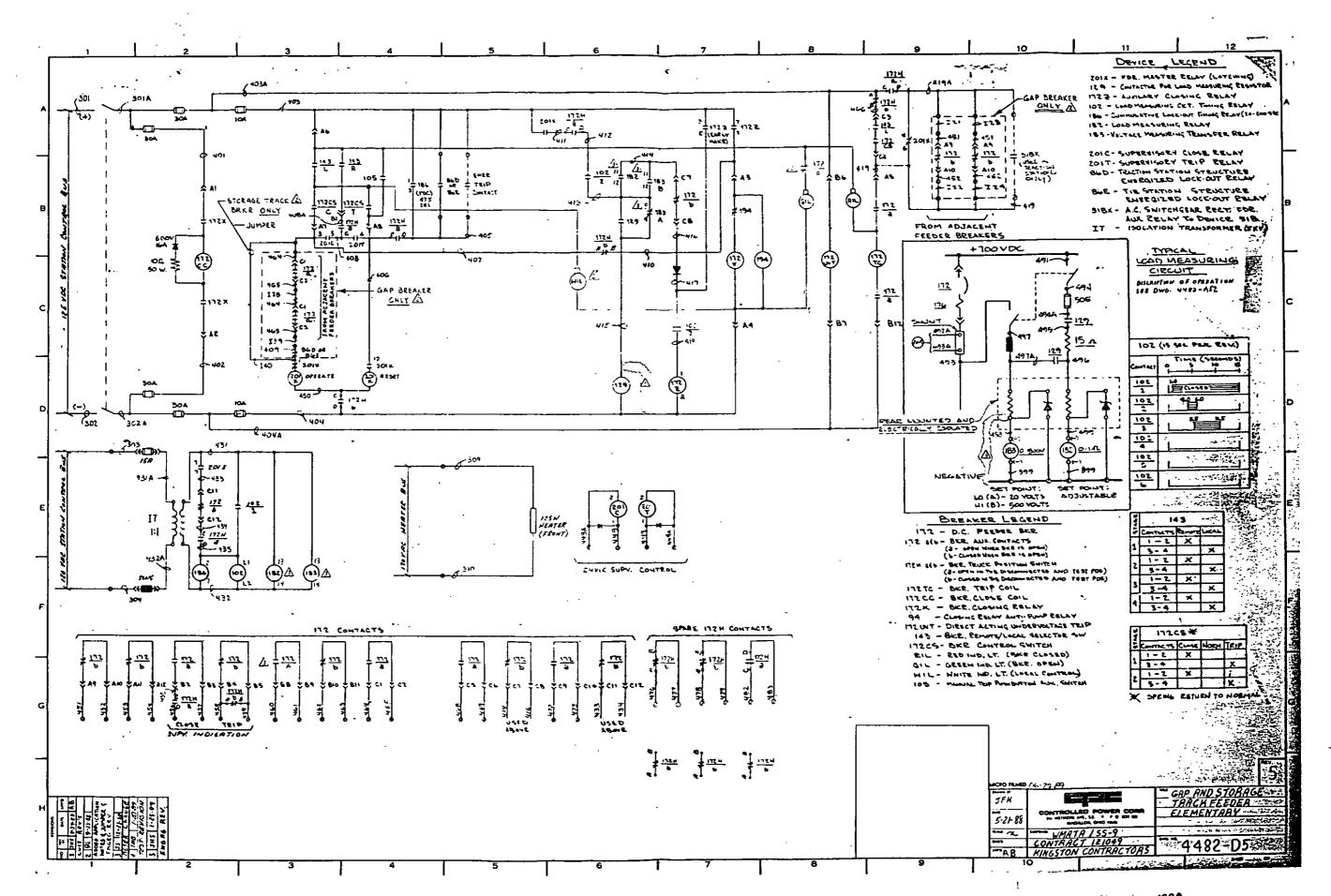
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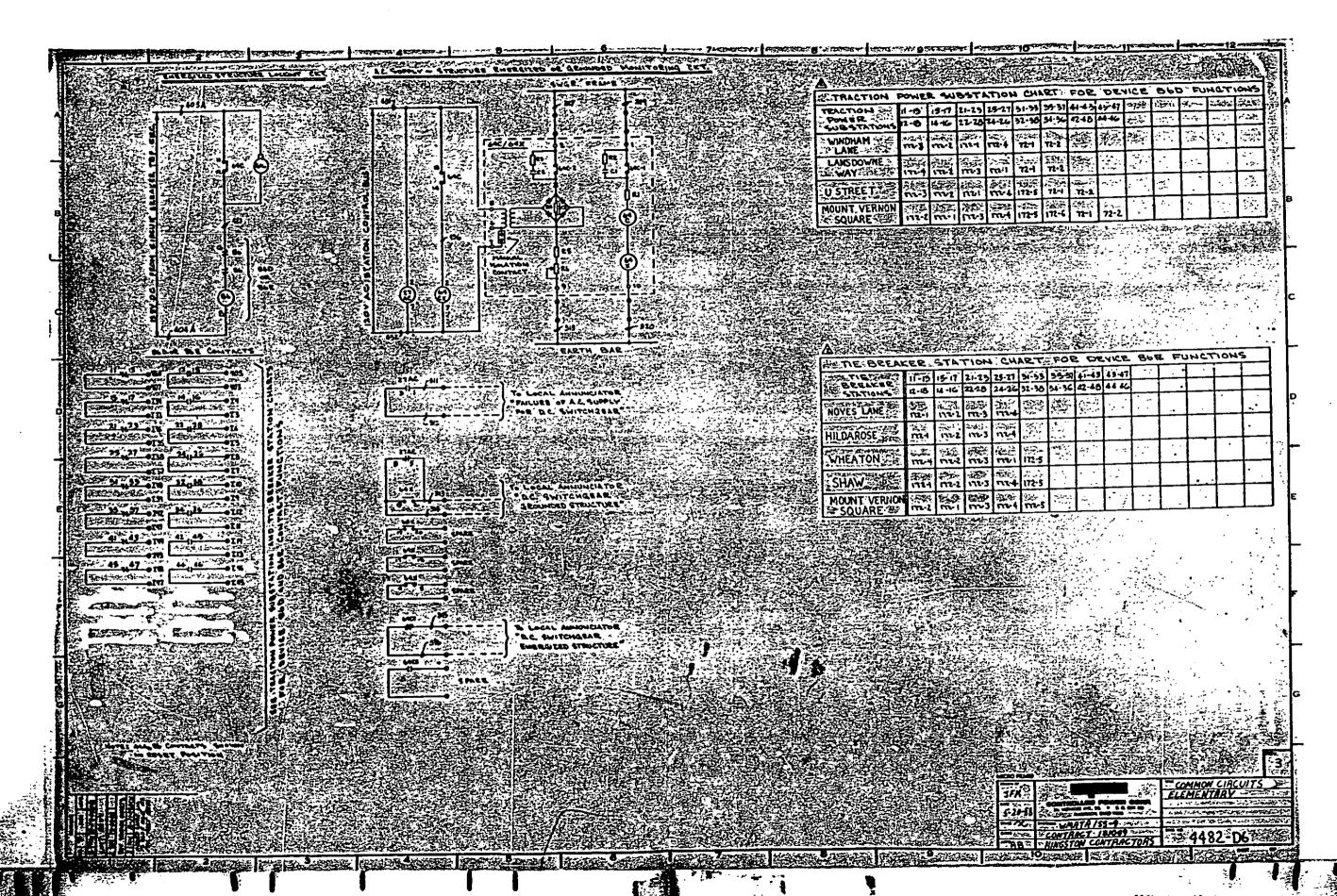
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^E 9-5-89						
SCALE	CONTROLLED POWER LIMITED PARTNERSHIP	NO .	BY	DATE	DESCRIPTION	
CHK'D.	CANTON, OHIO 44710	REVISIONS				
APP'D. BCN	DRAWING REFERENCE LIST	DWG. NO. 4482-A2		<u> </u>	SHEET 3 of 3	

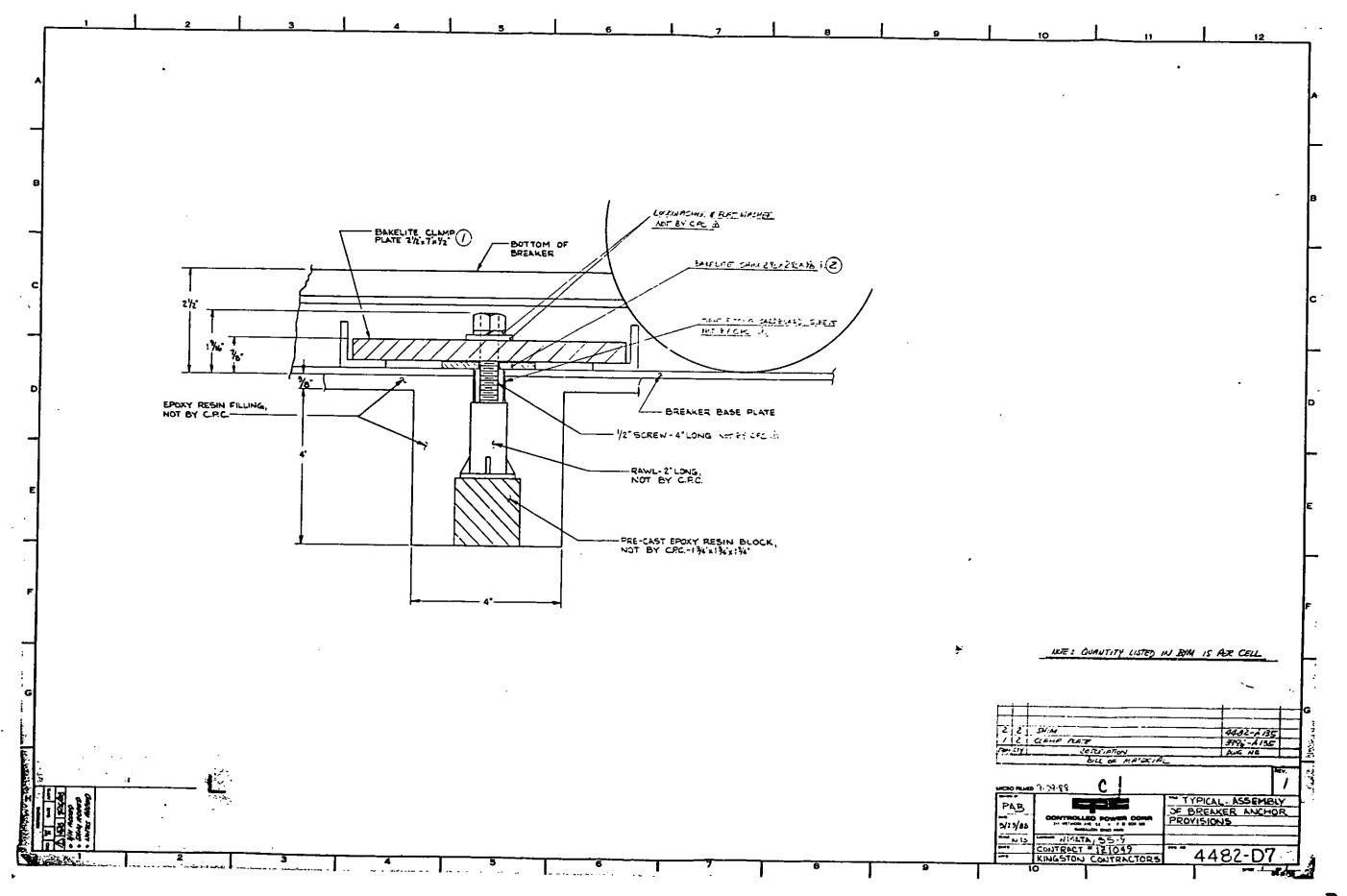




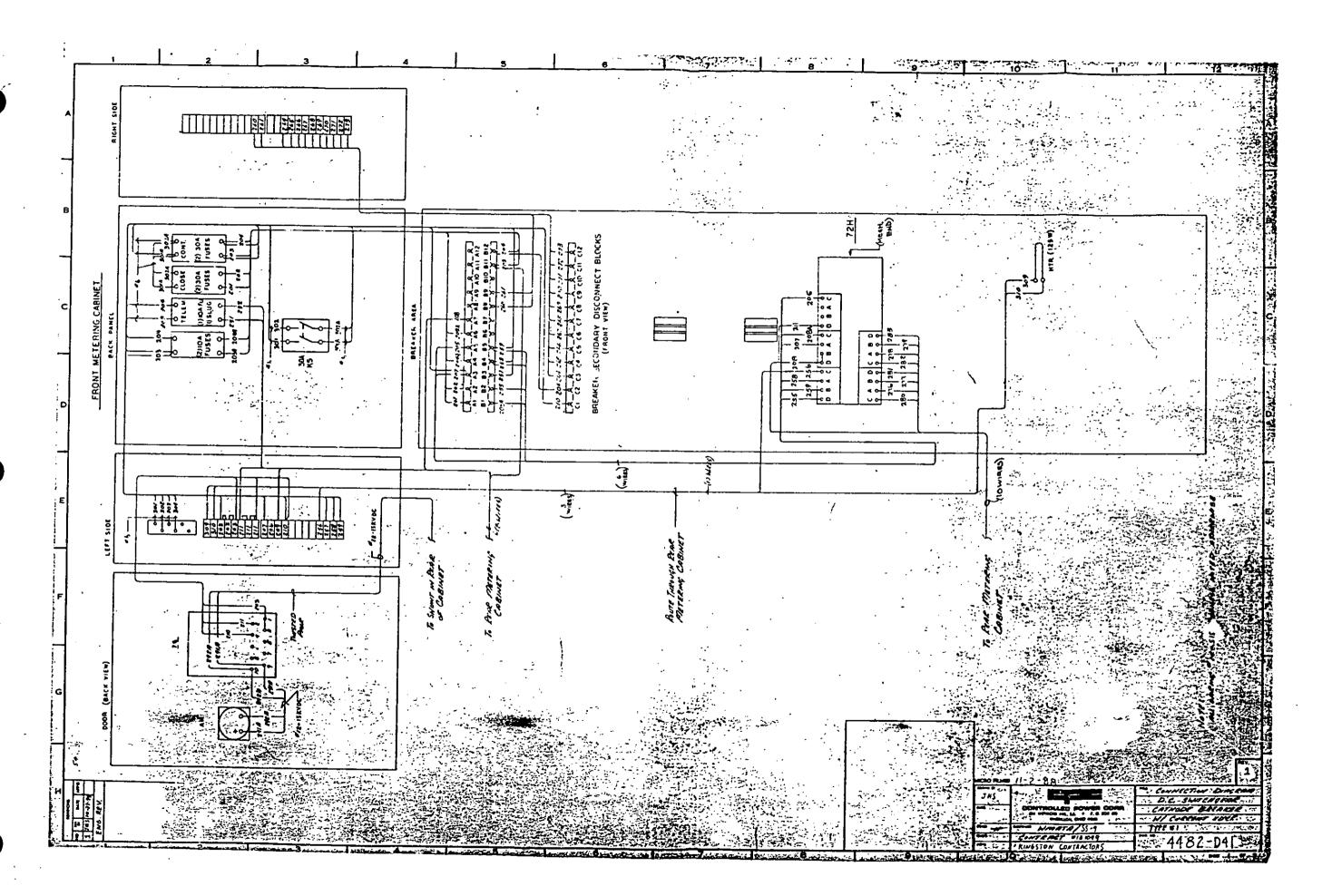


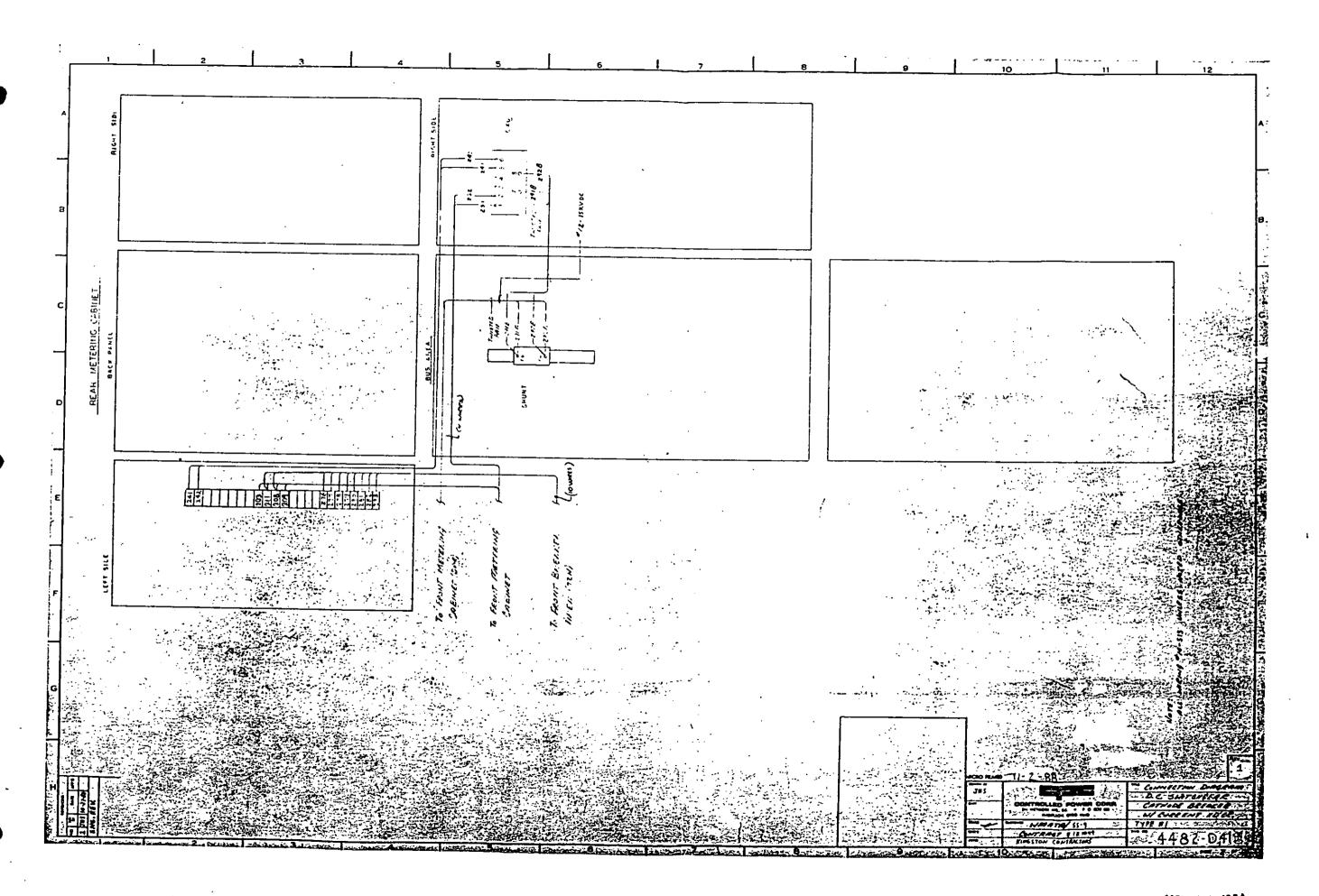
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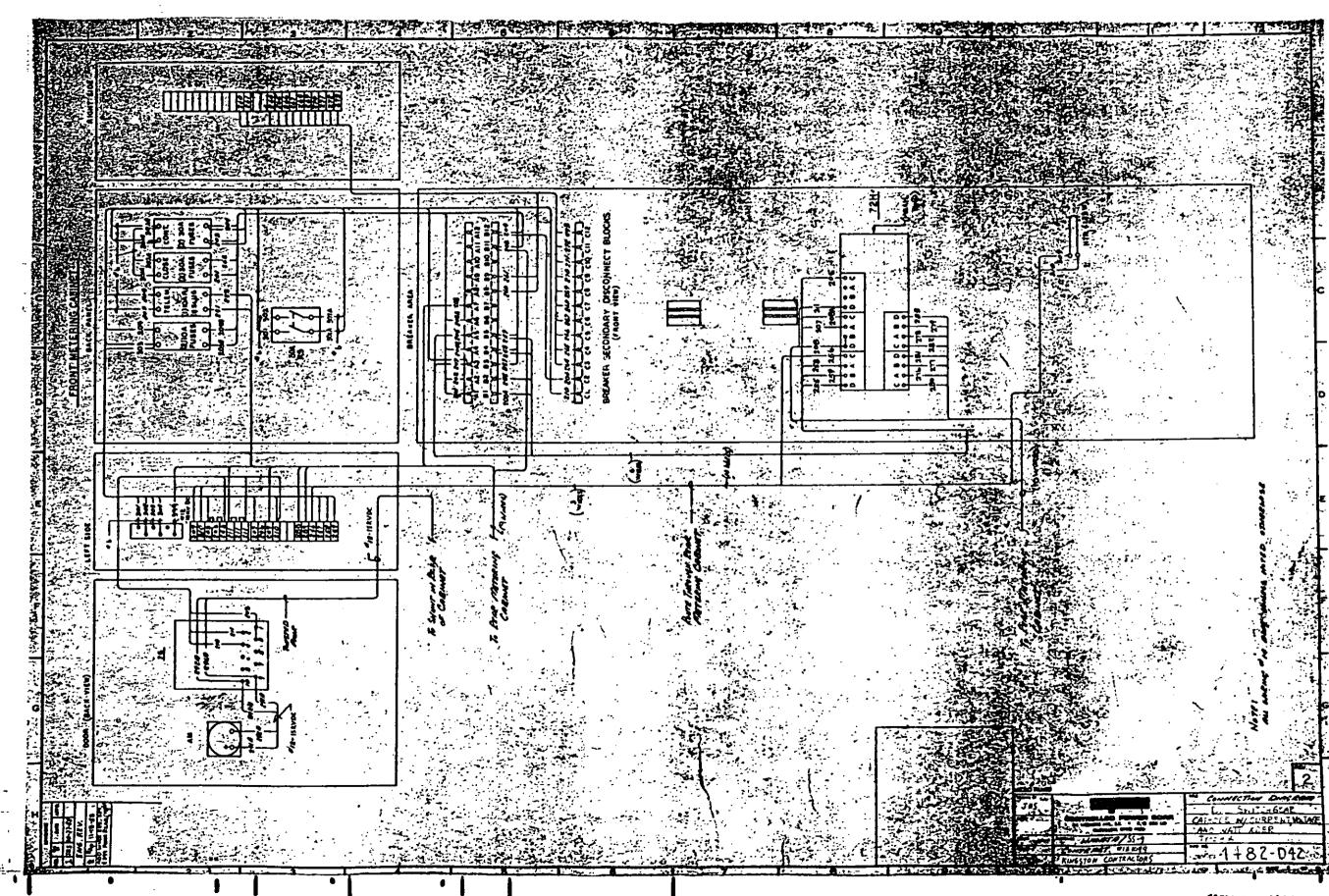




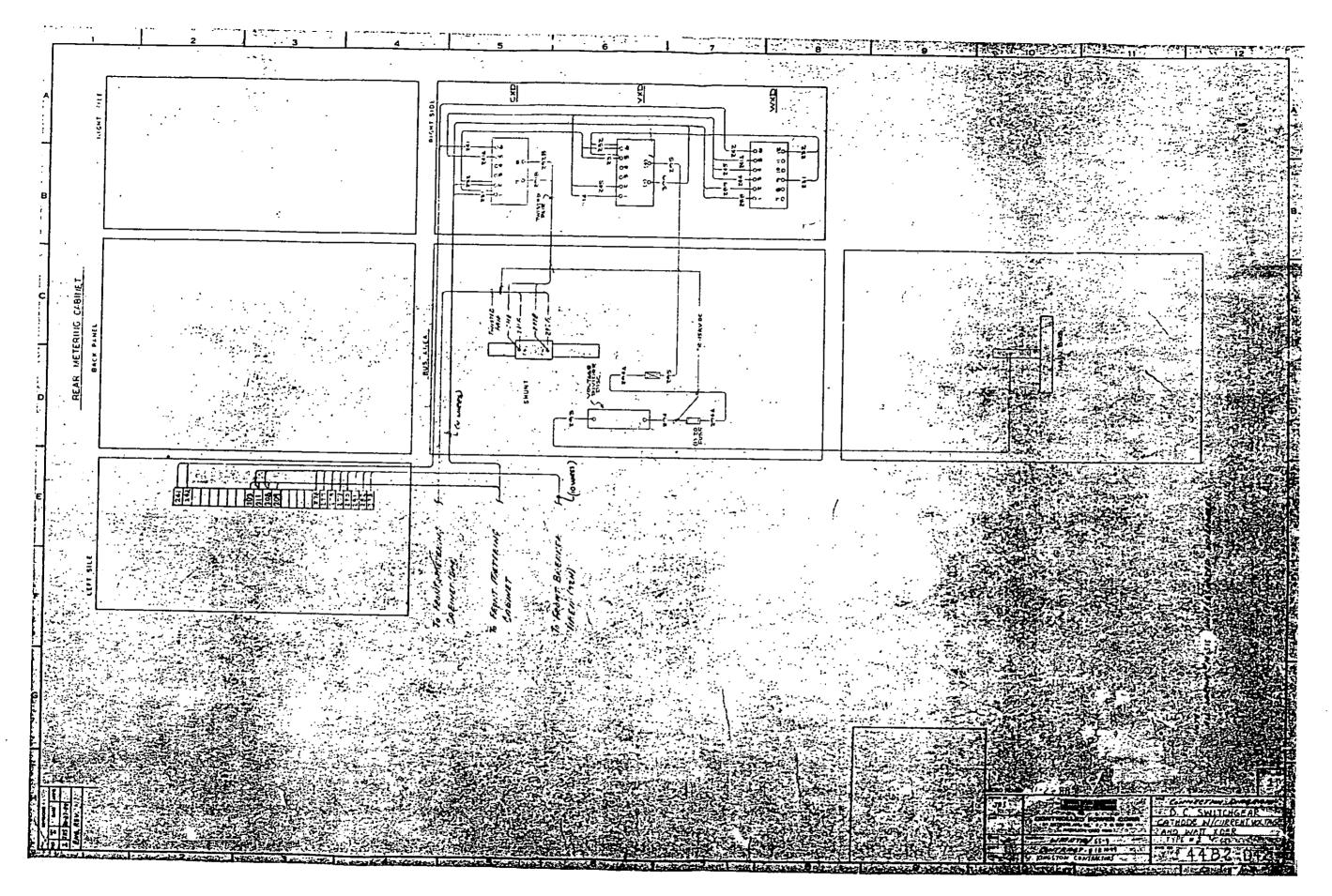
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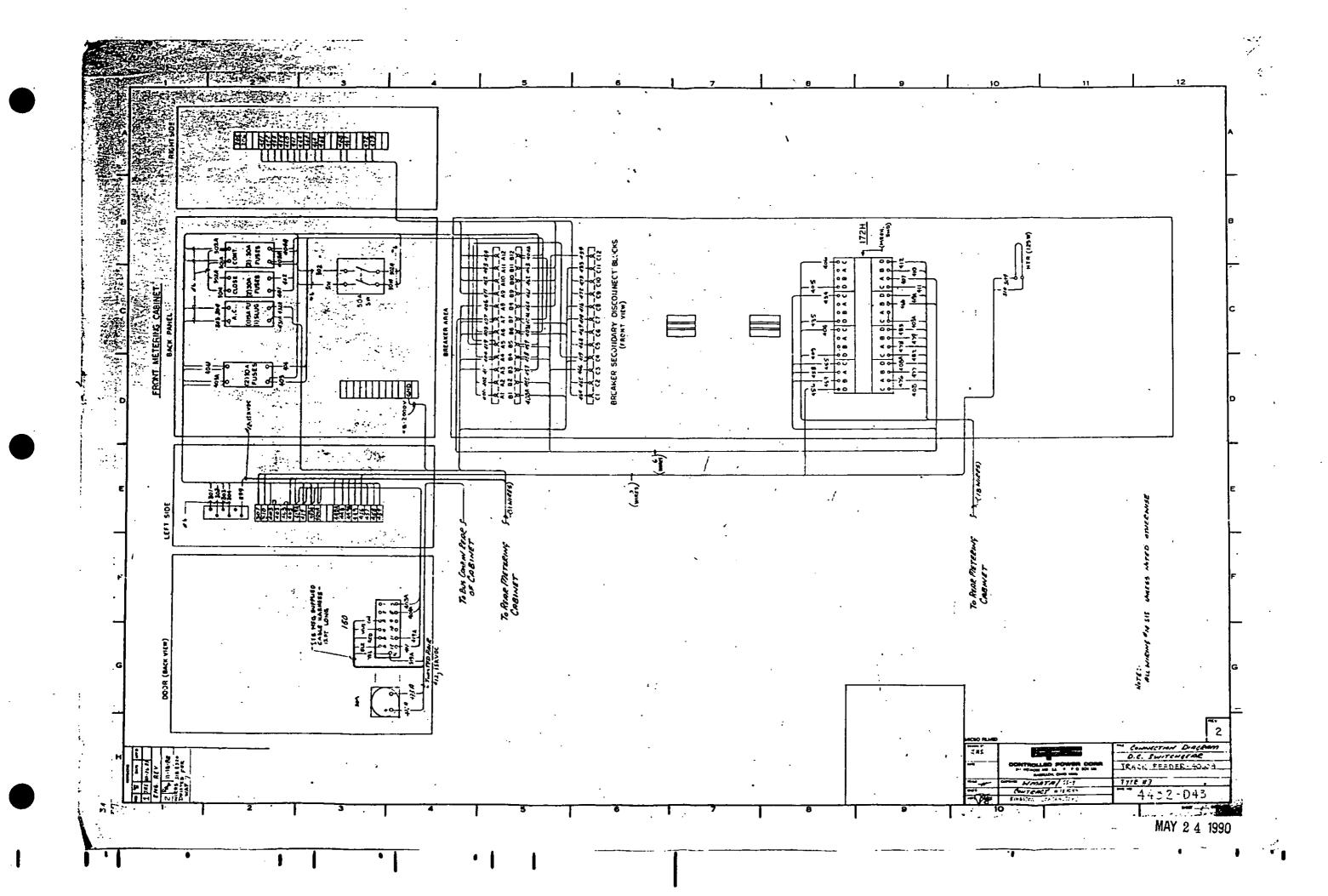


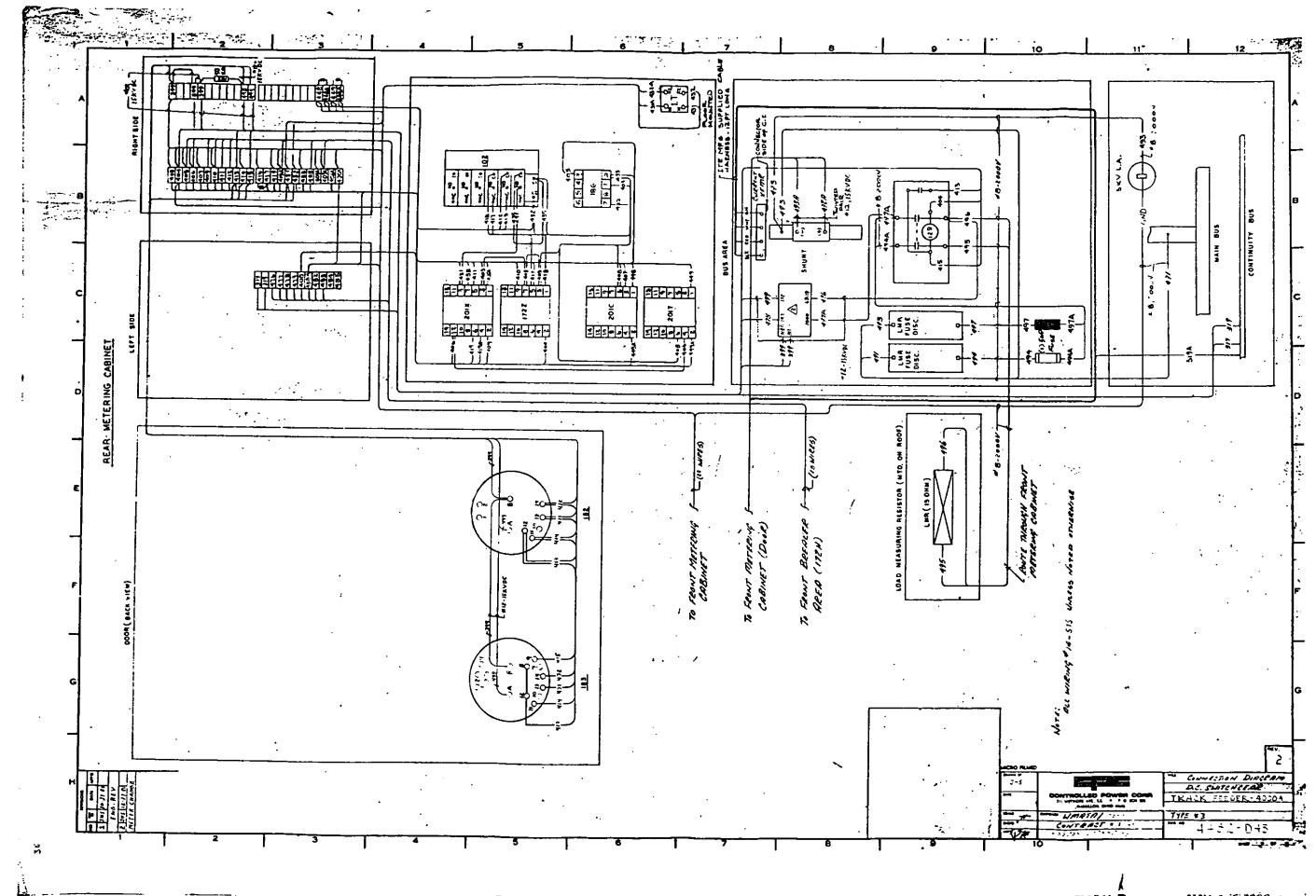




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